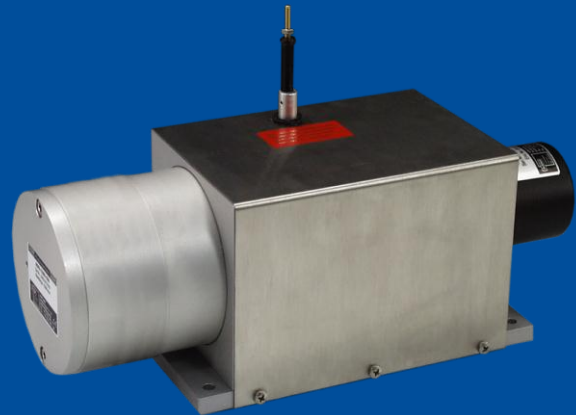




WS60

Displacement sensor with
measurement length up to
60,000 mm



- Protection class IP52, encoder IP64
- Aluminum/stainless steel housing
- With optical or incremental encoder

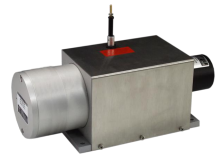
Product versions



Absolute encoder output



Incremental encoder output



WS60 - Cable Extension Position Sensor

Version with absolute encoder output

Specifications

		Order options	
Measurement range	60000 mm	1	60000
Output for 12 bit per revolution (4096 steps / revolution)	0.125 mm, (8 steps / mm)		
Output	Absolute encoder with synchronous serial output (SSI) Absolute encoder with Profibus interface Absolute encoder with Interbus interface Absolute encoder with DeviceNet interface Absolute encoder with CAN-interface Absolute encoder with CANopen interface	2	HSSI HPROF HINT HDEV HCAN HCANOP
Linearity	±0.10% f.s. (standard) ±0.025% f.s. (optional)	3	L025
Sensing device	Absolute encoder		
Material	Aluminum, stainless steel measuring cable: stainless steel		
Protection class	IP52, encoder IP64		
Cable fixing	M4 cable fixing Cable clip	4	M4 SB0
Connection	Depending on the type of encoder: connector or Bus cover		
Temperature range	-20 ... +85 °C		
Weight	Approx. 15 kg		
EMC	DIN EN 61326-1:2013		

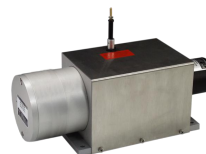
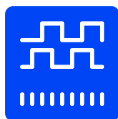
Order code

WS60 – **1** – **2** – **3** – **4**

Order example: WS60 – 60000 – HSSI – M4

Accessories:

Mating connector CONN-CONIN-12F-G (see page 12)



WS60 - Cable Extension Position Sensor

Version with incremental encoder output

Specifications

		Order options	
Measurement range	60000 mm	1	60000
Resolution	8 pulses/mm or 32 edges/mm)		
Output	Incremental encoder TTL compatible Incremental encoder HTL compatible	2	LD5VC PP24VC
Linearity	±0.10% f.s (standard) ±0.025% f.s. (optional)	3	L025
Sensing device	Incremental encoder		
Material	Aluminum, stainless steel measuring cable: stainless steel		
Protection class	IP52, encoder IP64		
Cable fixing	M4 cable fixing Cable clip	4	M4 SB0
Connection	Connector 12 pin		
Temperature range	-20 ... +85 °C		
Weight	Approx. 15 kg		
EMC	DIN EN 61326-1:2013		

Order code

WS60 – 1 – 2 – 3 – 4

Order example: WS60 – 60000 – LD5VC – L025 – M4

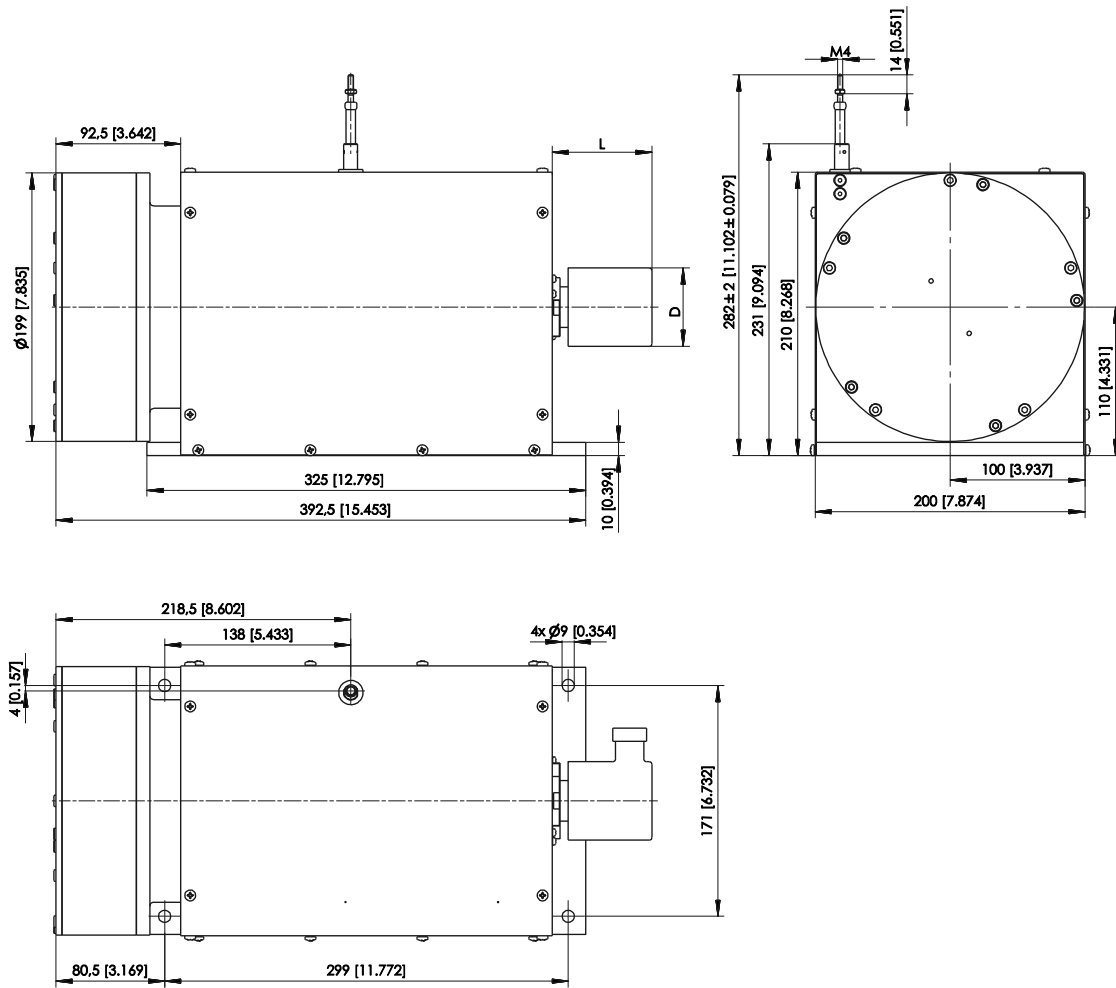
Accessories:

Mating connector CONN-CONIN-12F-G (see page 12)

Cable forces typical at = 20 °C	Measurement range [mm]	Maximum pull-out force [N]	Minimum pull-in force [N]
	60000	17.0	6.5

Dimensions

Measurement range 60000 mm, absolute encoder output, incremental encoder output,



Dimensions in mm [inch]

Dimensions D and L depending on the encoder.

Dimensions informative only.

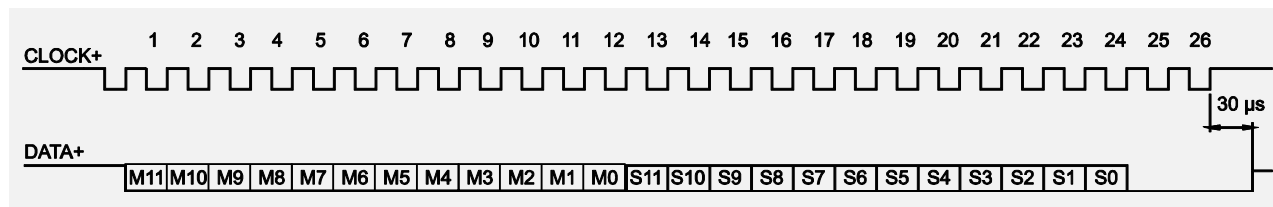
For guaranteed dimensions consult factory.

Output specifications

Absolute encoder output

HSSI synchronous serial 	Excitation voltage	10 ... 30 V DC
	Excitation current	100 mA
	Interface	Standard-SSI
	Lines / drivers	Clock and data / RS422
	Code	Gray
	Resolution	12 + 12 bit
	3 dB cutoff frequency	500 kHz
	Control input	$\overline{\text{DIRECTION}}$
	Preset key	Zero adjustment with optical response
	Alarm output	Alarm bit (SSI option), warning bit
	Status LED	Green = OK, red = alarm
	Connection	12 pin male socket

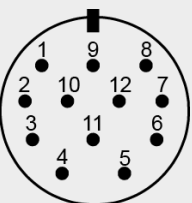
Data format



(Mx = Multiturn bits, Sx = Singleturn bits)

Transmission rate

Cable length	Baud rate	Note:
< 50 m	< 400 kHz	Extension of the cable length will reduce the maximum transmission rate.
< 100 m	< 300 kHz	
< 200 m	< 200 kHz	
< 400 m	< 100 kHz	

Signal wiring	Signal	Connector pin no.	Cable color
CONN-CONIN-12F-G  View to the sensor connector	Excitation +	8	white
	Excitation GND	1	brown
	CLOCK	3	yellow
	$\overline{\text{CLOCK}}$	11	green
	DATA	2	pink
	$\overline{\text{DATA}}$	10	grey
	Direction*	5	blue
	0 V Signal output	12	black

* unconnected or Excitation + = cw increasing code
0 V = cw decreasing code

HPROF Profibus 	Interface	RS485
	Excitation voltage	10 ... 30 V DC
	Excitation current	250 mA
	Protocol	Profibus DP with encoder profile C2
	Resolution	12 (10 ... 14) + 12 bit
	Output code	Binary
	Baud rate	Automatically selected between 9,6 kBaud and 12 MBaud
	Programmability	Resolution, preset, direction
	Integrated special functions	Velocity, acceleration, operating time
	Bus terminating resistor	Selectable via DIP switch
	Connection	Bus cover with T manifold
	EMC	Din EN 61326: Class A

Signal wiring	Output signals	Cable terminal no. (bus cover)
	U _b in	1
	0 V in	2
	U _B out	3
	0 V out	4
	B in	5
	A in	6
	B out	7
	A out	8

HINT Interbus 	Interface	Interbus, ENCOM profile K3 (configurable), K2
	Excitation voltage	10 ... 30 V DC
	Excitation current	250 mA
	Output code	32 Bit binary
	Baud rate	500 kBaud
	Data refresh	Every 600 µs
	Resolution	12 (10 ... 14) + 12 bit
	Programmability	Direction, preset, offset, resolution
	Connection	Bus cover with T manifold
	EMC	DIN EN 61326-1:2013

Data format K2 / K3					
		Differential signals (RS485) ENCOM profile K3, K2, 32 Bit, binary process data			
DÜ-Format	Sµpi-Adresse	0	1	2	3
(according to the Phoenix company)	Byte no.	3	2	1	0
ID-Code K2	36H (=54 dez.)				
ID-Code K3	37H (=55 dez.)				

Signal wiring	Output signals	Cable terminal no. (bus cover)
	U _b +	1
	GND	2
	DI1	4
	$\overline{DI1}$	6
	D01	3
	$\overline{D01}$	5
	D02	7
	$\overline{D02}$	8
	DI2	9
	$\overline{D02}$	10
	RBST	11
	GND	12

HDEV DeviceNet 	Interface	CAN highspeed according to ISO/DIS 11898 CAN specification 2.0 A (11 bit identifier)
	Excitation voltage	10 ... 30 V DC
	Excitation current	250 mA
	Protocol	DeviceNet according rev. 2.0, programmable encoder
	Resolution	12 (10 ... 14) + 12 bit
	Output code	Binary
	MAC-ID	Selectable via DIP switch
	Date refresh	Every 5 ms
	Baud rate	Selectable via DIP switch: 125 kBaud, 250 kBaud, 500 kBaud
	Programmability	Resolution, preset, direction
	Bus terminating resistor	Selectable via DIP switch
	Connection	Bus cover with T manifold
	EMC	DIN EN 61326-1:2013

Recommended transmission

Characteristic impedance	135 ... 165 Ω (3 ... 20 MHz)
Operating capacity	< 30 pF
Loop resistance	< 110 Ω/km
Wire diameter	> 0.63 mm
Wire width	> 0.34 mm ²

Transmission rate

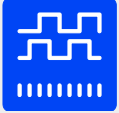
Segment length	Kbit/s
500 m	125
250 m	250
100 m	500

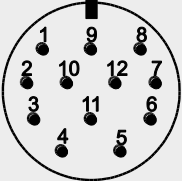
Signal wiring	Output signals	Cable terminal no. (bus cover)
	U _b in	1
	0 V in	2
	CAN-L	3
	CAN-H	4
	Drain	5
	Drain	6
	CAN-H	7
	CAN-L	8
	0 V out	9
	U _b out	10

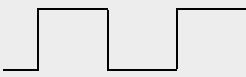
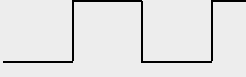
HCAN / HCANOP CANopen / CAN Layer 2 	Interface	CAN highspeed according to ISO/DIS 11898
	Excitation voltage	10 ... 30 V DC
	Excitation current	250 mA
	Protocol	CANopen according DS301 with encoder profile DSP406, programmable encoder according class C2
	Resolution	12 (10 ... 14) + 12 bit
	Output code	Binary
	Data refresh	Every millisecond (selectable), on request
	Baud rate	Selectable 10 up to 1000 kbit/s
	Base identifier	Selectable via DIP switch
	Programmability	CANopen: direction, resolution, preset, offset CAN L2: direction, limit values
	Integrated special functions	CANopen: velocity, acceleration, rotary axis, limit values CAN L2: direction, limit values
	Connection	Bus cover with T manifold
	EMC	DIN EN 61326-1:2013

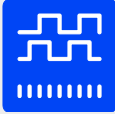
Signal wiring	Output signals	Cable terminal no. (bus cover)
	U _b in	1
	0 V in	2
	CAN in – (dominant L)	3
	CAN in + (dominant H)	4
	CAN GND in	5
	CAN GND out	6
	CAN out + (dominant H)	7
	CAN out – (dominant L)	8
	0 V out	9
	U _b out	10

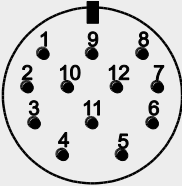
Incremental output

LD5VC Incremental interface 	Excitation voltage	5 V DC ±10 %
	Excitation current	150 mA max. w/o load
	Interface	Line driver RS422
	Output frequency	300 kHz max.
	Output current	20 mA per channel
	Signal level	
	U _d High bei I _d = 20 mA	≥ 2.5 V
	U _d Low bei I _d = 20 mA	≥ 0.5 V
	Transition time positive edge	< 100 ns
	Transition time negative edge	< 100 ns
	Stability (temperature)	±20 x 10 ⁻⁶ / °C f.s. (sensor-mechanism)
	Operation temperature	-20 ... +85 °C
	Protection	Short circuit, overvoltage
	EMC	DIN EN 61326-1:2013

Signal wiring CONN-CONIN-12F-G	Output signals	Connector pin no.	Cable color
 View to soldering side of mating connector	Excitation +	12	white
	Excitation GND	10	brown
	Signal A	5	yellow
	Signal $\bar{A}$	6	pink
	Signal B (A + 90°)	8	green
	Signal $\bar{B}$	1	grey
	Signal Z (reference pulse)	3	blue
	Signal $\bar{Z}$	4	red
	Fault detection signal	7	-
	Shield	housing	-

Output signals	
Signal A	
Signal B	
Signal Z	

PP24VC Incremental interface 	Excitation voltage	10 ... 30 V DC
	Excitation current	150 mA max. w/o load
	Interface	Push-pull line driver (24 V-HTL)
	Output frequency	300 kHz max.
	Output current	100 mA per channel
	Signal level	
	Ud High at Id = 20 mA, Ub = 24 V	≥ 21 V
	Ud Low at Id = 20 mA, Ub = 24 V	≥ 2.8 V
	Transition time positive edge	< 200 ns
	Transition time negative edge	< 200 ns
	Stability (temperature)	±20 x 10 ⁻⁶ / °C f.s. (sensor mechanism)
	Operating temperature	Refer to output specification
	Protection	Reverse polarity, short circuit, overvoltage
	EMC	DIN EN 61326-1:2013

Signal wiring CONN-CONIN-12F-G	Output signals	Connector pin no.	Cable color
 View to soldering side of mating connector	Excitation +	12	white
	Excitation GND	10	brown
	Signal A	5	yellow
	Signal $\bar{A}$	6	pink
	Signal B (A + 90°)	8	green
	Signal $\bar{B}$	1	grey
	Signal Z (reference pulse)	3	blue
	Signal $\bar{Z}$	4	red
	Fault detection signal	7	-
	Shield	housing	-

Output signals	
Signal A	
Signal B	
Signal Z	

Accessories

Plug-in connector CONIN, 12 pin (straight coupling)

Order code:

CONN-CONIN-12F-G

Cable diameter
max. 6 ... 8 mm

