

TM320

OPERATION MANUAL

01APR2020REV.1.02

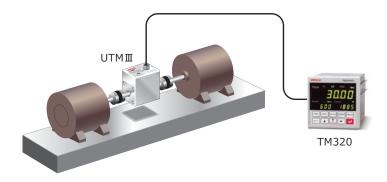
UNIPULSE

Introduction

Thank you very much for purchasing our Torque Monitor TM320.

The TM320 is an indicator only for our company UTM III and UTF series. Equipped with peak hold and HI/LO limit comparison functions, the TM320 is used for a testing machine etc. (Connectable to UTM II series.)

To take full advantage of high performance of TM320, thoroughly read this operating manual first before use and understand the explanations contained herein for correct operating procedures. Also, carefully store this instruction manual so that it can be referred to at any time.



Safety Precautions

BE SURE TO READ FOR SAFETY

Installation, maintenance and inspection of the TM320 should be performed by personnel having technical knowledge of electricity.

In order to have an TM320 Torque Monitor used safely, notes I would like you to surely follow divide into " WARNING " and " CAUTION ", and are indicated by the following documents.

Notes indicated here are the serious contents related to safely.

Please use TM320 after understanding the contents well.

M WARNING

This sign forewarns the presence of hazards that could result in serious injury or fatality when incorrectly handled.

▲ CAUTION

This sign forewarns the presence of hazards that could result in personnel injury or property damage when incorrectly handled.

⚠ WARNING

This sign forewarns the presence of hazards that could result in serious injury or fatality when incorrectly handled.

Warning on design

- For the entire system to function safely when the TM320 becomes faulty or malfunctions, provide a safety circuit outside the TM320.
- Before using the TM320 as described below, make sure to consult with our sales personnel.
 - Use in environments not described in the operation manual.
 - Use greatly impacting human lives and assets, such as medical devices, transport devices entertainment devices, and safety devices.

Warning on installation

- Do not disassemble, repair, or modify the TM320. Doing so may cause a fire or an electric shock
- Do not install in the following environments.
 - Places containing corrosive gas or flammable gas.
 - Where the product may be splashed with water, oil or chemicals.

Warning on wiring

- Do not connect a commercial power source directly to the signal input/output terminals.
- Be sure to ground the protective ground terminal.
- Before performing the following, make sure that no power is applied.
 - Attachment/detachment of connectors of options, etc.
 - Wiring/connection of cables to the signal input/output terminals.
 - Connection to the ground terminal.
- For connection to the signal input/output terminals, check the signal names and pin assignment numbers, and then carry out wiring properly.
- Be sure to use crimp contacts for connection to the terminal blocks, and do not to connect bare wires as they are.
- After wiring, be sure to mount the attached terminal block cover. Otherwise, it may cause an electric shock.
- Do not connect anything to unused terminal(s).
- Before applying power, carefully check the wiring, etc.

Warning during startup and maintenance

- Use a power supply voltage and load within the specified and rated ranges.
- Do not damage the power cord. Doing so may cause fire or electric shocks.
- Do not touch any signal input/output terminal while applying power. Doing so may cause electric shocks or malfunctions.
- If the cover of the main body is opened, it may cause an electric shock internally. Even if the power is off, the internal capacitor is charged. Contact us for internal inspection or repair.
- In the case of smoke, an abnormal smell or strange sound, immediately turn off the power, and disconnect the power cable.



This sign forewarns the presence of hazards that could result in personnel injury or property damage when incorrectly handled.

Caution on installation

- Use the TM320 as it is incorporated in a control panel, etc.
- Do not install in the following environments.
 - Where the temperature/humidity exceeds the range of the specifications.
 - Where the temperature changes remarkably or there is a danger of freezing or condensing.
 - Outdoors, or where the altitude exceeds 2000m.
 - Places exposed to direct sunlight
 - Dusty places
 - Poor-ventilated places
 - Places containing large quantities of salt or iron powder.
 - Where the main body is directly affected by vibrations or shocks.
- Take adequate shielding measures when using at the following locations.
 - Near a power line.
 - Where a strong electric field or magnetic field is formed.
 - Where static electricity, relay noise or the like is generated.
- Install the TM320 as far away from devices generating high frequency, high voltage, large current, surge, etc., as possible. Also, carry out wiring separately from their power lines. Do not carry out parallel wiring and common wiring.
- Do not use it. broken down.

Caution on wiring

- Tighten the screws for the power input terminal at the specified torque.
 - If they are loose, shorts, fire or malfunctions may occur.
 - Tightening torque: 0.5N m
- For external inputs/outputs and options, use shielded cables.
- The temporary overvoltage applied to the power should not exceed 1500V.

Caution during startup and maintenance

- For turning on/off the power, be sure to keep intervals of 5 seconds or more.
- After power-on, make sure to warm up the TM320 for at least 30 minutes or more before use.
- If the TM320 is not used by the specified method, its protective performance may be impaired.
- Maintenance
 - When performing maintenance, disconnect the power.
 - Do not wipe with a wet rag, or with benzine, thinner, alcohol, etc. Doing so may cause discoloration or deformation of the TM320. In the case of heavy contamination, wipe off the contamination with a cloth after dipping it into a diluted neutral detergent and wringing it well, and then wipe with a soft, dry cloth.

Caution during transportation

 When the TM320 is shipped, spacers made of corrugated cardboard are used as cushioning materials.

Though it is factory-designed so that shocks can sufficiently be absorbed, breakage may result if shocks are applied when the spacers are reused for transportation. If you send the TM320 to us for repair, etc., take adequate measures against shocks by using polyurethane materials, etc., separately.

Caution during disposal

If you dispose of the product, handle it as industrial waste.

RoHS-Compliant Product

The parts and attachments (including the instruction manual, packaging box, etc.) used for this unit are compliant with the RoHS Directive restricting the use of hazardous substances with regard to adverse effects on the environment and human body.

Contents

1	OUTLINE	1
	1-1. Main features of the TM320	1
	1-2. Contents of the package	1
	1-3. About connectable devices	2
	1-4. Appearance description	2
	Front panel	
	■ Rear panel	5
2	INSTALLATION & CONNECTION	8
	2-1. Installation	9
	2-2. Connection	10
	■ DC power input terminal connection	
	■ UTM II connection	
	■ UTF connection	
	■ External I/O connection	14
	■ How to assemble the connector■ SI/F interface connection	
3	SETTING MODE CONFIGURATION	16
3	SETTING MODE CONFIGURATION	
3		16
3	3-1. Setting mode composition	16
3	3-1. Setting mode composition	16
	3-1. Setting mode composition	16 18 21
	3-1. Setting mode composition	16
	3-1. Setting mode composition	16
	3-1. Setting mode composition 3-2. Key operation 3-3. Calling a setting mode CALIBRATION PROCEDURE 4-1. How to perform calibration Equivalent input calibration Actual load calibration	
	3-1. Setting mode composition 3-2. Key operation 3-3. Calling a setting mode CALIBRATION PROCEDURE 4-1. How to perform calibration Equivalent input calibration Actual load calibration 4-2. Procedure of equivalent input calibration and calibration protect (torque)	21
	3-1. Setting mode composition 3-2. Key operation. 3-3. Calling a setting mode CALIBRATION PROCEDURE 4-1. How to perform calibration ■ Equivalent input calibration ■ Actual load calibration 4-2. Procedure of equivalent input calibration and calibration protect (torque). 4-3. Rotation speed/power display settings.	
	3-1. Setting mode composition 3-2. Key operation. 3-3. Calling a setting mode. CALIBRATION PROCEDURE 4-1. How to perform calibration. ■ Equivalent input calibration ■ Actual load calibration 4-2. Procedure of equivalent input calibration and calibration protect (torque). 4-3. Rotation speed/power display settings. 4-4. Rotation stop settings for rotation speed	16212222222331
	3-1. Setting mode composition 3-2. Key operation. 3-3. Calling a setting mode CALIBRATION PROCEDURE 4-1. How to perform calibration ■ Equivalent input calibration ■ Actual load calibration 4-2. Procedure of equivalent input calibration and calibration protect (torque). 4-3. Rotation speed/power display settings.	
	3-1. Setting mode composition 3-2. Key operation. 3-3. Calling a setting mode. CALIBRATION PROCEDURE. 4-1. How to perform calibration. ■ Equivalent input calibration. ■ Actual load calibration. 4-2. Procedure of equivalent input calibration and calibration protect (torque). 4-3. Rotation speed/power display settings. 4-4. Rotation stop settings for rotation speed ■ Minimum input rotation speed (Only for UTM III & UTM II).	
	3-1. Setting mode composition 3-2. Key operation 3-3. Calling a setting mode CALIBRATION PROCEDURE 4-1. How to perform calibration Equivalent input calibration Actual load calibration 4-2. Procedure of equivalent input calibration and calibration protect (torque) 4-3. Rotation speed/power display settings 4-4. Rotation stop settings for rotation speed Minimum input rotation speed (Only for UTM III & UTM II) Rotation stop mode	162122222331333335

5 I	EXPLANATION OF INDICATED-VALUE-RELATED FUNCTIONS	36
	5-1. About each indicated value	36
	5-2. Digital low-pass filter	
	■ Digital low-pass filter (torque) setting method	
	5-3. Digital filter	
	■ Digital filter (torque) setting method	
	5-4. Dead band	
	■ Dead band setting method	
	5-5. Digital zero	
	■ Digital zero / Digital zero reset by means of keys	38
	■ Digital zero by means of the external signal "D/Z input"	
	5-6. Motion detect	39
	■ Motion detect setting method	
	5-7. Zero tracking	
	■ Zero Tracking setting method	
	5-8. Display frequency	
	■ Display frequency setting method	
	5-9. Display ON/OFF	
	■ Display ON/OFF setting method	
	5-10.Absolute value display select	
	■ Absolute value display select setting method	43
6 1	EXPLANATION OF COMPARISON FUNCTIONS	44
	EXITER AN ATTOM OF COMM ANGIOTT CHOTICHE	
	6-1. HI/LO limit comparison	44
	■ HI/LO limit setting method	
	■ Alarm HI and LO limits setting method	
	6-2. Hysteresis	
	■ Hysteresis setting method	
	6-3. Near zero	
	■ Near zero setting method	
	6-4. Comparison timing	47
	 Comparison timing (Torque), Comparison timing (Rotation speed), B2 output selection setting method	47
	■ Timing output	
7 I	EXPLANATION OF HOLD FUNCTIONS	49
	7-1. Hold functions of torque	
	■ Flow of hold measurement	
	7-2. Setting of hold mode.	
	■ Hold mode setting method	
	■ Peak hold	50

	■ Peak-to-Peak (P-P) hold	
7-3	. Setting of hold section	53
	■ Hold section setting method	
	All section	
	■ External signal	
	Level + time	
7-4	. Auto reset function	57
	■ Auto reset setting method	58
7-5	. B8 OFF detect wait	58
	■ B8 OFF detect wait	58
7-6	. B9 OFF detect wait	59
	■ B9 OFF detect wait	59
8 STA	NDARD INTERFACE	60
8-1	External I/O	
	Connector pin assignment	
	■ About outputs	
	About the RUN signal	
8-2	. SI/F (serial interface)	61
	■ SI/F indicated value format	61
	■ SI/F print	61
8-3	. RS-485	63
	■ RS-485 communication mode	
	■ Read setting values from UTM/UTF Write filter setting to UTM/UTF	
	■ Write inter setting to OTM/OTF	
	■ Write minimum rotation speed display to UTM/UTF	65
	UTM/UTF assigned action	
	■ RS-485 dedicated rated capacity value	
	■ RS-422 terminator	67
	■ About RS-485 command mode & RS-485 display mode	68
9 REC	ORD FUNCTION	69
9-1	. Record timing	69
	. History	
9-3	Record data clear	
	■ Clear by means of keys	
	Clear by means of communication (232/USB option)	
	- , , ,	
10 OP	TION INTERFACE	71
10-	1.BCD interface	71

	Connection	
	Connector pin assignment	
	Output data select	
	Logic switching	
	BCD data hold	
	Output rate	
	BCD/binary select	75
	Pin assignment at binary	75
10-2.R	S-232C interface	76
	Communication specifications	76
	Connector pin assignment	76
	Connection	
	Communication mode	
	Communication conditions	
	Delimiter	
	Communication format	
	·	
	/A converter voltage output (3ch)	
	Connector pin assignment	85
	Connection	
	Output mode	
	Data select	
	Adjustment by fixed output	
	/A converter output	
	Connection	
	Output data select	
	Zero/Full scale setting	
	SB interface	
	Communication specifications	
=	PC hardware requirement	
=	Connection of USB.	
	The check of a virtual COM port.	
=	Installation of the TM320 PC application software	
	The injection of a power supply	
	Starting of the TM320 PC application software	
	Specification of a COM port	
	The check of a indicating value	
=	Communication mode	
=	Delimiter	
	Communication format	
_		
110000	EICATIONS 44	ا ر
119PECII	FICATIONS	JU
	Specifications	
	Analog section	
	Display section	
	Setting section	
	External input/output section	
	Interface	υΊ

■ Options 102 ■ General performance 103 ■ Attachment 103
11-2.Dimensions
■ Standard equipment104■ Equipped with BCD parallel data output interface option104■ Equipped with RS-232C interface option105■ Equipped with D/A converter (3ch) option105■ Equipped with D/A converter option106■ Equipped with USB interface option10611-3. TM320 block diagram107
12 SUPPLEMENTS
12-1.The list of initial setting value
12-2.Self-check function
■ Self-check method
12-3.Setting protect
Setting protect setting method
12-4.Key protect
■ Key protect setting method
12-5.Initialize
■ Initialize setting method
12-6.Password
12-7.Error/message list
■ Main numerical display section
12-8.Troubleshooting
12-9.Conformity with EC directives
■ Attachment of the ferrite core

IVI	E	IVI	O		

1 OUTLINE

1-1. Main features of the TM320

- The TM320 is a simple torque monitor that can easily be connected to our torque meter UTMII and UTF series (UTMII) with a dedicated cable (optionally available).
- In addition to torque, rotation speed and power can also be displayed.
- The TM320 is equipped with hold functions with respect to torque.
 (sample, peak, bottom, P-P, and average holds)
- The TM320 is equipped with the function of recording data according to a print command of the SI/F (up to 30 pieces of the most recent data). Also, data can be checked on the spot by key operation.
- The TM320's compact size of DIN96×96 realizes space-saving.
- By mounting an optional interface according to the purpose, ease of load control can be further improved.

1-2. Contents of the package

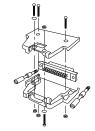
The packaging box contains the following. Be sure to check them before use.



TM320 body.....1



TM320 operation manual.....1



External input/output connector.....1



Unit seal.....1



Ferrite core.....1 [E04SR211132]



Connector for BCD parallel data output.....1 (with BCD parallel data output option)

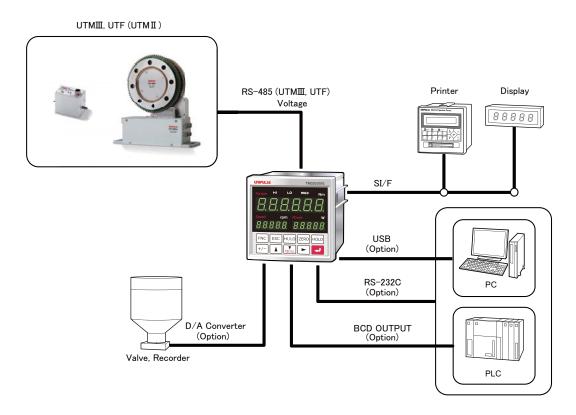


Operating tool.....1 (with D/A converter (3ch) option)



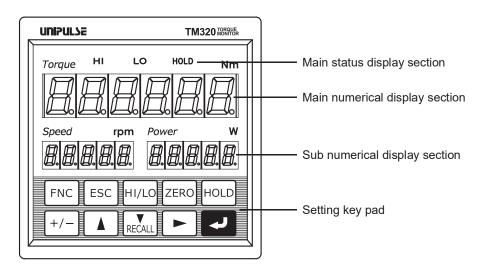
Mini screwdriver for terminal block connection.....1 (with D/A converter option)

1-3. About connectable devices



1-4. Appearance description

■Front panel



Chapter

Main status display section

The status with respect to torque is indicated.

HI: Lights when the indicated value is larger than the HI limit.

Indicates that the external output "HI" is ON.

LO: Lights when the indicated value is smaller than the LO limit.

Indicates that the external output "LO" is ON.

HOLD: Blinks during hold detection, and lights when a hold is confirmed.

Also, it blinks when hold waiting in all section sample hold.

Main numerical display section

The following display patterns exist.

Indicated value: Displays torque during measurements.

Error display: Displays an error message when an error occurs.

Setting value: Displays setting values in setting mode.

Sub numerical display section

The following display patterns exist.

Indicated value: Displays rotation speed and power during measurements.

Error display: Displays an error message when an error occurs.

Setting value: Displays the mode number and item number at the rotation speed display

section in setting mode; the load value may be displayed at the power display

section according to the setting item.

In this operation manual, the display status is expressed as follows:

Lighting: Status display section → Black

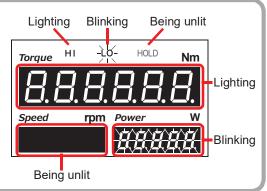
Numerical display section → White

Blinking: Lighting state + Lines in a radial pattern

Being unlit: Status display section → Gray

Numerical display section

→ Nothing displayed



OUTLINE

Setting key pad

These are keys for commanding settings and operations.



- Use this key to go to a setting mode state.



- Use this key to cancel setting/execution.
- Use this key to go back from a setting mode state to an indication display state.



- Use this key to take a shortcut from an indication value display state to HI/LO limit setting.



- Use this key to go from an indication value display state to torque Digital Zero ready.



- Use this key to execute/release the hold in an indication value display state.



- Use this key to switch the setting in HI/LO limit setting mode.
- Use this key to set whether or not to sign a setting value, when available, in a setting value input state.



- Use this key to select a trailing setting item number in a setting mode state.
- Use this key to select the previous item number in a setting item select state.
- Use this key to increment the numerical value by one in a setting value input state.



- Use this key to go from an indicated value display state to history mode (record data display).
- Use this key to select a leading setting item number in a setting mode state.
- Use this key to select the next item number in a setting item select state.
- Use this key to decrement the numerical value by one in a setting value input state.



- Use this key to execute Digital Zero reset in a Digital Zero ready state.
- Use this key to increment the leading setting mode number by one in a setting mode
- Use this key to move the setting digit by one in the lower direction in a setting value input state.



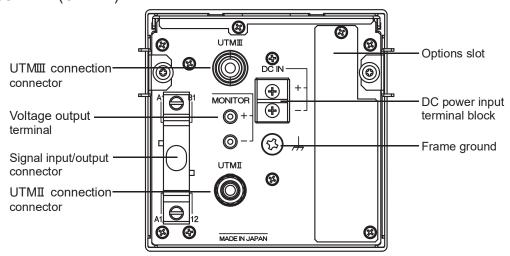
- Use this key to execute Digital Zero in a Digital Zero ready state.
- Use this key to move to a setting value input state in a setting item select state.
- Use this key to validate the setting value in a setting value input state.

Chapter

1

■Rear panel

■UTMⅢ (UTMⅡ)



UTMIII connection connector

Connect a UTMIII with a dedicated cable.

* For connection, see "■UTM II connection" on page 11.

UTMI connection connector

Connect a UTMII with a dedicated cable.

* For connection, see "■UTM II connection" on page 11.



UTMIII/UTM II cannot be connected simultaneously.

Voltage output terminal

The approximate input voltage from UTMIII (UTM II) can be confirmed. (approx. 1V per sensor input voltage of 1V, with load resistance of $2k\Omega$ or more)

* For connection, see "■Voltage output" on page 13.

Signal input/output connector

Connect external input/output signals or SI/F (serial interface).

* For connection, see "External I/O connection" on page 14.

DC power input terminal block

Connect the DC power cord. The power supply voltage is 24V DC (±15%).

* For connection, see "■DC power input terminal connection" on page 10.

Frame ground \bot

Please ground the frame ground terminal to prevent failures due to static electricity.

(The frame and the frame ground terminal are conducted.)

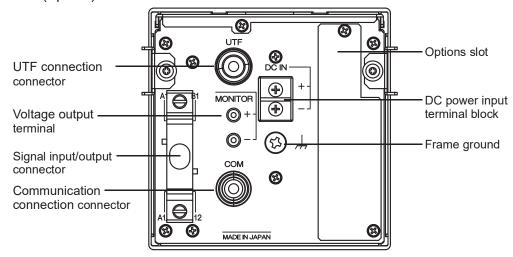
It may be better to remove depending on the environment of the installation location.

Options slot

One option board can in stall in the option slot.

- BCD parallel data output	(BCO)
- RS-232C interface	(232)
- D/A converter voltage output (3ch)	(D3V)
- D/A converter voltage output	(DAV)
- D/A converter current output	(DAI)
- USB interface	(USB)

■UTF (option)



UTF connection connector

Connect a UTF with a dedicated cable.

* For connection, see "■UTM II connection" on page 11.

Voltage output terminal

The approximate input voltage from UTF can be confirmed.

(approx. 1V per sensor input voltage of 1V, with load resistance of $2k\Omega$ or more)

* For connection, see "■Voltage output" on page 13.

Signal input/output connector

Connect external input/output signals or SI/F (serial interface).

* For connection, see "■External I/O connection" on page 14.

Chapter

Communication connection connector

For RS-485 communication with UTF, dedicated cable is needed.

* For connection, see "■External I/O connection" on page 14.

DC power input terminal block

Connect the DC power cord. The power supply voltage is 24V DC (±15%).

* For connection, see " DC power input terminal connection" on page 10.

Frame ground \downarrow

Please ground the frame ground terminal to prevent failures due to static electricity. (The frame and the frame ground terminal are conducted.)

It may be better to remove depending on the environment of the installation location.

Options slot

One option board can in stall in the option slot.

- BCD parallel data output	(BCO)
- RS-232C interface	(232)
- D/A converter voltage output (3ch)	(D3V)
- D/A converter voltage output	(DAV)
- D/A converter current output	(DAI)
- USB interface	(USB)

Chapter

2

2

INSTALLATION & CONNECTION

The following are precautions related to connection.

The precautions described here are important for safety.

Make connections after properly understanding the description.

MARNING

- Do not connect commercial power directly to the signal input/output terminals.
- Make connection to the signal input/output terminals with no power applied because you may receive an electric shock.
- For connections to the signal input/output terminals, carry out wiring properly after confirming the signal names and pin assignment numbers.
- Be sure to use crimp contacts for connection to the terminal blocks, and do not to connect bare wires as they are.
- After wiring, make sure to mount the attached terminal block cover. Otherwise, you may receive an electric shock.
- Turn on the power after carefully checking the wiring, etc.
- Do not touch the signal input/output terminals while the power is on. Otherwise, you may receive an electric shock, or a malfunction may occur.

A CAUTION

- Tighten the terminal screws at specified torque. If the terminal screws are loose, short-circuiting, fire, or a malfunction may occur.
- Use shielded cables.

92mm⁺¹

Panel-cut dimensions

Panel thickness

1.6 to 3.2mm

92mm -0

2

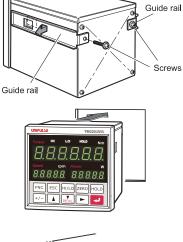
Chapter

INSTALLATION & CONNECTION

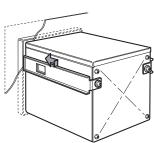
2-1. Installation

To install the TM320 into a control panel, use the following procedure.

- **1.** Make a hole in the panel according to the panel-cut dimensions.
- **2.** Remove the screws (two), and remove the guide rails from both sides.
 - * Do not use other screws than those installed to the TM320 body.
- **3.** Fit in the TM320 from the front of the panel.



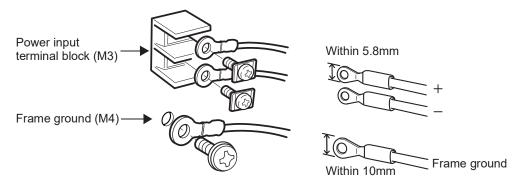
4. Install from the rear the guide rails having been removed from both sides in Step 2, and fix them with the screws (two).



2-2. Connection

■DC power input terminal connection

Connect the DC power cord. (DC24V (±15%) 24W)



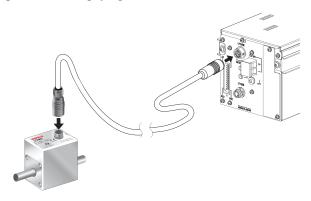
- 1. Ensure that the power is OFF.
- 2. Remove the terminal block cover.
- **3.** Remove the screws from the power input terminal block (two locations).
- **4.** After fitting crimping terminals into the screw holes, secure them with screws.
 - +: Red screw
 - -: Black screw
- **5.** Connect the frame grounding.
- **6.** Attach the terminal block cover.

MARNING

- Connect with no power applied because it may cause an electric shock.
- Be careful, as the voltage will drop depending on the diameters and lengths of the wires. Also, never input an AC power supply. Doing so may cause failure.
- Since the TM320 has no power switch, install a breaker.
- Be sure to ground the frame grounding terminal to prevent malfunctions arising from noise. Do not use screws other than those used for attaching the main unit.
 Furthermore, in some installation environments, it may perform better without the grounding.

■UTMⅢ connection

A UTM III can easily be connected with the dedicated cable (Sold separately). The cable is nonpolar. Connect paying attention to the orientation of the connector.



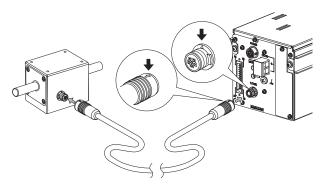
Pin assignments

Pin arrangement	Pin No.	Cable color	Signal at TM320 side	Signal at UTMⅢ side
	1	Red	PWR (+24V) (Drive power supply for UTMIII)	PWR (+24V)
	2	Black	PWR (0V) (Drive power supply for UTMIII)	PWR (0V)
	3	Green	SIG IN (±10V DC)	SIG OUT (±10V DC)
	4	White	SIG GND	SIG GND
① 9 ② _⑥ 8	5	Yellow	PULSE IN+	PULSE OUT+
(3 10 12 7)	6	Brown	PULSE IN-	PULSE OUT-
4 5 6	7	Orange		
	8	Purple	RS-485 RX+ (B+)	RS-485 TX+ (B+)
	9	Gray	RS-485 RX- (A-)	RS-485 TX- (A-)
	10	Pink	RS-485 TX+ (B+)	RS-485 RX+ (B+)
	11	Light blue	RS-485 TX- (A-)	RS-485 RX- (A-)
	12	Blue	COM	COM

^{*} Cable color is based on UTM III dedicated cable. (Sold separately)

■UTMII connection

A UTMII can easily be connected with the dedicated cable (Sold separately). The cable is nonpolar. Connect paying attention to the orientation of the connector.



^{*} Compatible connector: HR10-10P-12P (HIROSE)

Pin assignments

Pin arrangement	Pin No.	Cable color	Signal at TM320 side	Signal at UTM II side
	1	Red	PWR (+24V) (Drive power supply for UTM II)	PWR (+24V)
	2	Black	PWR (0V) (Drive power supply for UTM II)	PWR (0V)
10 05	3	Green	SIG IN (±5V DC)	SIG OUT (±5V DC)
20 3 04	4	White	SIG GND	SIG GND
	5	Yellow	PULSE IN+	PULSE OUT+
	6	Brown	PULSE IN-	PULSE OUT-
	Shield	Braided wire	*The shield is not connected to the TM320 housing.	* The shield is not connected to the UTMII housing.

- * Cable color is based on UTMII dedicated cable. (Sold separately)
- * Compatible connector: HR30-6P-6P (HIROSE)

■UTF connection

A UTF can easily be connected with the dedicated cable (Sold separately).

The cable is nonpolar. Connect paying attention to the orientation of the connector.

* Please prepare power supply for UTF.



Pin assignments (OUTPUT)

Pin arrangement	Pin No.	Cable color	Signal at TM320 side	Signal at UTF side
	1	Red	SIG IN (±10V DC)	SIG OUT (±10V DC)
	2	Black	SIG GND	SIG GND
	3	Green		
	4	White		
1 9	5	Yellow	RS-422A A phase + IN	RS-422A A phase + OUT
2 0 8	6	Brown	RS-422A A phase - IN	RS-422A A phase - OUT
(3 (1) (2) (7)	7	Orange	RS-422A B phase + IN	RS-422A B phase + OUT
4 6 6	8	Purple	RS-422A B phase - IN	RS-422A B phase - OUT
	9	Gray	COM	COM
	10	Pink		
	11	Light blue		
	12	Blue		

- * Cable color is based on UTF dedicated cable. (Sold separately)
- * Compatible connector: HR10-10P-12S (HIROSE)

Pin assignments (COM)

Pin arrangement	Pin No.	Cable color	Signal at TM320 side	Signal at UTF side
	1	Orange Red dot	RS-485 TX+ (B+)	RS-485 RX+ (B+)
	2	Orange Black dot	RS-485 TX- (A-)	RS-485 RX- (A-)
	3	Gray Red dot	RS-485 RX+ (B+)	RS-485 TX+ (B+)
	4	Gray Black dot	RS-485 RX- (A-)	RS-485 TX- (A-)
3 6	5	White Red dot	СОМ	СОМ
	6	Shield	FG	FG
	7			
	8			
	9			
	10			

^{*} Cable color is based on UTF dedicated cable. (Sold separately)

■Voltage output

The voltage output terminal outputs the input voltage from the UTMIII and UTF (UTMII) as it is turned back.

The check of voltage is possible at the probe of a voltmeter, etc.

Since the output voltage is taken out in a step prior to A/D conversion of the sensor input signal, it is not synchronized with indicated values processed digitally, such as Digital Zero and digital filter. Output in synchronization with indicated values requires an optional D/A converter.

The ±MONITOR terminals are not insulated from the internal circuit.

Use terminal: C-55-111A (manufactured by Miraial or an equivalent) ϕ 2, Depth: 6mm

Compatible terminal: C-55-155B (manufactured by Miraial or an equivalent)

A CAUTIONWARNING

- Do not short-circuit. Doing so will cause a failure.
- Do not apply voltage externally. Doing so will cause breakage.

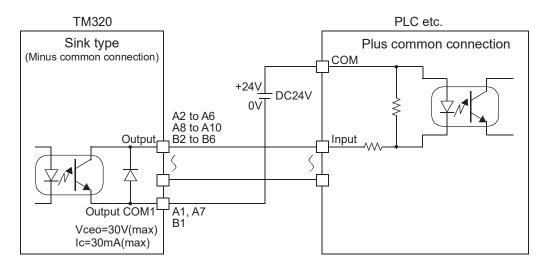
^{*} Compatible connector: HR10A-10P-10P (HIROSE)

■External I/O connection

Details of signal, see "8-1.External I/O" on page 60.

- How to connect external output (Sink type)

The external output circuit is operated through an open collector. A1(A7) COM1 is the common terminal. The open collector output capacity is 30mA and the withstand voltage is up to 30V.



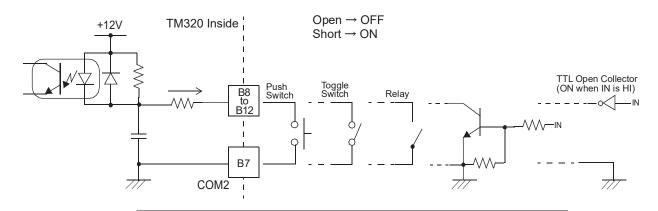
Output transistor status

Output data	Tr
OFF	OFF
ON	ON

For driving, have an external power source ready. (24V DC is shown in the illustration.)

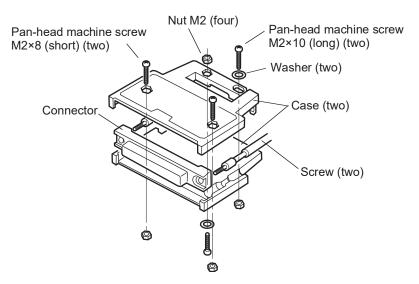
How to connect external input (minus common connection of no-voltage contact input type)

A signal is inputted to the signal input circuit by short-circuiting or opening the input terminal and the COM2 terminal. Short-circuiting is effected by means of a contact (such as a relay or a switch) or a noncontact (such as a transistor or an open-collector TTL)



- The external element is required to withstand Ic=10mA.
- Leakage from the external element is required to be 100µA or below.

■ How to assemble the connector



- 1. Set the connector and screws (two) into the grooves of the case (one side).
- 2. Cover with the other case, and fit the cases.
- 3. Tighten the M2×8 pan-head machine screws (two).
 Tighten the M2×10 pan-head machine screws (two).
 Be aware that washers should be set to the M2×10 pan-head machine screws (two).

■SI/F interface connection

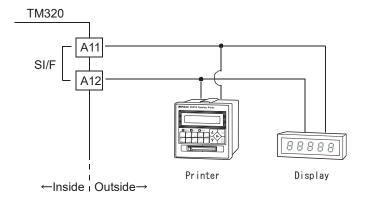
Two-wire serial interface (SI/F) for connecting printers and external display from UNIPULSE.

Connect from A11 and A12 of the external input/output connector.

The interface is nonpolarized and up to three external devices can be connected.

Wiring materials should use a two-core parallel cable, cabtyre cable (electric wire with covering thickened for construction), etc. When a two-core parallel cable or a cabtyre cable is used, the transmission distance is approximately 30m. When a two-core shielded twisted pair wire is used, the transmission distance is approximately 30m.

Do not parallel it with AC lines and high-voltage lines. Doing so will cause malfunction.

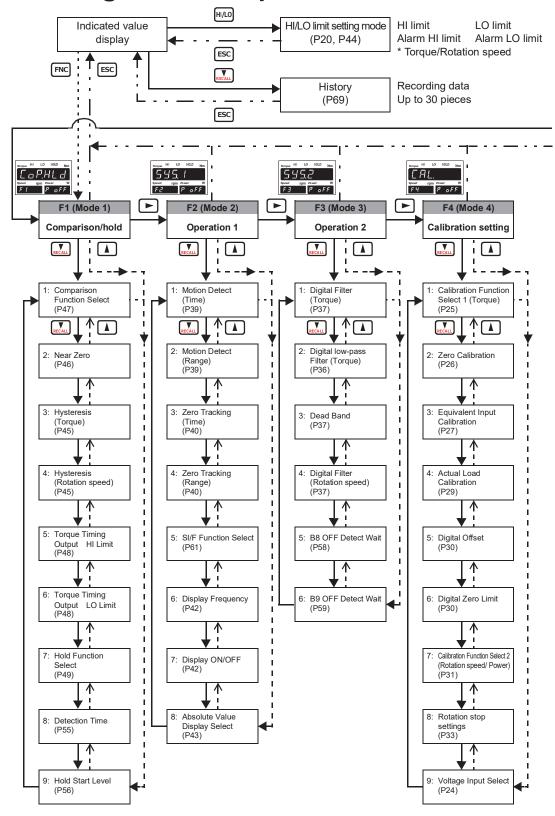


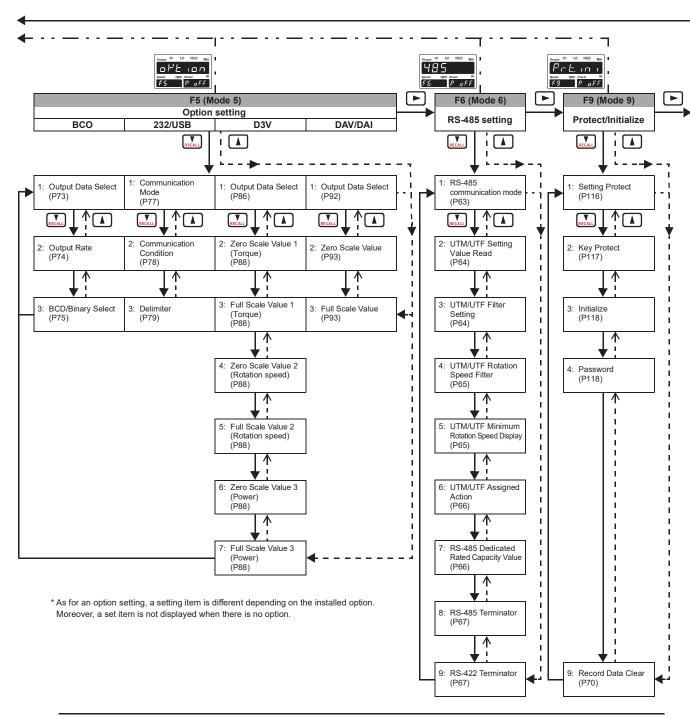
Point

For purchasing peripheral devices, consult our sales department.

3 SETTING MODE CONFIGURATION

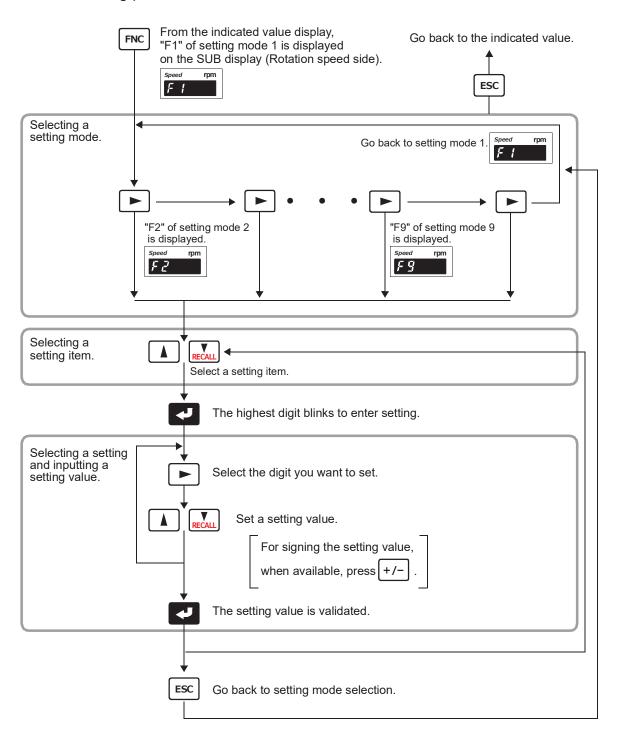
3-1. Setting mode composition





3-2. Key operation

≪Setting procedure≫



Point

If key operation is not performed for one minute or more between the time of pressing the FNC key and the time of validating with the key, the setting is stopped to go back to the indicated value display. In that case, the setting value is not saved.

≪Setting mode select state≫

[Setting mode 1 (COP.HLD)]



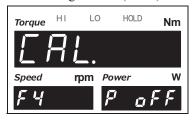
[Setting mode 2 (SYS.1)]



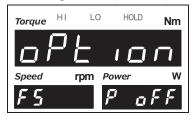
[Setting mode 3 (SYS.2)]



[Setting mode 4 (CAL.)]



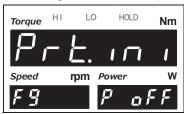
[Setting mode 5 (OPTION)]



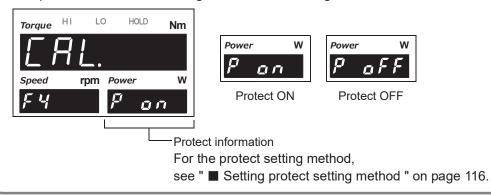
[Setting mode 6 (485)]



[Setting mode 9 (PRT.INI)]





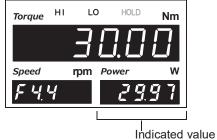


≪Setting item select state≫

[Normal setting item]



【Calibration operation item】 (Zero calibration, equivalent input calibration, actual load calibration)



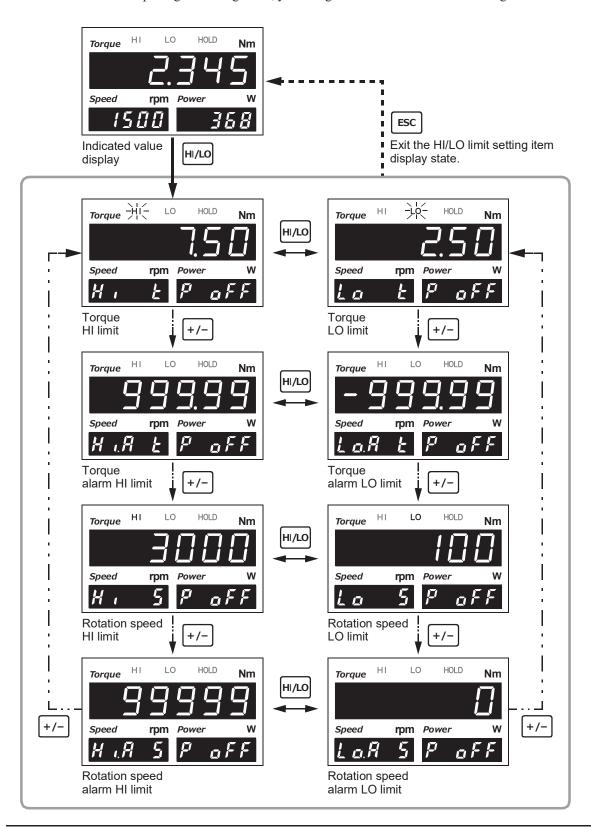
Example) Torque 29.97

≪HI/LO limit setting mode function≫

By pressing [HI/LO] on the indicated value display screen, you can enter a HI/LO limit setting item select state.

Press at the setting value you want to change, and you will go to a setting value input state.

After inputting the setting value, you will go back to the HI/LO limit setting item state.



Torque

Torque

Torque

Torque

F 3.

Chapter 3

Nm

358

Nm

SETTING MODE CONFIGURATION

3-3. Calling a setting mode

Example) For changing the digital filter (torque) from "000" to "256"

- **1.** Press FNC from an indicated value display state.
- **2.** Go to a setting mode select state.

Press twice to make the mode number "3."



LO

HOLD

Nm

rpm Power

3. Go to a setting item select state.

Press RECALL once to select F3-1.

Press 🗗

4. Go to a setting value input state.

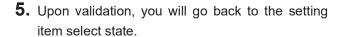
Press **b** to move the setting digit.

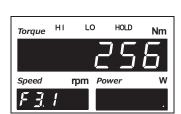
Press to change the numerical value.

Press **U** to validate it.

The change can be cancelled by pressing **ESC**

While a signed setting value is being input, press [+/-] to select whether or not to sign it.







While the lowest decimal place on the sub display (power display side) is lit, writing in NOVRAM is in progress.

If the power is turned off at this time, normal writing cannot be performed.



Chapter



CALIBRATION PROCEDURE

4-1. How to perform calibration

"Calibration" refers to an operation whereby matching between the TM320 and a sensor is obtained. The TM320 uses the two calibration methods as described below.

■ Equivalent input calibration

Calibration is performed without an actual load by entering the rated output value (V) and the capacity (to be indicated) of the sensor by the keys. Calibration is easily performed when no actual load is available.

For example, gain will be automatically decided by registering the values as follows.

for UTMII-0.1Nm: 10.000V - 0.100Nm for UTMII-2Nm: 10.000V - 2.000Nm for UTF-500Nm: 10.000V - 500.00Nm for UTMII -0.1Nm: 5.000V - 0.100Nm for UTMII -2Nm: 5.000V - 2.000Nm

■Actual load calibration

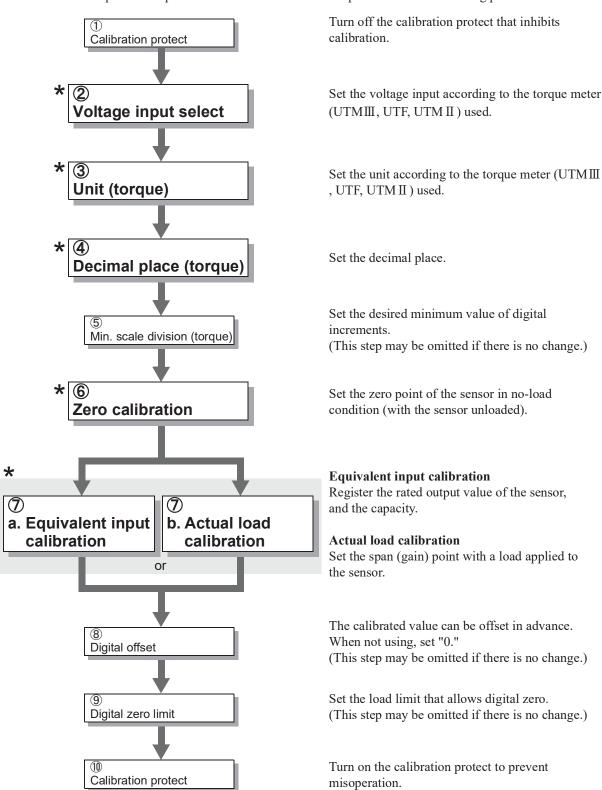
This approach provides calibration by applying an actual load to the sensor and inputting the actual load value. This calibration is without little errors and more correct.

* Perform either actual load calibration or equivalent input calibration.

If an actual load cannot be applied, make sure to perform equivalent input calibration alone.

4-2. Procedure of equivalent input calibration and calibration protect (torque)

The equivalent input calibration and the calibration protect uses the following procedure:



*: It is indispensable.

①Releasing the calibration protect

Turn off the calibration protect that inhibits calibration.

≪Setting value≫

0: OFF Enables rewriting of setting values.

1: ON Disables rewriting of setting values.

♦ Calibration protect setting method

1. Select setting mode 9.

Press $FNC \rightarrow \blacktriangleright$ six times.

2. Set "Calibration protect."

Press RECALL once. ⇒ "Setting protect" is displayed.

Press → twice to make the digit of the calibration protect blink.

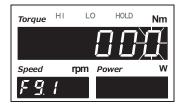
Input the setting value with

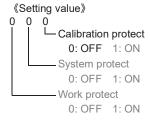
(Initial value: 0)

Press **t** to validate it.

3. Press ESC twice to go back to the indicated value display.







2 Voltage input setting

Select according to the torque output (V) of torque sensor.

Depending on selection, range of calibration & ±LOAD changes.

After this setting, make sure to perform calibration.

For UTF (option), "0: 10V" is fixed.

≪Setting value≫

0: 10V (UTMII/UTF) 1: 5V (UTMII)

♦Voltage input setting method

1. Select setting mode 4.

 $Press \boxed{\textbf{FNC}} \rightarrow \boxed{\hspace{1cm}} \ \ \, \text{three times.}$

2. Set "Voltage input" according to spec of torque sensor.

Press $\fbox{\ \ }$ nine times. \Rightarrow "Voltage input select" is displayed.

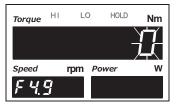
Press , and present set value blinks.

Input the setting value with

Press to validate it. (Initial value: 0)

3. Press ESC twice to go back to the indicated value display.





3 Unit (torque) setting

Set the unit for performing calibration.

After this setting, make sure to perform calibration.

≪Setting value≫

00: mNm 01: Ncm 02: Nm 03: kNm 04: kgm 05: kgcm 06: gcm

4Decimal place (torque) setting

Set the decimal place for load-value-related display, setting items, etc.

≪Setting value≫

0: None 1: 0.0 2: 0.00 3: 0.000



Point

Power is calculated by performing internal conversion based on the unit and decimal place settings. Therefore, do not change these settings improperly after calibration. If they are changed, perform calibration again.

For unit conversion, see "4-6.Unit conversion table" on page 35.

⑤Min. scale division (torque) setting (This step may be omitted if there is no change.)

Set the minimum unit (scale interval, scale division) of the torque.

≪Setting value≫

0: 1 1: 2 2: 5 3: 10 4: 20 5: 50 6: 100

♦ How to set the unit, decimal place, and min. scale division of torque

1. Select setting mode 4.

Press $\lceil FNC \rceil \rightarrow \lceil \blacktriangleright \rceil$ three times.



2. Set "Unit," "Decimal place," and "Min. scale division" н LO HOLD Nm Torque of torque. Press once. \Rightarrow "Calibration function select 1" is Speed rpm displayed. F4 Press , and the highest digit blinks. 《Setting value》 ① Select unit. 0 2 2 Min. scale division Input the unit with and move to the (torque) 0: 1 1: 2 2: 5 3: 10 4: 20 (Initial value: 2) lower digit with Decimal place (torque) 0: None ② Select decimal place. 1: 0.0 2: 0.00 5: 50 Input the decimal place with and move 3: 0.000 6: 100 to the lower digit with . (Initial value: 2) Jnit (torque) 00: mNm 01: Ncm

02: Nm

03: kNm 04: kgm (kgfm)

05: kgcm (kgfcm)

06: gcm (gfcm)

(Initial value: 2)

3 Select min. scale division.

Input the min. scale division with validate it with . (Initial value: 0).

3. Press ESC twice to go back to the indicted value display.

6Zero calibration

Register the zero point with the sensor unloaded. Also, if there is any initial load, such as a jig, for measurements, the zero point can be registered with the initial load applied, but the signal input range needs to be considered as the initial load is subtracted from it.

In addition, there is a way of considering the initial load by using the digital offset. See "®Digital offset (This step may be omitted if there is no change.)" on page 30.

By performing zero calibration, the setting value of zero calibration becomes the sensor output value (V) of the time when it was executed. The load with which zero calibration was performed can be confirmed. However, it stays unchanged when an error occurs.

rpm

Speed

F4

1. Select setting mode 4.



2. Set "Zero calibration."

Press $\[\mathbb{R} \]$ twice. \Rightarrow "Zero calibration" is displayed. Enter a setting value input state with $\[\mathbb{L} \]$, and the entire setting value blinks. (Initial value: 0.000)

Unload the sensor, check the current load value on the sub display (power display side), and press .



Power

3. Zero calibration is executed.

A message as shown on the right-hand side is displayed. If zero calibration is not executed normally, the alarm sounds and an error is displayed.



4. Go back to the setting item select state.

If zero calibration is executed normally, you will go back to the setting item select state, and the output (V) of the time when it was performed will appear.

The example shows that zero calibration was performed at 0.017V.



5. Press ESC twice to go back to the indicated value display.

7a.Equivalent input calibration

Check the specification of the sensor, and register the rated output value and the value you want to display at that time (rated capacity value).

Input the rated output value and display value (rated capacity value) successively.

Equivalent input calibration is not executed by simply inputting the rated output value.

- UTMⅢ

≪Setting value≫

Rated output value [V]: -10.000 to 10.000 (except 0)
Display value (rated capacity): -99999 to 99999 (except 0)

- UTM II

≪Setting value≫

Rated output value [V]: -5.000 to 5.000 (except 0)
Display value (rated capacity): -99999 to 99999 (except 0)

By performing equivalent input calibration, the setting value of actual load calibration becomes the input rated capacity value.

However, it stays unchanged when an error occurs.



Point

Set a display value (rated capacity value) converted according to the set unit and decimal place of torque.

Speed

Torque

Speed

Speed

FY3

rpm Power

For unit conversion, see "4-6.Unit conversion table" on page 35.

1. Select setting mode 4.

Press $\boxed{FNC} \rightarrow \boxed{\blacktriangleright}$ three times.

2. Set "Rated output value" of the sensor.

Press \nearrow three times. \Rightarrow "Equivalent input calibration" is displayed.

Enter a setting value input state with , and the highest digit blinks.

Check the specification of the sensor in use, and input the rated output value (V) with RECALL.

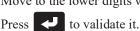
Move to the lower digits with . (Initial value: 10.000)

Press to validate it.

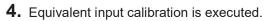
3. Set "Rated capacity value."

Decide the load you want to display at the rated output value, and input it with A RECALL.

Move to the lower digits with



* For inputting a negative sign, press +/-



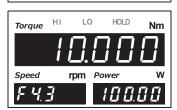
A message as shown on the right-hand side is displayed. If equivalent input calibration is not executed normally, the alarm sounds.

5. If equivalent input calibration is executed normally, you will go back to the setting item select state.



Power

Nm



rpm Power



Point

If the calibration error ($_{\it CErr}$) is displayed, take measures according to each error, and redo calibration. For details, see "12-7.Error/message list" on page 119.

After completion of calibration, make sure to turn on the calibration protect.

7b.Actual load calibration

Apply an actual load, and register the value of the actual load (rated capacity value).

≪Setting value≫
-99999 to 99999 (except 0)

By performing actual load calibration, the setting value of equivalent input calibration becomes the sensor output value (V) of the time when it was executed. The load with which actual load calibration was performed can be confirmed. However, it stays unchanged when an error occurs.



Set a display value (rated capacity value) converted according to the set unit and decimal place of torque.

For unit conversion, see "4-6. Unit conversion table" on page 35.

♦Actual load calibration setting method

1. Select setting mode 4.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ three times.



2. Set "Actual load" of the sensor.

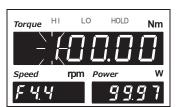
Press $\begin{bmatrix} \text{RECALL} \end{bmatrix}$ four times. \Rightarrow "Actual load calibration" is displayed.

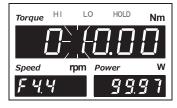
Enter a setting value input state with , and the highest digit blinks.

Check the capacity of the actually-applied load, and input the value with RECALL.

Move to the lower digits with . (Initial value: 10000)

Recheck that the load is properly applied on the sub display (power display side), and press to validate it.





3. Actual load calibration is executed.

If actual load calibration is executed normally, a message as shown on the right-hand side is displayed.

If actual load calibration is not executed normally, the alarm sounds and an error is displayed.

4. If actual load calibration is executed normally, you will go back to the setting item select state.





®Digital offset (This step may be omitted if there is no change.)

This function is to subtract a set value from the indicated value. This function is convenient when zero cannot be obtained with no load for some reason or for offsetting. When not using, set "0."

Speed

F4

Toraue

Speed

Power

rpm Power

Nm

rpm

(Displayed value) = (Actual indicated value)—(Setting value of digital offset)

≪Setting value≫ -99999 to 99999

♦Digital offset setting method

1. Select setting mode 4.

Press $\boxed{\mathbf{FNC}} \rightarrow \boxed{}$ three times.

2. Set "Digital offset."

Press RECALL five times. ⇒ "Digital offset" is displayed.

Press , and the highest digit blinks.

Input the setting value with

Move to the lower digits with . (Initial value: 0)

Validate it with 🛂 .



3. Press ESC twice to go back to the indicated value display.

Digital zero limit (This step may be omitted if there is no change.)

Set the load limit that allows digital zero.

If the absolute value of the load at which digital zero is about to be performed is larger than the setting value, an error will result, and the indicated value will not be zeroed.

≪Setting value≫ 0 to 99999

The amounts of digital zero obtained from the point where zero calibration was performed are monitored.

♦Digital zero limit setting method

1. Select setting mode 4.

Press FNC \rightarrow three times.

2. Set "Digital zero limit."

Press $\underset{\mathsf{RECALL}}{\mathsf{RECALL}}$ six times. \Rightarrow "Digital zero limit" is displayed.

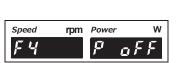
Press, and the highest digit blinks.

Move to the lower digits with . (Initial value: 99999)

Validate it with

Input the setting value with

3. Press ESC twice to go back to the indicated value display.





Chaptei

10Locking the calibration protect

Turn on the calibration protect that inhibits calibration.

≪Setting value≫

0: OFF Enables rewriting of setting values.

1: ON Disables rewriting of setting values.

♦ Calibration protect setting method

1. Select setting mode 9.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ six times.

2. Set "Calibration protect."

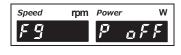
Press \nearrow once. \Rightarrow "Setting protect" is displayed. Press \longrightarrow twice to make the digit of

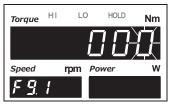
the calibration protect blink.

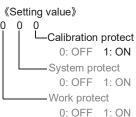
Input the setting value with (Initial value: 0)

Press to validate it.

3. Press ESC twice to go back to the indicated value display.







4-3. Rotation speed/power display settings

Make settings related to the display of rotation speed and power.

①Pulse rate (rotation speed) setting

Select the rate of a pulse input. Set the number of pulses per rotation.

≪Setting value≫ 0: 1 pulse 1: 4

1: 4 pulses 2: 90 pulses (Fixed for UTF option)

②Min. scale division (rotation speed) setting

Set the minimum unit (scale interval, scale division) of the rotation speed.

≪Setting value≫ 0: 1 1: 2 2: 5 3: 10

3Unit (power) setting

Set the unit of the power. The decimal place is not changed automatically.

≪Setting value ≫ 0: mW 1: W 2: kW 3: PS 4: HP

4Decimal place (power) setting

Set the decimal place of power. The unit is not changed automatically.

≪Setting value≫
0: None 1: 0.0 2: 0.00 3: 0.000

5Min. scale division (power) setting

Set the minimum unit (scale interval, scale division) of the power.

≪Setting value≫ 0: 1 1: 2 2: 5 3: 10



Point

Power is calculated by performing internal conversion based on the unit and decimal place settings. Therefore, do not change these settings improperly after calibration. If they are changed, perform calibration again.

For unit conversion, see "4-6.Unit conversion table" on page 35.

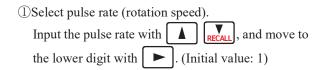
♦ How to set the pulse rate and min. scale division of rotation speed, and unit, decimal place, and min. scale division of power



Set the "Pulse rate" and "Min. scale division" of rotation speed, and "Unit", "Decimal place", and "Min. scale division" of power.

Press $\begin{array}{c} \hline \text{RECALL} \end{array}$ seven times. \Rightarrow "Calibration function select 2" is displayed.

Press , and the highest digit blinks.



②Select min. scale division (rotation speed).

Input the min. scale division with and move to the lower digit with .

(Initial value: 0)

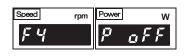
③Select unit (power).

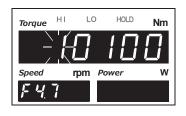
Input the unit with RECALL, and move to the lower digit with . (Initial value: 1)

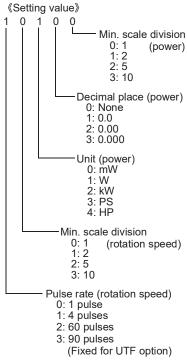
⑤ Select min. scale division (power).

Input the min. scale division with RECALL and validate it with . (Initial value: 0)









4-4. Rotation stop settings for rotation speed

■Minimum input rotation speed (Only for UTMⅢ & UTMⅡ)

Minimum input rotation speed that can be displayed is selectable.

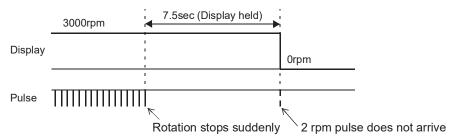
Max. detection time of UTF/60 pulses (F4-7) is 1sec, with min rotation speed at 1rpm.

≪Setting value≫

Pulse rate	Minimum input rotation speed (frequency)					
4 pulses	0: 15 rpm	1: 10 rpm	2: 5 rpm	3: 3 rpm	4: 2 rpm	
1 pulse	0: 60 rpm	1: 40 rpm	2: 20 rpm	3: 12 rpm	4: 8 rpm	
Max. detection time	1 sec	1.5 sec	3 sec	5 sec	7.5 sec	

Example) When set at "2rpm"

Since waiting for pulse detection for the duration of maximum detection time is required when rotation stops suddenly from high speed state, the previous rotation speed is not updated; therefore, the display will become 0 rpm after the display of the rotation speed that was last detected has held for 7.5 seconds.



■Rotation stop mode

Cut-off looks unclear when the rotation stops suddenly due to the constraint of maximum detection time corresponding to the minimum input rotation speed. For this reason, 0 rpm display can be forcibly set with "the cycle of the rotation speed last detected × a certain multiple".

≪Setting value≫

0: OFF (invalid)

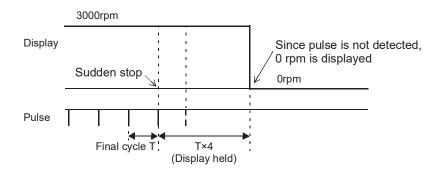
After detection is waited for the duration of the maximum detection time corresponding to the minimum input rotation speed, the display becomes 0 rpm.

1: 2 times 2: 4 times 3: 8 times (valid)

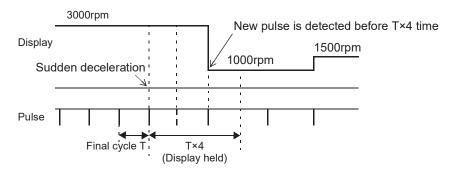
If pulse is not detected from the cycle of the rotation speed last detected to the cycle of the set multiple, the display becomes 0 rpm forcibly.

4

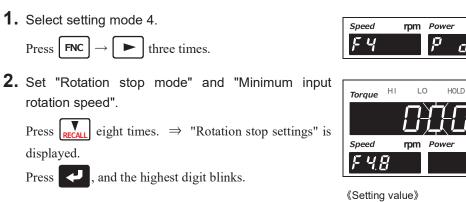
Example) When stopped suddenly with the setting of "4 times"



Example) When decelerated suddenly with the setting of "4 times"



♦ How to set the rotation stop mode and minimum input rotation speed

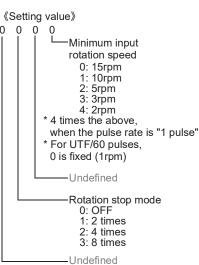


- ① Because the highest digit is undefined, move to the lower digit with .
- ② Select rotation stop mode.

 Input the rotation stop mode with RECALL, and move to the lower digit with .

 (Initial value: 0)
- ③ Select minimum input rotation speed.

 Input the minimum input rotation speed with
 RECALL, and validate it with
 . (Initial value: 0).
- **3.** Press ESC twice to go back to the indicated value display.

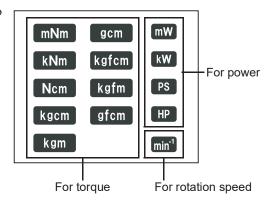


Nm

Chapter

4-5. Unit seal

For torque and power, affix a seal according to the unit at which calibration has been performed. Rotation speed does not matter either way.



4-6. Unit conversion table

Refer to the table for calibration of torque and power and unit setting. After the unit is changed, make sure to affix the attached unit seal.

■ Torque unit conversion table

	mNm	Ncm	Nm	kNm	kgm	kgcm	gcm
mNm	1	0.1	10 ⁻³	10 ⁻⁶	1.0197×10 ⁻⁴	1.0197×10 ⁻²	10.197
Ncm	10	1	10 ⁻²	10 ⁻⁵	1.0197×10 ⁻³	0.10197	1.0197×10^2
Nm	10^{3}	10^{2}	1	10 ⁻³	0.10197	10.197	1.0197×10 ⁴
kNm	10^{6}	10 ⁵	10^{3}	1	1.0197×10^2	1.0197×10^4	1.0197×10 ⁷
kgm	9.8067×10^3	9.8067×10^2	9.8067	9.8067×10 ⁻³	1	10^{2}	10 ⁵
kgcm	98.067	9.8067	9.8067×10 ⁻²	9.8067×10 ⁻⁵	10 ⁻²	1	10 ³
gcm	9.8067×10 ⁻²	9.8067×10 ⁻³	9.8067×10 ⁻⁵	9.8067×10 ⁻⁸	10 ⁻⁵	10 ⁻³	1

■ Power unit conversion table

	mW	W	kW	PS	HP
mW	1	10 ⁻³	10 ⁻⁶	1.3596×10 ⁻⁶	1.341×10 ⁻⁶
W	10 ³	1	10 ⁻³	1.3596×10 ⁻³	1.341×10 ⁻³
kW	10^{6}	10^{3}	1	1.3596	1.341
PS	7.355×10 ⁵	7.355×10^2	0.7355	1	0.9863
HP	7.457×10 ⁵	7.457×10^2	0.7457	1.01387	1

5 EXPLANATION OF INDICATED-VALUE-RELATED FUNCTIONS

5-1. About each indicated value

Torque

Analog signal (±10V) from the UTMIII and UTF is displayed as torque.

Rotation speed

Pulse signal from the UTMIII, UTF and UTMII is displayed as rotation speed.

Power

Power calculated from torque and rotation speed is displayed.

Power [W] = Torque [Nm]×Rotation speed× ω (ω : $2\pi/60 = 0.1047198$)



Point

Based on these data, torque/power characteristics with respect to rotation speed can be obtained.

5-2. Digital low-pass filter

This is a low-pass filter for filtering input signals from the sensor, and canceling unwanted noise components (a filter that passes only the signals with a specific frequency or less, and attenuates signals with higher frequencies). With an increase in the cut-off frequency, the response becomes faster, but noise components may be displayed.

≪Setting value≫ 3 to 1k, PASS [Hz]

■ Digital low-pass filter (torque) setting method

1. Select setting mode 3.



2. Set "Digital low-pass filter (torque)."

Press $\frac{1}{\text{RECALL}}$ twice. \Rightarrow "Digital low-pass filter (torque)" is displayed.

Press , and the highest digit blinks.

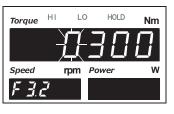
Input the setting value with RECALL.

Move to the lower digits with . (Initial value: 300)

Validate it with

Press | ESC | twice to go back to the indicated value display.





EXPLANATION OF INDICATED- VALUE-RELATED FUNCTIONS

5-3. Digital filter

The digital filter is a function for reducing fluctuations of the indicated value by means of a moving average of data converted. With an increase in the number of filterings, the indicated value becomes more stable, but the response to inputs becomes slower. It can be set for each of the torque and the rotation speed.

≪Setting value≫

OFF(0), 2 to 999 [times]

* One time corresponds to one sampling for A/D conversion.

■ Digital filter (torque) setting method

1. Select setting mode 3.

Press \vdash Twice.

2. Set "Digital filter (torque)."

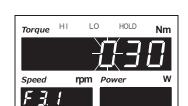
Press RECALL once. ⇒ "Digital filter (torque)" is displayed.

Press , and the highest digit blinks.

Input the setting value with

(Initial value: 030)

Press to validate it.



rpm Power

Speed

F3

- **3.** Press ESC twice to go back to the indicated value display.
- * Digital filter for rotation speed is F3-4.

5-4. Dead band

With respect to torque, the display is forcedly zeroed in a certain range by this function. Use this function when you do not want to display minute changes, such as microvibration, near zero.

≪Setting value≫ 0 to 9999

■Dead band setting method

1. Select setting mode 3.

 $Press \boxed{\textbf{FNC}} \rightarrow \boxed{\blacktriangleright} twice.$

2. Set "Dead band."

Press RECALL three times. ⇒ "Dead band" is displayed.

Press , and the highest digit blinks.

Input the setting value with

Move to the lower digits with . (Initial value: 0000)

Validate it with

3. Press ESC twice to go back to the indicated value display.





5-5. Digital zero

This function is to zero the indicated value.

■Digital zero / Digital zero reset by means of keys

With respect to torque, digital zero can be executed. Digital zero reset can also be executed.

1. Press ZERO on the normal measurement screen.



2. The display becomes as shown on the right-hand side, and execution is waited.

Press C

once to zero the indicated value.

Press 🗾

once to perform digital zero reset of

the indicated value.

Press ESC once to cancel the state for execute-wait and go back to the indicated value display state.

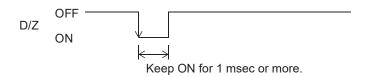




- If the digital offset is set, even if digital zero is executed, zero will not result. (Indicated value = -Setting value of digital offset)
- When digital zero reset is performed, the condition previous to correction by digital zero is restored.

■Digital zero by means of the external signal "D/Z input"

The instant when D/Z and COM2 of the external input/output connector are short-circuited from an open state (ON edge), digital zero functions to zero torque.



⚠ CAUTION

Digital zero will reset during power outage.

After recovering from power failure, digital zero again if necessary.

5-6. Motion detect

Set the parameters to detect stability of torque.

If the difference between the current indicated value and the 50-msec-previously indicated value becomes less than the set count and that condition continues for more than the set time, the indicated value is regarded as stable.

≪Setting value≫

Motion detect (time) 0.0 to 9.9 [second]
Motion detect (range) 000 to 999 [count]

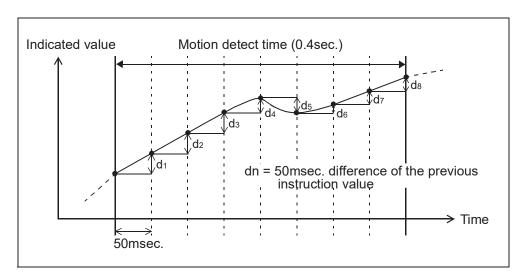
Point

When the time is 0.0 sec. and the width is 000 markings, stable is not detected. Stability detection by motion detect is closely related to the SI/F print (stable value) function and comparison timing. For details, see "6-4.Comparison timing" on page 47 and "

SI/F print" on page 61.

Setting example

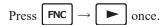
Motion detect (time) 0.4 sec. Motion detect (range) 010



When the condition of dn \leq set count (010) continues for the set time (0.4 sec.) or more (d1 \leq 10, and d2 \leq 10, and ..., and d8 \leq 10), the indicated value is regarded as stable.

■ Motion detect setting method

1. Select setting mode2.



2. Set "Motion detect (time)."

Press RECALL once. ⇒ "Motion detect (time)" is displayed.

Press , and the highest digit blinks.

Input the setting value with

Move to the lower digits with . (Initial value: 0.0)

Press to validate it.

3. Set "Motion detect (range)."

Press $\stackrel{\text{RECALL}}{}$ once. \Rightarrow "Motion detect (range)" is displayed.

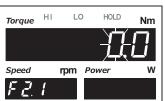
Press , and the highest digit blinks.

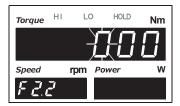
Input the setting value with RECALL

Move to the lower digits with ► . (Initial value: 000)

Press to validate it.







4. Press ESC twice to go back to the indicated value display.

5-7. Zero tracking

This function is to automatically track and correct gradual changes in the zero point due to drifts (phenomenon in which outputs fluctuate slowly due to temperature change or change with time), etc.

≪Setting value≫

Zero tracking (time) 0.0 to 9.9 [second]
Zero tracking (range) 000 to 999 [count]

■Zero Tracking setting method

1. Select setting mode 2.







2. Set "Zero tracking (time)."

Press \fbox{RECALL} three times. \Rightarrow "Zero tracking (time)" is displayed.

Press, and the highest digit blinks.

Input the setting value with RECALL.

Move to the lower digits with . (Initial value: 0.0)

Press to validate it.



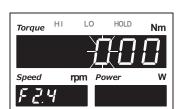
Press \bigcirc once. \Rightarrow "Zero tracking (range) " is displayed.

Press , and the highest digit blinks.

Input the setting value with

Move to the lower digits with ▶. (Initial value: 000)

Press to validate it.



LO

rpm Power

Nm

Torque

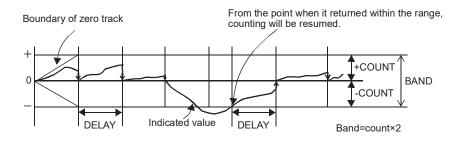
Speed

4. Press ESC twice to go back to the indicated value display.

Point

- When displacement of the zero point is within the set count of tracking and it continues more than the set time, it is automatically made zero by zero tracking function.
- The time (tracking delay) is set in the range of 0.1 9.9 sec., and the band (tracking band) is set in the range of 001 to 999.

If the time is set at 0.0 sec. and the band at 000, the zero tracking function does not work.



⚠ CAUTION

- Zero tracking is equal to digital zero functioning automatically. Therefore, the digital zero limit is also monitored.
- Zero tracking does not function if the indicated value has already exceeded the tracking band.

Chapter **5**

EXPLANATION OF INDICATED- VALUE-RELATED FUNCTIONS

5-8. Display frequency

Set the per-second display update frequency of the indicated value. However, the A/D conversion speed does not change.

≪Setting value≫
0: 3 1: 6 2: 13 3: 25 [times/sec.]

■ Display frequency setting method

1. Select setting mode 2.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ once.

2. Set "Display frequency."

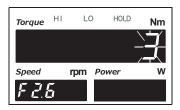
Press \Longrightarrow "Display frequency" is displayed.

Press , and present set value blinks.

Input the setting value with RECALL.

Press to validate it. (Initial value: 3)





3. Press ESC twice to go back to the indicated value display.

5-9. Display ON/OFF

The display of rotation speed and power can be turned ON/OFF by this function.

Torque is always displayed.

Also, internal computation is not stopped.

■ Display ON/OFF setting method

1. Select setting mode 2.

 $Press \ \boxed{\textbf{FNC}} \rightarrow \boxed{\hspace{1cm}} \ \text{once}.$

2. Set "Display ON/OFF."

Press $_{\text{RECALL}}$ seven times \Rightarrow "Display ON/OFF" is displayed.

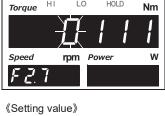
Press , and present set value blinks.

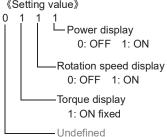
Input the setting value with RECALL.

Press to validate it. (Initial value: 0111)

3. Press ESC twice to go back to the indicated value display.







5-10. Absolute value display select

This setting allows judgement according to torque absolute value display.

Use this setting if you want judge in situation where torque value is always + sign in left or right rotation.

≪Setting value≫

0: Not valid 1: Valid (marked) 2: Valid (Without mark)

■ Absolute value display select setting method

1. Select setting mode 2.

Press FNC \rightarrow once

2. Set "Absolute value display select."

Press \bigcirc eight times \Rightarrow "Absolute value display select" is displayed.

Press , and present set value blinks.

Input the setting value with

Press to validate it. (Initial value: 0)





3. Press ESC twice to go back to the indicated value display.

) Point

After judgement of absolute value, select "1: Valid (marked)" if you want to know whether the current torque is positive or negative.

The mark is displayed for current torque only, as it does not link with hold value. If reading is minus, "_" is shown instead of "-".

If absolute value is selected at B2 output selection, it will turn ON based on 2 conditions: (1) Value is minus (2) "1: Valid (marked)" is selected.

For details, see "■Timing output" on page 48.

Chapter

6

6 EXPLANATION OF COMPARISON FUNCTIONS

6-1. HI/LO limit comparison

Set the HI/LO limit of torque and rotation speed. (Hold synchronized)

≪Setting value≫

- Torque

HI limit/LO limit: -99999 to 99999

- Rotation speed

HI limit/LO limit: 0 to 99999

<HI/OK/LO output conditions>

- HI Indicated value > HI limit- LO Indicated value < LO limit

- OK LO limit ≦ Indicated value ≦ HI limit

Point

With ±LOAD, OFL1, or OFL2 on torque, torque HI, LO is forcedly turned on. With OFL2 on rotation speed, rotation speed HI, LO is forcedly turned on.

Overload of the torque and rotation speed is monitored. (Hold not synchronized)

When they exceed the alarm HI limit or fall below the alarm LO limit, the external output "ALM" turns ON.

≪Setting value≫

- Torque

Alarm HI limit: -99999 to 99999 (invalid at 99999 (initial value))
Alarm LO limit: -99999 to 99999 (invalid at -99999 (initial value))

- Rotation speed

Alarm HI limit: 0 to 99999 (invalid at 99999 (initial value))
Alarm LO limit: 0 to 99999 (invalid at 0 (initial value))

- For initial value, since both the alarm HI and LO limits are invalid as default settings, set them again for use.
- Since the alarm HI limit and LO limit are independent, simple use of either one of them is also possible.

■HI/LO limit setting method

See "≪HI/LO limit setting mode function > " on page 20.

■Alarm HI and LO limits setting method

See "≪HI/LO limit setting mode function»" on page 20.

6-2. Hysteresis

This function is to allow a margin for timing at which HI/LO of the HI/LO limit comparison is turned off. Normally, HI is turned on when the indicated value exceeds the HI limit and is turned off when the indicated value falls below it. However, by setting the hysteresis, HI is turned off when the indicated value falls below the HI limit further lowered by the hysteresis value. This function is effective to prevent chattering (phenomenon in which signals repeat turning on/off immediately after switching of relay contacts and switch contacts) in such a case where signals fluctuate (vibrate) subtly.

≪Setting value≫

Hysteresis range: 0 to 9999

<HI/LO output conditions>

- HI

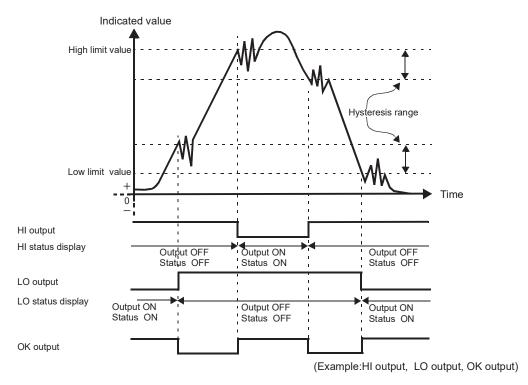
ON conditions Indicated value > HI limit

OFF conditions Indicated value ≤ (HI limit setting value – Hysteresis setting value)

- LO

OFF conditions Indicated value ≥ (LO limit setting value – Hysteresis setting value)

- Hysteresis operation



Point

Torque and rotation speed can be set to HI/LO limit comparison, respectively. However, this does not apply to timing output and alarm HI and LO limits.

Hysteresis setting method

1. Select setting mode1.

Press FNC once.

2. Set "Hysteresis."

Press $| \mathbf{recall} |$ three times \Rightarrow "Hysteresis (Torque)" is displayed.

Press $|_{RECALL}|$ four times for rotation speed \Rightarrow

"Hysteresis (Rotation speed)" is displayed.

Press , and the highest digit blinks. Input the setting value with

Move to the lower digits with ▶ . (Initial value: 0)

to validate it. Press

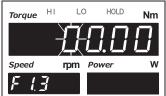
3. Press | ESC | twice to go back to the Indicated value display.



rpm

Speed

Power



Power

Power

Nm

rpm

Speed

F 1.2

6-3. Near zero

This function is to detect that the torque is near zero.

|Torque| ≤ Setting value of near zero Near zero ON: Near zero OFFF: |Torque| > Setting value of near zero

≪Setting value≫ 0 to 99999

Point

Near zero ON/OFF is closely related to the SI/F print (stable value) function and comparison timing.

For details, see "6-4. Comparison timing" on page 47, and "■SI/F print" on page 61.

■ Near zero setting method

1. Select setting mode1.

Press FNC once.

2. Set "Near zero."

Press $| \mathbf{r}_{\mathsf{RECALL}} |$ twice \Rightarrow "Near zero" is displayed.

, and the highest digit blinks. Press

Input the setting value with Move to the lower digits with ▶ . (Initial value: 100)

Press **t** to validate it.

3. Press | ESC | twice to go back to the indicated value display.

Point Near zero operates by absolute value.



6-4. Comparison timing

Set the operating conditions of HI/LO limit comparison (Torque). Select the conditions from the following.

O: All time HI/LO limit comparison is always performed.1: Stable When stable, HI/LO limit comparison is performed.

2: Near zero OFF HI/LO limit comparison is performed when

Near zero is off.

3: Stable and Near zero OFF When stable and near zero is off, HI/LO limit

comparison is performed.

4: Hold HI/LO limit comparison is performed when a hold is

decided.

Set the operating conditions of HI/LO limit comparison (Rotation speed). Select the conditions from the following.

0: All time HI/LO limit comparison is always performed.

1: Torque synchronized HI/LO limit comparison is performed at the same timing

as that of the torque comparison timing.

■Comparison timing (Torque), Comparison timing (Rotation speed), B2 output selection setting method

1. Select setting mode1.

Press FNC once.

(Initial value: 0)

2. Set "Comparison timing (Torque), Comparison timing (Rotation speed), B2 output selection."

Press $\stackrel{\mathsf{RECALL}}{\mathsf{lonce}}$ once. \Rightarrow "Comparison function select" is displayed.

Press , and the highest digit blinks.

① Set "Comparison timing (Torque)."

Input the comparison timing (torque) with

RECALL, and move to the lower digit with ...

② Set "Comparison timing (Rotation speed)."

Input the comparison timing (rotation speed) with

RECALL, and move to the lower digit with

.(Initial value: 1)

③ Set "B2 output selection."

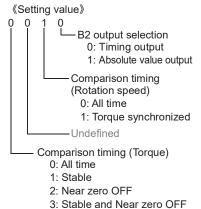
Input the B2 output selection with RECALL. (Initial value: 0)

Press to validate it.

3. Press ESC twice to go back to the indicated value display.



Power



4. Hold

47

6



Point

B2 output can be either timing output or absolute value output.

Refer to "5-10.Absolute value display select" on page 43 for absolute value display select.

■Timing output

Outputs a signal in synchronization with current torque value.

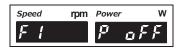
 $\mathsf{ON}:$ Torque timing output LO limit $\leqq \mathsf{Torque} \leqq \mathsf{Torque}$ timing output HI limit

OFF: Torque < Torque timing output LO limit
Torque > Torque timing output HI limit

Torque timing output HI limit: -99999 to 99999 Torque timing output LO limit: -99999 to 99999

1. Select setting mode1.

Press FNC once.



2. Set "Torque timing output HI limit."

Press $\begin{picture}(1,0)\put(0,0){\line(0,0){100}}\put$

Press, and the highest digit blinks.

Input the setting value with RECALL

Move to the lower digits with ► . (Initial value: 99999)

Press to validate it.



Nm

Toraue

3. Set "Torque timing output LO limit."

Press \nearrow once. \Rightarrow "Torque timing output LO limit" is displayed.

Press , and the highest digit blinks.

Input the setting value with RECALL.

Move to the lower digits with . (Initial value: -99999)

Press **t**o validate it.

Press ESC twice to go back to the indicated value display.

7 EXPLANATION OF HOLD FUNCTIONS

7-1. Hold functions of torque

The hold functions are to take out a specific point of torque for HI/LO limit comparison. Here, the operation of each hold will be described in detail.

Hold mode	Hold section	
0: OFF	None	
1: Sample	0: All section 1: External signal	
2: Peak	0: All section	
3: Bottom	1: External signal	
4: P-P	2: External signal+Time	
5: Average	3: Level+Time	

■Flow of hold measurement

- 1. Select a hold you want to use.
- **2.** If the hold has the setting of section, set a section you want to use. For details, see "7-3.Setting of hold section" on page 53.
- 3. Set the special setting value required for the hold used.
- **4.** After confirmation of wiring, perform hold control by external input etc., and start measurement.

7-2. Setting of hold mode

■ Hold mode setting method

1. Select setting mode 1.

Press FNC once.

2. Set "Hold mode."

Press RECALL seven times ⇒ "Hold function select " is displayed.

Press , and the highest digit blinks.

Move to the lower digits with .

Input the setting value with

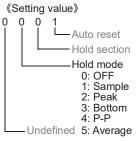
(Initial value: 0)

Validate it with

Press ESC twice to go back to the indicated value display.





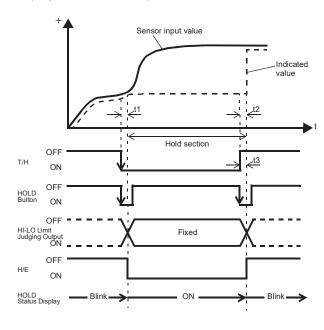


■Sample hold

The start point of the specified section is held.

The section is specified by the setting of "all section" or "external signal."

(Example) All section sample hold

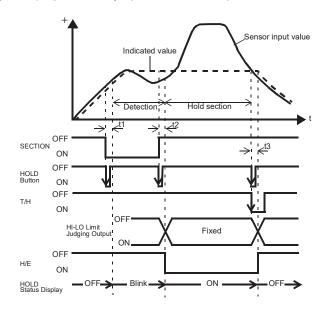


- t1: A delay time between the instant when the T/H signal is inputted and the instant when the indicated value is held Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the T/H signal is released and the instant when the indicated value returns to tracking Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

Peak hold

The maximum value in the positive direction (peak value) of the specified section is held. The section is specified by the setting of "all section", "external signal", "external signal+time", or "level+time".

(Example) Externally specified section peak hold

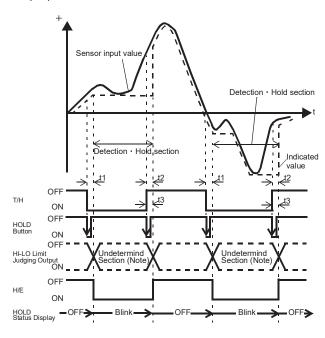


- t1: A delay time between the instant when the SECTION signal is inputted and the instant when the value to be held is detected Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the SECTION signal is released and the instant when the value to be held is determined Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

■Bottom hold

The maximum value in the negative direction (bottom value) of the specified section is held. The section is specified by the setting of "all section", "external signal", "external signal+time", or "level+time".

(Example) All section Bottom hold



- t1: A delay time between the instant when the T/H signal is inputted and the instant when the indicated value is held
 Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the T/H signal is released and the instant when the indicated value returns to tracking Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

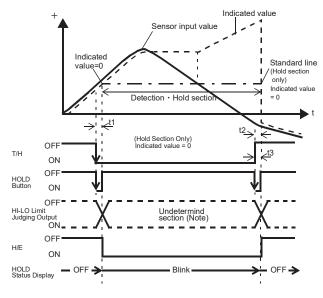
Note: During the undetermined section, the judging output varies with fluctuations in the input waveform. However, the H/E output remains on during the undetermined Section. Read the judging result when the indicated value becomes stable (immediately before the T/H signal rises).

■Peak-to-Peak (P-P) hold

The difference value between the peak and valley over the specified section is held.

The section is specified by the setting of "all section", "external signal", "external signal+time", or "level+time".

(Example) All section Peak-to-Peak (P-P) hold



- t1: A delay time between the instant when the T/H signal is inputted and the instant when the indicated value is held
 - Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the T/H signal is released and the instant when the indicated value returns to tracking Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

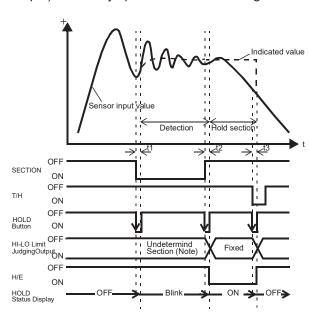
Note: During the undetermined section, the judging output varies with fluctuations in the input waveform. However, the H/E output remains on during the undetermined section. Read the judging result when the indicated value becomes stable (immediately before the T/H signal rises).

Average hold

The average of the sampling values over the specified section is calculated and updated, and then

The section is specified by the setting of "all section", "external signal", "external signal+time", or "level+time".

(Example) Externally specified section average value hold



- t1: A delay time between the instant when the SECTION signal is inputted and the instant when the value to be held is detected Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the SECTION signal is released and the instant when the value to be held is determined Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)



Point

Detection time for maximum average value in average value hold

Although the detection section is specified by the SECTION signal, etc., detection cannot be carried out exceeding the maximum average value detection time. If the maximum average value detection time is exceeded, detection ends automatically, when the average value is held.



Point

When a hold is used, rotation speed is also held.

The hold value of rotation speed is as follows:

- < Sample/ Peak/ Bottom > Hold at the hold point of torque
- < P-P/ Average > Hold at the end point of section

Holding of torque and rotation speed will also result in holding of power.

7-3. Setting of hold section

■ Hold section setting method

1. Select setting mode 1. Press FNC once.

2. Set "Hold section."

Press $\stackrel{\text{RECALL}}{}$ seven times \Rightarrow "Hold function select" is displayed.

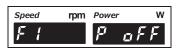
Press , and the highest digit blinks.

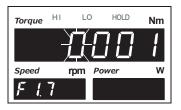
Press twice to make the digit of the Hold section blink. (Initial value: 0)

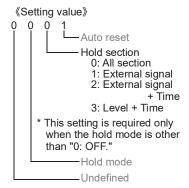
Input the setting value with

Press **U** to validate it.

3. Press ESC twice to go back to the indicated value display.







■ All section

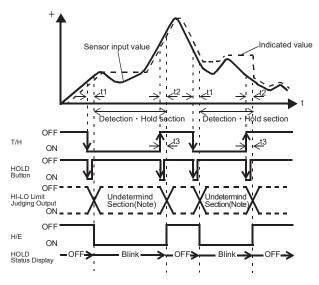
By this method, the hold detection section is specified by the T/H signal.

Detection starts with the T/H signal ON to perform each hold operation.

Control is performed simply by the T/H signal without using the SECTION signal.

Therefore, there are tracking sections and detection sections, but there are no hold deciding sections.

(Example) All section peak hold



- t1: A delay time between the instant when the T/H signal is inputted and the instant when the indicated value is held
 Approximately 1.0ms (MAX.)
 - ripproximatery rooms (ivii ixi.)
- t2: A delay time between the instant when the T/H signal is released and the instant when the indicated value returns to tracking Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)
- Note: During the undetermined sections, the judging output varies with fluctuations in the input waveform. However, the H/E output remains on during the undetermined ections. Read the judging result when the indicated value becomes stable (immediately before the T/H signal rises).

■External signal

By this method, the hold detection section is specified by the SECTION signal.

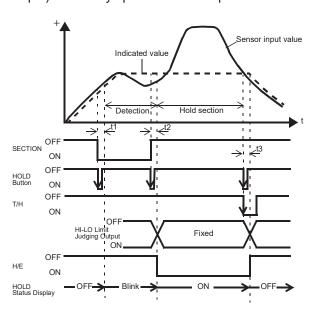
Detection starts with the SECTION signal ON, and ends with the SECTION signal OFF to perform each hold operation.

The hold value is maintained until the hold reset signal is turned on.

The hold is released by turning on the T/H signal as a reset signal.

There are tracking sections, detection sections, and hold deciding sections.

(Example) Externally specified section peak hold



- t1: A delay time between the instant when the SECTION signal is inputted and the instant when the value to be held is detected Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the SECTION signal is released and the instant when the value to be held is determined Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

By turning on the SECTION signal again without turning on the T/H signal while the hold is decided, the hold is released and re-detection is started. For details, see "7-4.Auto reset function" on page 57.

■External signal + time

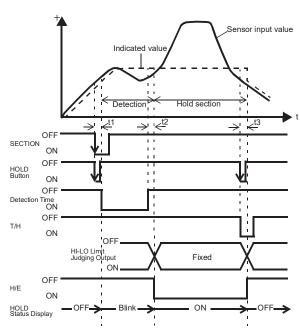
By this method, the hold detection section is specified as a timer. Detection starts with the SECTION signal ON, and ends when the set time (detection time) has elapsed.

The hold value is maintained until the hold reset signal is turned on.

The hold is released by turning on the T/H signal as a reset signal.

There are tracking sections, detection sections, and hold deciding sections.

(Example) External signal + Time specified section peak hold



- t1: A minimum SECTION signal width required for beginning detection Approximately 1.0ms (MAX.)
- t2: A delay time between the instant when the detection time is ended and the instant when the value to be held is determined Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

By turning on the SECTION signal again without turning on the T/H signal while the hold is decided, the hold is released and re-detection is started.

For details, see "7-4. Auto reset function" on page 57.

■ Detection time

Set the hold detection time.

《Setting value》 0.01 to 9.99 [sec.]

Detection time setting method

1. Select setting mode 1. Press FNC once.

2. Set "Detection time."

Press $|_{RECALL}|$ eight times \Rightarrow "Detection time" is displayed. Press , and the highest digit blinks.

Move to the lower digits with ► . (Initial value: 1.00)

Press **U** to validate it.

Speed rpm Power 1.8 Input the setting value with

Speed

Torque

F

rpm

Ø

ΩF

Nm

3. Press | ESC | twice to go back to the indicated value display.

EXPLANATION OF HOLD FUNCTIONS

■Level + time

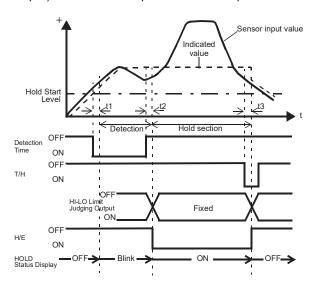
By this method, the hold detection section is specified as a timer. Hold is detected during the predetermined time (hold section time) from the point in time when the torque crosses the hold start level.

The hold value is maintained until the hold reset signal is turned on.

The hold is released by turning on the T/H signal as a reset signal.

There are tracking sections, detection sections, and hold deciding sections.

(Example) Level + Time specified section peak hold



- t1: A delay time between the instant when the indicated value exceeds the hold start level and the instant when the value to be held is detected
- Approximately 0.5ms (MAX.)
- t2: A delay time between the instant when the detection time is ended and the instant when the value to be held is determined

 Approximately 1.0ms (MAX.)
- t3: A minimum reset signal width required for releasing the hold Approximately 1.0ms (MIN.)

■ Hold start level

Set the start level in the case where the Section setting is Level + Time for Peak, Valley, PP, or Average hold.

《Setting value》 -99999 to 99999

♦ Hold start level setting method

1. Select setting mode 1. Press FNC once.

2. Set "Hold start level."

Press $\begin{array}{|c|c|}\hline & & \\\hline & \\\hline & & \\\hline$

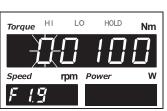
Press , and the highest digit blinks.

Move to the lower digits with . (Initial value: 100)

Input the setting value with Press to validate it.

3. Press ESC twice to go back to the indicated value display.

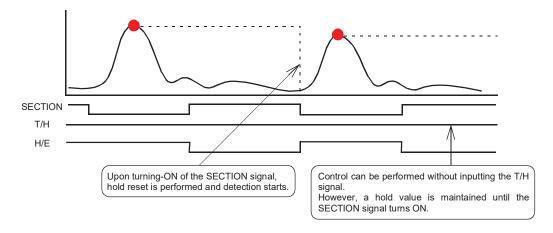




7-4. Auto reset function

It is factory-set that each hold is automatically reset at the start of the detection section, and therefore, simple control can be performed by one signal without releasing the hold.

Example) Auto reset in externally specified section peak hold

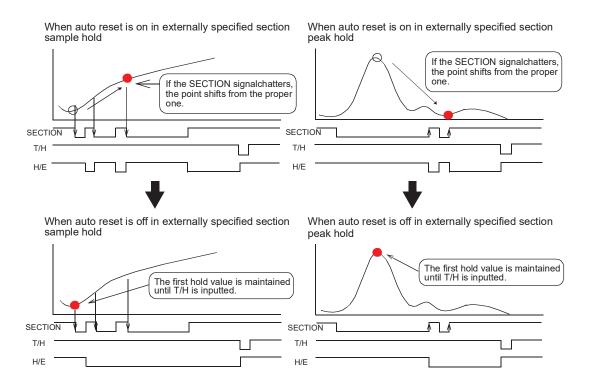


However, when the auto reset functions, if the signal causes chattering, the point that should be taken originally may deviate. Switching is provided so as to prevent the next detection from being performed until the T/H signal is turned on even if the SECTION signal is turned on again.

《Setting value》

0: OFF After a hold is decided, the next detection is not started until the T/H signal is turned on even if the SECTION signal is turned on.

1: ON After a hold is decided, the next detection is started when the SECTION signal is turned on again even if the T/H signal is not turned on. This is the initial setting (factory default setting).



■ Auto reset setting method

1. Select setting mode 1.

Press FNC once.

2. Set "Auto reset."

Press \mathbb{RECALL} seven times \Rightarrow "Hold function select" is displayed.

Press, and the highest digit blinks.

Press htree times to make the digit of the auto

reset blink. (Initial value: 1)

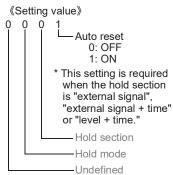
Input the setting value with RECALL

Press to validate it.

3. Press ESC twice to go back to the indicated value display.







7-5. B8 OFF detect wait

Hold is controlled by the T/H signal alone, detection/hold section is assured during the set waiting time. This is convenient for ignoring chattering parts.

The timer functions so as to also ignore chattering when the OFF edge is detected.

《Setting value》 0.00 to 9.99 [sec.]

■B8 OFF detect wait

1. Select setting mode 3.

 $Press \quad \boxed{\textbf{FNC}} \rightarrow \boxed{\hspace{1cm}} \quad \text{twice}$

2. Set "B8 OFF detect wait."

Press $\stackrel{\text{RECALL}}{\text{RECALL}}$ five times \Rightarrow "B8 OFF detect wait" is displayed.

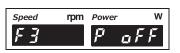
Press , and the highest digit blinks.

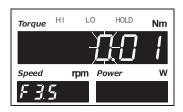
Input the setting value with RECALL

Move to the lower digits with \triangleright . (Initial value: 0.01)

Press to validate it.

3. Press ESC twice to go back to the indicated value display.





Speed

Torque

F 3.6

Power

rpm

rpm

Chapter

EXPLANATION OF HOLD FUNCTIONS

7-6. B9 OFF detect wait

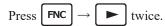
In hold controlled by the T/H signal alone, detection/hold section is assured during the set waiting time. This is convenient for ignoring chattering parts.

The timer functions so as to also ignore chattering when the OFF edge is detected.

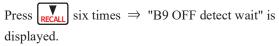
《Setting value》 0.00 to 9.99 [sec.]

■B9 OFF detect wait

1. Select setting mode 3.



2. Set "B9 OFF detect wait."



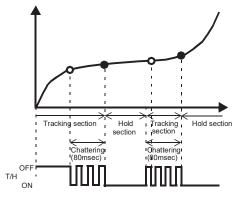
Press , and the highest digit blinks.

Input the setting value with Move to the lower digits with \triangleright . (Initial value: 0.01)

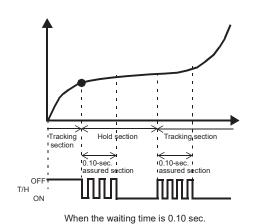


3. Press | ESC | twice to go back to the indicated value display.

Example) Sample hold



When the waiting time is 0.00 sec.



Chapter

8 STANDARD INTERFACE

8-1. External I/O

■Connector pin assignment

A1		COM1	B1		COM1
A2	OUT	ALM HI (Torque)	B2	OUT	Timing output/ Absolute value output
A3	OUT	HI (Torque)	В3	OUT	H/E
A4	OUT	OK (Torque)	B4	OUT	ALM HI (Rotation speed)
A5	OUT	LO (Torque)	B5	OUT	ALM LO (Rotation speed)
A6	OUT	ALM LO (Torque)	B6	OUT	RUN
A7		COM1 (Torque)	B7		COM2
A8	OUT	HI (Rotation speed)	B8	IN	SECTION
A9	OUT	OK (Rotation speed)	B9	IN	T/H
A10	OUT	LO (Rotation speed)	B10	IN	
A11	OUT	SI/F	B11	IN	DZ
A12	OUT	SI/F	B12	IN	CLEAR

Compatible connector: FCN-361J024-AU (manufactured by FUJITSU COMPONENT or equivalent)

Connector cover: FCN-360C024-B (manufactured by FUJITSU COMPONENT or equivalent)

(connector & cover optional type: CN50)

■About outputs

A1, A7, B1	Common for external output signals.	→"■External I/O connection " on page 14	
A2	Outputs the alarm HI limit signal of torque.		
A3	Outputs the HI limit signal of torque.		
A4	Outputs the OK signal of torque.	→"6.EXPLANATION OF COMPARISON	
A5	Outputs the LO limit signal of torque.		
A6	Outputs the alarm LO limit signal of torque.	FUNCTIONS " on page 44	
A8	Outputs the HI limit signal of rotation speed.		
A9	Outputs the OK signal of rotation speed.		
A10	Outputs the LO limit signal of rotation speed.		
B2	Output signal varies. Choose either timing output or absolute value output.	→"5-10.Absolute value display select " on page 43 "■ Timing output " on page 48	
В3	Outputs the hold complete signal.	→"7.EXPLANATION OF HOLD FUNCTIONS" on page 49	
B4	Outputs the alarm HI limit signal of rotation speed.	→"6.EXPLANATION OF COMPARISON	
B5	Outputs the alarm LO limit signal of rotation speed.	FUNCTIONS " on page 44	
В6	Outputs the normal run signal.	→"■About the RUN signal " on page 61	
A11, A12	2-wire serial interface for connecting a UNIPULSE-manufactured printer, external display, etc.	→"■SI/F interface connection " on page 15 "8-2.SI/F (serial interface) " on page 61	

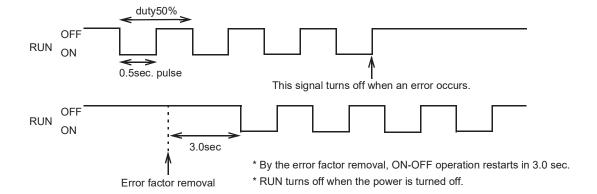
■About inputs

В7	Common for external input signals.	→"■External I/O connection " on page 14
B8, B9	Inputs the hold control signal.	→"7.EXPLANATION OF HOLD FUNCTIONS" on page 49
B11	Inputs the Digital Zero signal.	→"5-5.Digital zero " on page 38
B12	Input for record data clear.	→"9-3.Record data clear " on page 70

■ About the RUN signal

The RUN output stops when an abnormal state of the indicated value is detected. The conditions under which the output stops as in an abnormal state are as follows.

- ±LOAD
- OFL1, OFL2
- Calibration error
- Digital zero limit error
- * See "12-7.Error/message list" on page 119 about the contents of errors.



8-2. SI/F (serial interface)

■SI/F indicated value format

GROSS area: Torque

NET area: Rotation speed

TARE area: Power

■SI/F print

《Setting value》

0: None No print command is sent.

1: Stable value When stability is detected, a print command is sent to the SI/F to make the

connected printer print automatically. When near zero is OFF, the torque

is held until near zero ON after stable ON.

Hold is reset in 1.5 sec. after near zero ON.

2: Hold value When hold is reset, a print command is sent to make the connected

printer print the hold value automatically.

(When the hold mode is OFF, turn on T/H or press |HOLD|.)



Point

When stable value print is selected, be aware that automatic printing is not performed in the following case.

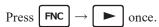
- When motion detect is set in time: 0.0 sec, count: 000. Also, the indicated value is not held in the following case.
- Hold mode: When any item other than none is selected.

Chapter

8

♦SI/F print setting method

1. Select setting mode 2.



2. Set "SI/F print."

five times \Rightarrow "SI/F function select" is displayed.

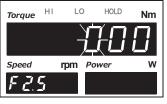
, and the highest digit blinks. Select the digit Press of the SI/F print.

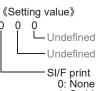
Input the setting value with (Initial value: 0)

Press to validate it.

3. Press twice to go back to the indicated value display.

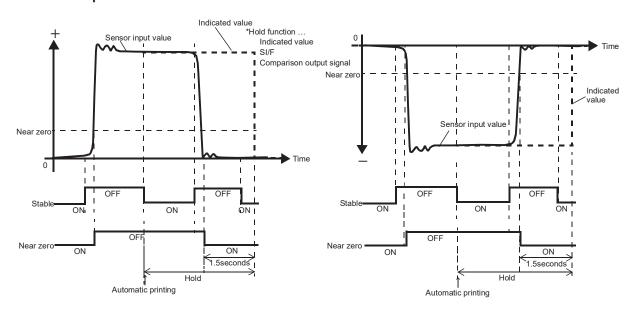






- 1. Stable value
- 2: Hold value

- Operation of the indicated value hold function



For the "Stable" parameter, see "5-6.Motion detect " on page 39, and for the "Near zero" parameter, see "6-3.Near zero" on page 46.



Point

The print command and the record function are closely related. For details, see "9-1.Record timing " on page 69.

8-3. RS-485

Usable when connecting to UTMIII & UTF (TM320 option).

You can use RS-485 to change settings, digital zero, display torque and rotation speed of UTMIII & UTF (TM320 option).

Communication specifications

Signal level Based on RS-485

Transmitting distance Approx. 1 km

Transmitting method Asynchronous, Full duplex

Transmitting speed 230.4kbps

Bit configuration Start bit: 1bit

Character length: 8bit

Stop bit: 1bit Parity: none Terminator: CR

Code ASCII

■RS-485 communication mode

In communication mode, select RS-485 command mode / RS-485 display mode / invalid.

《Setting value》

0: RS-485 command mode 1: RS-485 display mode 2: Invalid

1. Select setting mode 6.

 $Press \boxed{\textbf{FNC}} \rightarrow \boxed{\hspace{1.5cm}} \qquad \qquad \boxed{\hspace{1.5cm}} \qquad \qquad \text{five times.}$

Speed rpm Power W

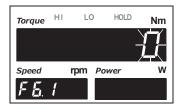
2. Set "RS-485 communication mode."

Press \fbox{RECALL} once. \Rightarrow "RS-485 communication mode" is displayed.

Press , and present set value blinks.

Input the setting value with

Press to validate it. (Initial value: 0)



■Read setting values from UTM/UTF

Read the following setting values from UTM/UTF.

* Only applicable when "0: RS-485 command mode" "1: RS-485 display mode" is selected in communication mode.

《Setting value》

0: Cancel 1: Filter setting 2: Rotation speed filter 3: Minimum rotation speed display

1. Select setting mode 6.

 $Press \boxed{\textbf{FNC}} \rightarrow \boxed{\hspace{1.5cm}} \qquad \qquad \boxed{\hspace{1.5cm}} \qquad \qquad \text{five times}.$

2. Set "UTM/UTF setting value read."

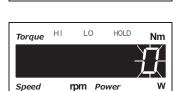
Press $\begin{bmatrix} \text{RECALL} \end{bmatrix}$ twice. \Rightarrow " UTM/UTF setting value read" is displayed.

Press , and present set value blinks.

Input the setting value with RECALI

Press to validate it. (Initial value: 0)

3. Press [ESC] twice to go back to the Indicated value display.



rpm Power

Speed

F 5.2



E.g. To read filter setting, enter 1 & validate. After reading setting from UTM/UTF, Mode F6.2 of TM320 will return to 0. (Initial value)

If restart power, Mode F6.3 - F6.5 will display 0. (Not value from UTM/UTF) Please note that setting read from UTM/UTF will not be kept.

■Write filter setting to UTM/UTF

Write the following filter setting to UTM/UTF.

In addition, after reading filter setting from UTM/UTF, the setting value from UTM/UTF will be shown at this item no.

* Only applicable when "0: RS-485 command mode" "1: RS-485 display mode" is selected in communication mode.

《Setting value》

0: 1 1: 3 2: 10 3: 30 4: 100 5: 300 6: 1k 7: PASS [Hz]

1. Select setting mode 6.

Press $[FNC] \rightarrow [\blacktriangleright]$ five times.

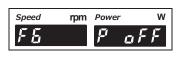
2. Set "UTM/UTF filter setting."

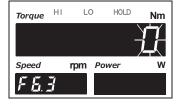
Press $_{\text{RECALL}}$ three times. \Rightarrow "UTM/UTF filter setting" is displayed.

Press , and present set value blinks.

Input the setting value with RECALL

Press to validate it. (Initial value: 0)





■Write rotation speed filter to UTM/UTF

Write the following rotation speed filter to UTM/UTF.

In addition, after reading rotation speed filter from UTM/UTF, the setting value from UTM/UTF will be shown at this item no.

* Only applicable when "0: RS-485 command mode" "1: RS-485 display mode" is selected in communication mode.

《Setting value》

0: OFF 1: 2 2: 4 3: 8 4: 16 5: 32 [times]

1. Select setting mode 6.





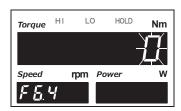
2. Set "UTM/UTF rotation speed filter."

Press $_{\text{RECALL}}$ four times. \Rightarrow "UTM/UTF rotation speed filter" is displayed.

Press , and present set value blinks.

Input the setting value with





3. Press ESC twice to go back to the Indicated value display.

■Write minimum rotation speed display to UTM/UTF

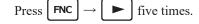
Write the following minimum rotation speed display to UTM/UTF.

In addition, after reading minimum rotation speed display from UTM/UTF, the setting value from UTM/UTF will be shown at this item no.

* Only applicable when "0: RS-485 command mode" "1: RS-485 display mode" is selected in communication mode.

《Setting value》 00 to 99

1. Select setting mode 6.





2. Set "UTM/UTF minimum rotation speed display."

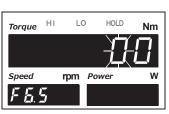
Press $\[\mathbb{R} \]$ five times. \Rightarrow "UTM/UTF minimum rotation speed display" is displayed.

Press , and the highest digit blinks.

Input the setting value with RECALL.

Move to the lower digits with . (Initial value: 00)

Press U to validate it.



■UTM/UTF assigned action

UTM/UTF will execute assigned action.

* Only applicable when "0: RS-485 command mode" "1: RS-485 display mode" is selected in communication mode.

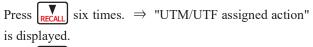
《Setting value》

- 0: Cancel 1: Digital zero 2: Digital zero reset
- 1. Select setting mode 6.

Press $\boxed{\mathsf{FNC}} \rightarrow \boxed{\blacktriangleright}$ five times.



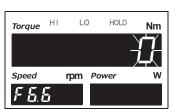
2. Set "UTM/UTF assigned action."



Press, and present set value blinks.

Input the setting value with RECALL.

Press to validate it. (Initial value: 0)



3. Press ESC twice to go back to the Indicated value display.

■RS-485 dedicated rated capacity value

Set rated capacity value for RS-485 display mode.

Since the torque value obtained from RS-485 is %FS, it is necessary to set rated capacity value.

* Decimal point is linked to Calibration Function Select 1 (Torque). (Mode 4)

《Setting value》

0 to 99999

1. Select setting mode 6.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ five times.



Nm

Torque

2. Set "RS-485 dedicated rated capacity value."

Press || seven times. \Rightarrow "RS-485 dedicated rated capacity value" is displayed.

Press, and the highest digit blinks.

Input the setting value with

Move to the lower digits with . (Initial value: 10000)

Press to validate it.





Chapter

■RS-485 terminator

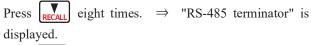
Set termination resistor on receiving side of RS-485 at TM320.

《Setting value》 0: OFF 1: ON

1. Select setting mode 6.



2. Set "RS-485 terminator."



Press , and present set value blinks.

Input the setting value with

Press to validate it. (Initial value: 1)



rpm Power

Speed

F 5.8

rpm Power

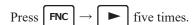
3. Press ESC twice to go back to the Indicated value display.

■RS-422 terminator

Set termination resistor on receiving side of RS-422 at TM320.

《Setting value》 0: OFF 1: ON

1. Select setting mode 6.



2. Set "RS-422 terminator."

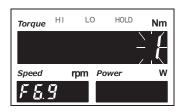
Press \mathbb{R}^{\bullet} nine times. \Rightarrow "RS-422 terminator" is displayed.

Press , and present set value blinks.

Input the setting value with

Press to validate it. (Initial value: 1)





■ About RS-485 command mode & RS-485 display mode

With "0: RS-485 command mode" "1: RS-485 display mode as communication mode, you can easily execute assigned action, read & write setting values or indicated value display from UTM/UTF.

RS-485 command mode

- Read/write setting values
- Assigned action

RS-485 display mode

- Read/write setting values
- Assigned action
- Digital data display of torque value or rotation speed

Read/write of setting values & assigned action will be executed according to setting mode 6, item no. 2 to 6.

Digital data display of torque value or rotation speed are data from RS-485. They can be seen on main & sub display of TM320.

* Digital data of RS-485 display mode is displayable if: communication status is confirmed after turning ON UTM/UTF & communication check.

Communication confirmation time depends on condition of UTM/UTF.

If indicated display value does not change after 5 seconds, check the condition of UTM/UTF.

Acquired data will be displayed in reference with setting of RS-485 dedicated rated capacity value. Rotation speed is displayed from acquired data.

Power is calculated from torque value and rotation speed obtained above.



Point

Acquirable data from RS-485 is 300 times/sec..

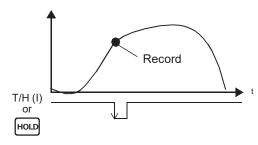
Perform comparison / hold with acquired data.

However, the following functions are not reflected.

- Digital zero and digital zero reset (keys input, external signal, option)
- Zero tracking
- Filter settings (digital filter (torque and rotation speed), digital low-pass filter)
- Deadband
- Absolute value display
- Min. scale division (torque and rotation speed)
- Digital offset
- Pulse rate (rotation speed)
- Rotation stop settings

9-1. Record timing

Each value (torque, rotation speed, and power) is recorded according to a print command. Up to 30 pieces of the most recent data can be stored. If 30 pieces are exceeded, the oldest data in chronological order will be overwritten. Select hold value (when hold is reset) or stable value (at stable-time out of near zero) of the SI/F print setting. (For details, see "SI/F print" on page 61.) Even without using hold, data can be immediately recorded by setting SI/F print to hold value and by pressing HOLD or turning T/H ON.



In addition, when using hold with SI/F print at hold value, the value is recorded at the time of release.

<Indicated value display>

9-2. History

Recorded data can be checked on the indicated value display screen in history mode.

- 1. Enter the history mode with recall from the indicated value display.
- 2. The most recent data are displayed.

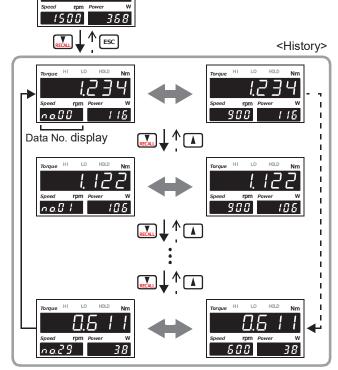
Rotation speed and data No. are displayed alternately.
No. 00 corresponds to the

Data can be checked with

most recent data.

and

No. 29 (30 pieces old) corresponds to the oldest data.





Point

- Even while the history is displayed, when the record is updated, the record data are updated. In that case, the displayed data No. does not change but the record data alone change.
- The record data are saved in F-RAM.

9-3. Record data clear

All 30 pieces of data are cleared to zero. However, they cannot be cleared if work protect is ON.

■Clear by means of keys

1. Select setting mode 9.

Press $\lceil FNC \rceil \rightarrow \lceil \blacktriangleright \rceil$ six times.

2. Execute "Record data clear."

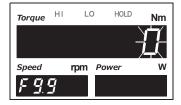
Press $\frac{1}{RECALL}$ five times \Rightarrow "Record data clear" is displayed.

Press , and blinks.

Input a value other than zero with



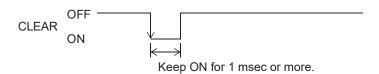




- * Upon validation, they are cleared and the set values go back to 0.
- **3.** Press ESC twice to go back to the indicated value display.

■Clear by means of the external signal "CLEAR input"

The record data are cleared at the instant when the external input/output connectors CLEAR and COM2 are short-circuited from an open state (at the ON edge).



■Clear by means of communication (232/USB option)

The record data are cleared when a record data clear command is received in communication (232/USB option).



Point

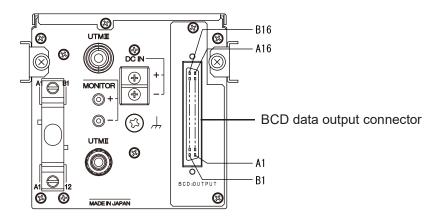
If you enter the history mode after clearing, all data show zero.

10 OPTION INTERFACE

10-1. BCD interface

The BCD data output is an interface to extract the indicated value of the TM320 as BCD data. This interface is convenient to process controls, totals, records, etc., by connecting the TM320 to a computer, process controller, sequencer or the like.

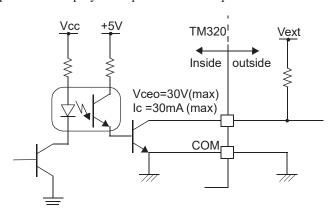
The I/O and internal circuits are electrically insulated by photocoupler.



■Connection

Output

The signal output circuit employs the open collector output.



Internal transistor status

Output data	Negative	Positive
0	OFF	ON
1	ON	OFF
		Throu

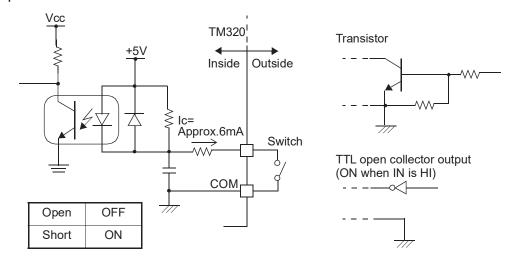
Output pin level

Output data	Negative	Positive
0	Н	L
1	L	Н

—Through logic switching (pin B14)

Chapter 10

Input



CAUTION

- Do not apply external voltage to the signal input circuit.
- The external element is required to withstand Ic=10mA.
- Leakage from the external element is required to be 30µA or below.

■Connector pin assignment

A1	*	COM	B1	*	COM
A2	OUT	1	B2	OUT	1000
A3	OUT	2	В3	OUT	2000
A4	OUT	4	B4	OUT	4000
A5	OUT	8	B5	OUT	8000
A6	OUT	10	B6	OUT	10000
A7	OUT	20	B7	OUT	20000
A8	OUT	40	B8	OUT	40000
A9	OUT	80	B9	OUT	80000
A10	OUT	100	B10	OUT	Minus (polarity)
A11	OUT	200	B11	OUT	OVER
A12	OUT	400	B12	OUT	STAB
A13	OUT	800	B13	OUT	STROBE
A14	IN	Data hold	B14	IN	Logic switching
A15	IN	Data switching 0	B15	IN	Data switching 1
A16	_		B16	_	

Compatible connector: Connector cover:

FCN-361J032-AU (manufactured by FUJITSU COMPONENT or equivalent) FCN-360C032-B (manufactured by FUJITSU COMPONENT or equivalent)

(connector & cover optional type: CN51)

■Output data select

《Setting value》

0: Torque (hold synchronized)

Torque synchronized with a hold is output.

1: Rotation speed The rotation speed is output.

2: Power is output.

3: Torque (hold not synchronized)

Torque in real time is output.

4: External select Data selected by the data select input (A15, B15) is output.

Data select 1	Data select 0	Output data
OFF	OFF	Torque (hold synchronized)
OFF	ON	Rotation speed
ON	OFF	Power
ON	ON	Torque (hold not synchronized)

^{*} In the case of external selection, read after at least 2 cycles.

Output data select setting method

1. Select setting mode 5.

Press $\boxed{\mathsf{FNC}} \rightarrow \boxed{\blacktriangleright}$ four times.

2. Set "Output data select."

Press RECALL once. ⇒ "Output data select" is displayed.

Press once, and present set value blinks.

Input the setting value with

(Initial value: 0)

Press to validate it.



■Signal timing

• Minus Turns on when the output indicated value data is negative.

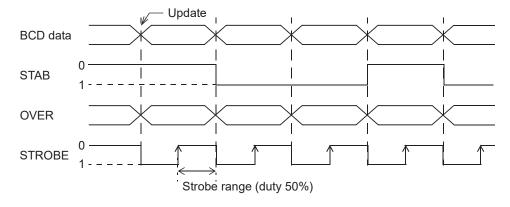
• OVER Turns on at over-scale time.

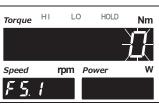
-LOAD, +LOAD, OFL1, OFL2

■ STAB Turns on at stable-time. See "5-6.Motion detect" on page 39.

● STROBE Strobe pulses are output in synchronization with BCD data.

For reading the data, use the rising edges of the pulses when the logic is negative, and the falling edges of the pulses when the logic is positive.





■ Logic switching

Select the logic of the BCD data output signal. Make selection with B14.

When COM and B14 are open:

When COM and B14 are short-circuited:

Positive logic

Read at least 2 cycles after inputting the logic switching.

■BCD data hold

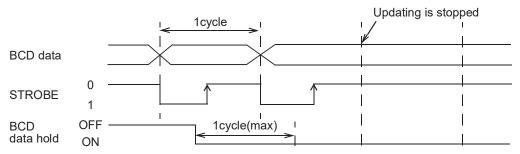
Updating of the BCD data output signal is stopped. Also, the STROBE output turns OFF. Make selection with A14.

When COM and A14 are open:

Update stop canceled

When COM and A14 are short-circuited:

Update stopped



Read at least 2 cycles after inputting the BCD data hold.

As long as the BCD data hold is input, data can be read reliably, but because the data is not updated, it may be different from original data.

■Output rate

《Setting value》

0: 10 1: 25 2: 50 3: 100 4: 250 5: 500 6: 1000 [times/sec.]



Even if this setting is changed, A/D conversions speed does not change.

Make the output rate slower when reading fails due to a low processing performance of the device that should receive BCD.

P

rpm Power

a F

Nm

F 5

Torque

Speed

F 5.2

♦Output rate setting method

1. Select setting mode 5.



2. Set "Output rate."

Press twice. ⇒ "Output rate" is displayed.

Press, and present set value blinks.

Input the setting value with RECALL.

(Initial value: 3)

Press to validate it.



10 <u></u>

■BCD/binary select

The output data selection can be changed to binary.

《Setting value》
0: BCD 1: Binary

♦BCD/binary setting method

1. Select setting mode 5.

Press FNC four times.

2. Select "BCD/binary select."

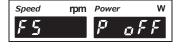
Press $\frac{1}{RECALL}$ three times. \Rightarrow "BCD/binary select" is displayed.

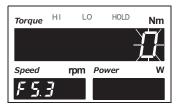
Press , and present set value blinks.

Input the setting value with \[\bigstyle \]

(Initial value: 0)

Press 🕶 to validate it.





3. Press ESC twice to go back to the indicated value display.

■Pin assignment at binary

A1	*	COM	B1	*	COM
A2	OUT	2 ⁰	B2	OUT	2 ¹²
А3	OUT	2 ¹	В3	OUT	2 ¹³
A4	OUT	2 ²	B4	OUT	2 ¹⁴
A5	OUT	2 ³	B5	OUT	2 ¹⁵
A6	OUT	2 ⁴	B6	OUT	2 ¹⁶
A7	OUT	2 ⁵	B7	OUT	
A8	OUT	2 ⁶	В8	OUT	Data switching 0 (response)
A9	OUT	2 ⁷	В9	OUT	Data switching 1 (response)
A10	OUT	2 ⁸	B10	OUT	Minus (polarity)
A11	OUT	2 ⁹	B11	OUT	OVER
A12	OUT	2 ¹⁰	B12	OUT	STAB
A13	OUT	2 ¹¹	B13	OUT	STROBE
A14	IN	Data hold	B14	IN	Logic switching
A15	IN	Data switching 0	B15	IN	Data switching1
A16	_		B16	_	

^{*} With the B8 and B9 outputs, the data specified by the output data selection or by A15 and B15 (data select) can be checked.

10

10-2. RS-232C interface

The RS-232C is an interface to read the indicated value and status of the TM320 and to write parameters into the TM320.

This interface is convenient to process controls, totals, records, etc., by connecting the TM320 to a computer, process controller, sequencer or the like.

■ Communication specifications

Signal level: Based on RS-232C

Transmitting distance: Approx.15m

Transmitting method: Asynchronous, Full duplex

Baud rate: 9600, 19200, 38400, 57600bps selectable

Bit configuration: Start bit: 1bit

> Character length: 7 or 8 bit selectable Stop bit: 1 or 2 bit selectable

Parity none, odd or even selectable Parity:

Delimiter: CR, CR+LFSelectable

Code: **ASCII**

■Connector pin assignment

1	_	
2	IN	RXD
3	OUT	TXD
4	OUT	DTR
5	*	GND
6	_	
7	_	
8	_	
9	_	
Case	*	SHIELD

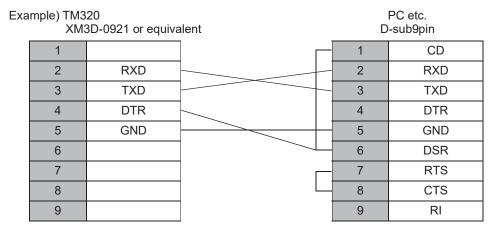
Adaptable connector 9-pin D-SUB connector

> Connector: XM3D-0921 (Omron) or equivalent

Cover: XM2S-0913 (with inch screw thread #4-40)(Omron) or equivalent

(connector & cover optional type: CN34)

■ Connection



This connection diagram shows cabling applicable to the case where your PC is DTE (data terminal equipment). For connection with DCE (data circuit-terminating equipment), such as a modem, use straight type cabling.

Prepare cabling after reconfirmation of the connector shape and signal lines (pin assignments) of the equipment you use.

■Communication mode

《Setting value》

0: Send/receive mode

This mode performs communication by a command from the host computer. In this mode, you can read out the indicated value, status, set values and write in set values.

1: Continuous transmission (hold synchronized) mode

This mode continuously transmits the indicated values and the status. Indicated value and status are synchronized with hold.

2: Printed transmission mode

When the indicated value is printed (a print command is output to the SI/F), the indicated value and status are sent from the TM320 to host.

3: Continuous transmission (hold not synchronized) mode

This mode continuously transmits the indicated values and the status. Only indicated value is not synchronized with hold.

Chaptei 10

77

♦ Communication mode setting method

1. Select setting mode 5.

 $Press \left[FNC \right] \rightarrow \left[\blacktriangleright \right]$ four times.

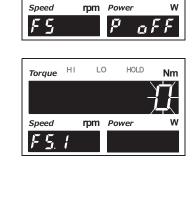
2. Set "Communication mode."

Press \bigcirc once. \Rightarrow "Communication mode" is displayed.

Press, and present set value blinks. Input the setting value with

(Initial value: 0)

Press to validate it.



3. Press ESC twice to go back to the indicated value display.

■ Communication conditions

Set the communication conditions according to the host.

♦ Communication conditions setting method

1. Select setting mode 5.

2. Set "Communication conditions."

Press $\fbox{\textbf{RECALL}}$ twice. \Rightarrow "Communication conditions" is displayed.

Press , and present set value blinks.

Input the setting value with

(Initial value: 11100)

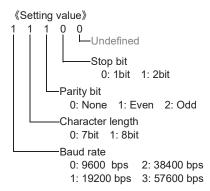
Move to the lower digits with

Press to validate it.

3. Press ESC twice to go back to the indicated value display.







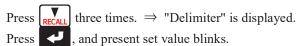
Chaptei 10 《Setting value》
0: CR 1: CR+LF

♦ Delimiter setting method

1. Select setting mode 5.



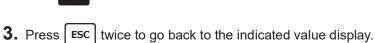
2. Set "Delimiter."



Input the setting value with
RECA

(Initial value: 0)

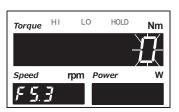
Press to validate it.



■Communication format

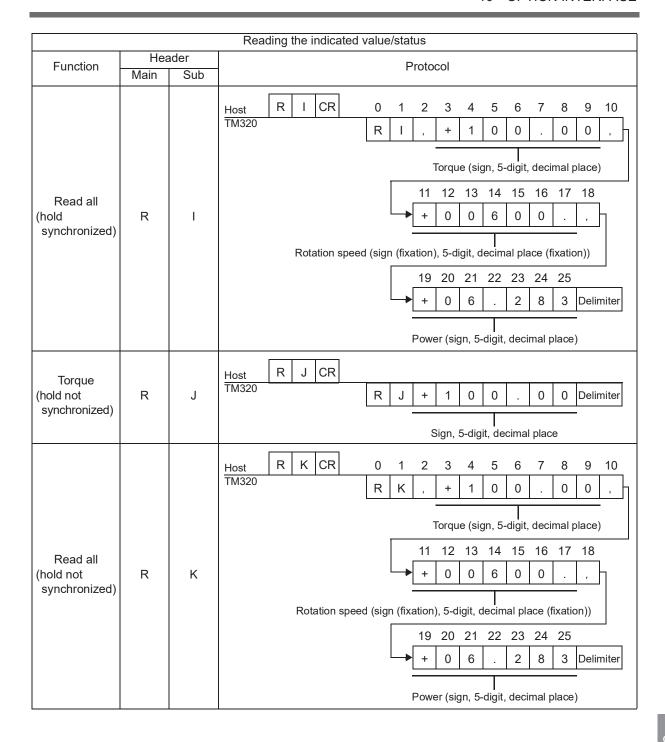
1.Send/receive [reading the indicated value/status]

	Reading the indicated value/status				
Function	Hea	ader	Protocol		
1 dilotion	Main	Sub	1 1010001		
Torque (Hold synchronized)	R	А	Host R A CR TM320 R A + 1 0 0 . 0 Delimiter Sign, 5-digit, decimal place		
Rotation speed	R	В	Host R B CR TM320 R B + 0 0 6 0 0 . Delimiter Sign (fixation), 5-digit, decimal place (fixation)		
Power	R	С	Host R C CR TM320 R C + 0 6 . 2 8 3 Delimiter Sign, 5-digit, decimal place		



10

			Reading the indicated value/status
Function	Hea Main	der Sub	Protocol
Status1 (torque)	R	D	Host R D CR TM320 R D 0 0 0 0 0 0 0 Delimiter Hold 0: OFF 1: ON Stable 0: OFF 1: ON Near zero 0: OFF 1: ON HI (torque) 0: OFF 1: ON OK (torque) 0: OFF 1: ON LO (torque) 0: OFF 1: ON Undefined 0
Status2 (torque)	R	Е	Host R E CR TM320 R E O O O O O O O Delimiter ALM HI (torque) 0: OFF 1: ON ALM LO (torque) 0: OFF 1: ON Undefined Undefined Undefined Undefined Undefined Undefined Undefined O Undefined Undefined O Undefined
Status3 (torque)	R	F	Host R F CR TM320 R F CR R F 0 0 0 0 0 0 0 0 Delimiter -LOAD 0: OFF 1: ON -LOAD 0: OFF 1: ON OFL1 0: OFF 1: ON OFL2 0: OFF 1: ON Undefined 0 Torque unit Unit number
Status4 (rotation speed/ power)	R	G	Host R G CR TM320 R G O O O O O O O Delimiter Undefined OFL2 (rotation speed) 0: OFF 1: ON OFL1 (power) 0: OFF 1: ON Undefined 0 Undef
Status5 (rotation speed)	R	н	Host R H CR TM320 R H 0 0 0 0 0 0 0 Delimiter ALM HI (rotation speed) 0: OFF 1: ON ALM LO (rotation speed) 0: OFF 1: ON HI (rotation speed) 0: OFF 1: ON OK (rotation speed) 0: OFF 1: ON LO (rotation speed) 0: OFF 1: ON Undefined Undefined 0

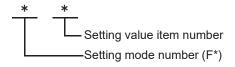


Chapter 10

2. Send/receive [setting value writing/reading]

	Setting value writing					
Function	Hea	der	Protocol			
Tanodon	Main Sub		1 1010001			
		W _	Host W CR TM320 Command Setting value (sign, 5-digit, no decimal place) (For a setting value with a decimal place, simply write the numerical value excluding the decimal place.)			
Various settings	W		* When the number of digits of the setting value is smaller than five, put a zero in the higher digit(s). Example) 3 digits			
			W * * + 0 0 1 2 3 CR			
			* When the setting value is unsigned, put a zero in the sign digit.			
			W * * 0 0 0 0 0 3 CR			
			Setting value reading			
Function	Hea	der	Protocol			
Tanodon	Main	Sub	1 1010001			
Various settings	W	_	Host W CR TM320 W Delimiter Command Setting value			
			(sign, 5-digit, no decimal place) (A setting value with a decimal place results in the numerical value excluding the decimal place.)			

* Command definition



- * The mode number of the setting value of HI/LO limit is "0."
- * For setting mode numbers and setting item numbers, see "12-1. The list of initial setting value" on page 108.

- "Initialize" and "password" cannot be either read or written.
- When the protect of the setting value you are going to write is ON, it cannot be written. Turn OFF the protect.
- If an output value is written in command 42 (zero calibration), simulated zero calibration is executed with the written value. Also, if an output value is written in command 43 (equivalent input calibration), equivalent input calibration is executed.

TERFACE

3. Send/receive [operation command]

	Movement directive				
Function	Header		Protocol		
Function	Main	Sub	FIGUCOI		
Zero calibration	С	Z	Host C Z CR TM320		
Equivalent input calibration	С	S	Host C S CR TM320 * Set the rated capacity value before sending an actual load calibration command.		
Digital zero	С	G	Host C G CR TM320		
Digital zero reset	С	Н	Host C H CR TM320		
Record data clear	С	J	Host C J CR TM320		
SECTION ON	С	1	Host C 1 CR TM320		
SECTION OFF	С	2	Host C 2 CR TM320		
T/H ON	С	3	Host C 3 CR TM320		
T/H OFF	С	4	Host C 4 CR TM320		



Point

If the calibration protect is ON, zero calibration and span calibration cannot be performed.

4. Send/receive [returning an error]

	Returning an error					
Function	Header		Protocol			
Function	Main	Sub	Piolocoi			
Error occurrence (send/receive mode)	Е	R	Host Command E R * Delimiter 1: The command or message length is improper. 2: The protect of the setting value you are going to write is ON, or a calibration command is received while the calibration protect is ON. 3: The format errors of the setting value which tried to write in. 4: Other communication errors (parity error, frame error, etc.)			

■Continuousness / printed transmission mode

			Continuousness / printed transmission
Function		der	Protocol
	Main	Sub	1.1.1.1
Indicated value & Status	G	S	0 1 2 3 4 5 6 7 8 9 10 11 12 TM320

10

About the timing for continuous transmission

According to the communication baud rate setting, the continuous transmission intervals in the case where the communication modes "Continuous" is selected are as follows:

Communication baud rate	Continuous transmission interval	
57600 bps	100 times/sec.	
38400 bps	50 times/sec.	
19200 bps	25 times/sec.	
9600 bps	12 times/sec.	

10-3. D/A converter voltage output (3ch)

This converter is used for obtaining analog outputs synchronized with torque, rotation speed and power.

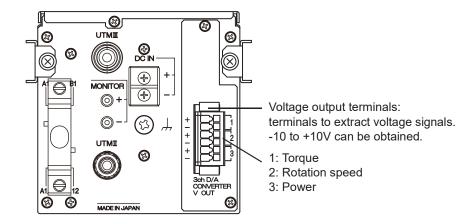
The analog output ranges are -10 to +10V output.

By using the D/A zero setting and D/A full scale setting functions, analog output can be obtained between zero (0V) and full scale (+10V) with respect to the predetermined digital value.

The output circuit and the main unit circuit are isolated.

The resolution is 1/10000 with respect to the ranges of -10 to +10V, and the conversion speed is 8000 times per second.

The maximum voltage output range are about ± 11 V.



■Connector pin assignment

1 Torque	+	VOUT
	_	GND
2 Rotation speed	+	VOUT
	_	GND
3 Power	+	VOUT
	ı	GND

Compatible plug 734-106/037-000

Operating tool 734-230

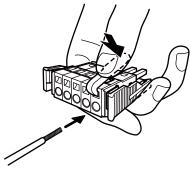
Connection

A two-piece terminal block is used. Perform wiring with the plug pulled out from the option. Use of the operating tool included is recommended to facilitate wiring.

1. Strip the casing 6.5 to 7.5mm on the cable to be

Twist the bare wire to fit the terminal hole.

- 2. Press the operating tool attached to the operation slot at the upper part with a finger and push down the spring.
- 3. While pressing the operating tool, insert the electric wire into the insertion opening until it hits the wall.



6.5 to 7.5mm

4. The wire will be connected once the operating tool is released. For confirmation, tug the electric wire gently.

The wire can be connected likewise without the operating tool by using a tool such as a flathead screwdriver to press down the spring from the top.

- Cable can be from 28 to 14AWG (0.08 to 1.5mm²).
- It is not necessary to solder the cable wires or to fix a solderless terminal.
- If several cables to be inserted to the same hole, twist those cable wires together and insert.
- Connect the cable with the power supply of the main body turned off without fail.
- For the protection from the damage, do not operate the lever without removing the plug.

Output mode

《Setting value》

0: Data select The output of each channel corresponds to the data select setting.

1: Zero scale fix All outputs of the channels are fixed to zero scale output (0V).

After confirmation, it will enter the output adjustment mode and zero

adjustment for each channel will be enabled.

2: Full scale fix All outputs of the channels are fixed to full scale output (+10V).

After confirmation, it will enter the output adjustment mode and gain

adjustment for each channel will be enabled.

Chapter 10

Chaptei

■ Data select

When the output mode is "0: Data select", the analog output for torque, rotation speed and power will be synchronized with the indicated value.

The output data for each indicated value can be selected.

《Setting value》

0: Hold synchronized Outputs value synchronized with the indicated value.

1: Hold not synchronized Outputs value without hold even when the indicated value is on hold.

♦ Output mode/ data select setting method

1. Select setting mode 5.

Press $\boxed{\mathbf{FNC}} \rightarrow \boxed{}$ four times.

2. Set "Output data select."

Press \bigcirc "Output data select" is displayed.

Press , and the highest digit blinks.

- ① Set "Output mode."

 Input the output mode with RECALL and move to the lower digit with .

 (Initial value: 0)
- ② Set "Data select 3 (power)."

 Input the data select 3 (power) with
 and move to the lower digit with
 (Initial value: 0)
- ③ Set "Data select 2 (rotation speed)."

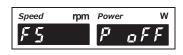
 Input the data select 2 (rotation speed) with

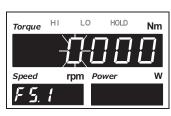
 RECALL, and move to the lower digit
 with

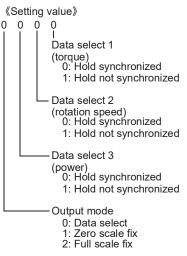
 (Initial value: 0)
- ④ Set "Data select 1 (torque)."

 Input the data select 1 (torque) with RECALL. (Initial value: 0)

 Press to validate it.
- **3.** Press ESC twice to go back to the indicated value display.







■Zero/Full scale setting

Zero scale 1 to 3 Set the indicated value to output 0V.

Full scale 1 to 3 Set the indicated value to output 10V.

The gain will be "full scale - zero scale".

Outputs value within the range of $\pm gain$ with the set zero scale at the

center.

《Setting value》

Zero/Full scale value -99999 to 99999

1. Select setting mode 5.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ four times.



Nm

Torque

- **2.** Set "Zero scale value 1 (torque)," and "Full scale value 1 (torque)."
 - ① Set "Zero scale value 1 (torque)."

Press $\frac{1}{\text{RECALL}}$ twice. \Rightarrow "Zero scale value 1 (torque)" is displayed.

Press , and the highest digit blinks.

Input the setting value with RECALL, and move to the lower digit with Initial value: 0)

* For inputting a negative sign, press +/-

Press to validate it.

② Set "Full scale value 1 (torque)."

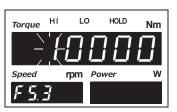
Press $\begin{array}{c} \text{RECALL} \end{array}$ once. \Rightarrow "Full scale value 1 (torque)" is displayed.

Press , and the highest digit blinks.

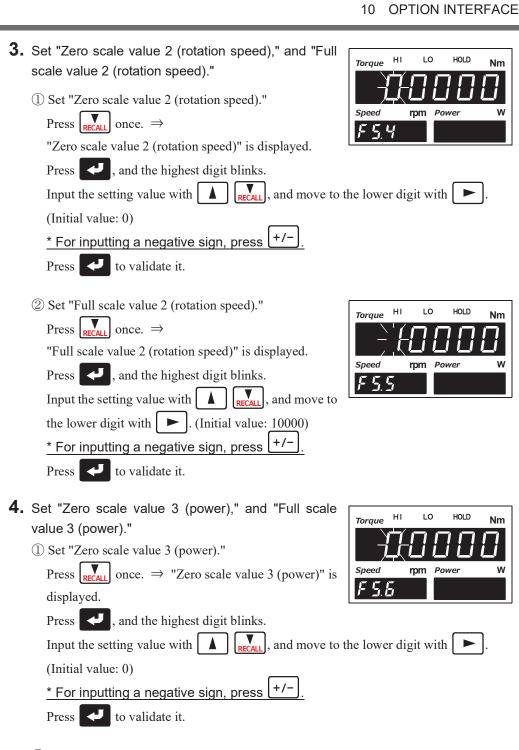
Input the setting value with , and move to the lower digit with . (Initial value: 10000)

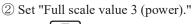
* For inputting a negative sign, press +/-.

Press to validate it.



Chaptei





Press $\left| \begin{array}{c} \mathbf{v} \\ \mathbf{r} \end{array} \right|$ once. \Rightarrow "Full scale value 3 (power)" is displayed.

Press , and the highest digit blinks.

 \blacktriangle $||_{RECALL}|$, and move to Input the setting value with the lower digit with \ \rightarrow \ | . (Initial value: 10000)

* For inputting a negative sign, press L+/-

Press to validate it.

5. Press | ESC | twice to go back to the indicated value display.

LO

н Torque

Speed

F 5.

HOLD

Nm

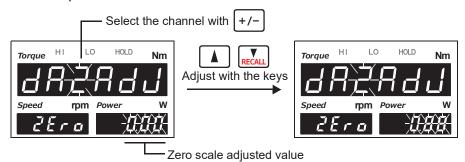
Chaptei 10

■Adjustment by fixed output

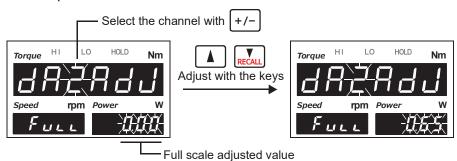
Make output adjustment on the adjustment screen appearing after selecting each fixed output by D/A output data select setting and pressing

Select the adjusting output channel with |+/-|, and make fine adjustment of the output with while monitoring the output value.

The adjustment values (%) is registered by pressing and confirming adjustment after completing adjustments for all channels to be adjusted.



♦Full fixed output



- results in continuous operation. * Keeping on pressing
- * The adjustable range is approximately ± 2.0 V.
- * Press | **ZERO** | to bring the adjusted value back to the central point (0%).
- * Press | **ESC** to stop adjustment and go back to the indicated value display screen.
- * By initializing the system settings, the adjusted value is cleared to go back to 0%.

ION INTERFACE

10

10-4. D/A converter output

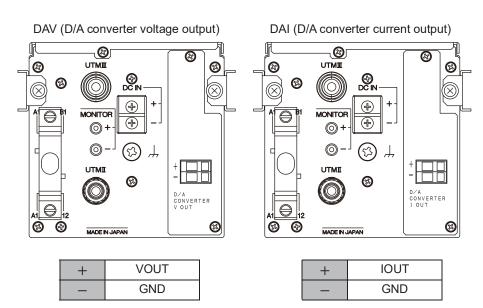
A D/A converter is provided for obtaining analog output synchronized with the indicated value of the TM320. The analog output ranges are -10 to +10V output and 4 to 20mA constant-current output.

By using the D/A zero setting and D/A full scale setting functions, analog output can be obtained between zero (0V, 4mA) and full scale (10V, 20mA) with respect to the predetermined digital value. The output circuit and the main unit circuit are isolated.

The resolution is 1/10000 with respect to the ranges of -10 to +10V and of 4 to 20mA, and the conversion speed is 8000 times per second.

The maximum voltage output range are about ± 11 V, the maximum current output range are about 2.4 to 21.6 mA.

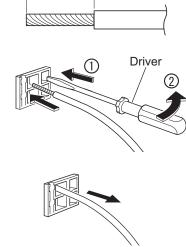
■ Connection



For the output terminals of the D/A converter option, a cage clamp type terminal block is used. Make connections by the following procedure.

Connecting to cage clamp terminal block

- **1.** Strip the casing 0.2in (6mm) on the cable to be connected.
 - Twist the bare wire to fit the terminal hole.
- **2.** Insert the supplied screwdriver into the right hole and lift right.
- **3.** Insert the twisted wires into the left hole.
- **4.** Pull the screwdriver out from the upper hole.
- **5.** Make sure cable is clamped securely and does not come out with a slight tug.



5 to 6mm

CAUTION

- Cable can be from 24 to 14AWG (0.2 to 2.5mm²).
- It is not necessary to solder the cable wires or to fix a solderless terminal.
- If several cables to be inserted to the same hole, twist those cable wires together and insert.
- Connect the cable with the power supply of the main body turned off without fail.

■Output data select

《Setting value》

0: Torque (hold synchronized)

Torque synchronized with a hold is output.

1: Rotation speed The rotation speed is output.

2: Power The power is output.

3: Torque (hold not synchronized)

Torque in real time is output.

4: Zero fix Output is fixed at the zero output (0V for voltage output, 4mA for

current output). After fixing, you will go to the output adjustment

mode, so that zero adjustment can be made.

See "Adjustment by fixed output" on page 94.

Output is fixed at the full scale (10V for voltage output, 20mA for 5: Full scale fix

current output). After fixing, you will go to the output adjustment

mode, so that gain adjustment can be made.

See "■Adjustment by fixed output" on page 94.

Output data select setting method

1. Select setting mode 5.

 P_{ress} | FNC | \rightarrow | lack four times.

2. Set "Output data select."

Press $||\mathbf{RECALL}||$ once. \Rightarrow "Output data select" is displayed.

, and the highest digit blinks.

three times to make the digit of the output

data select blink. (Initial value: 0)

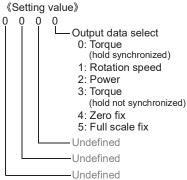
Input the setting value with

Press to validate it.

3. Press | ESC | twice to go back to the indicated value display.







Chaptei 10

■Zero/Full scale setting

Zero scale Set the indicated value to output 0V for voltage output, and 4mA for current

output.

Full scale Set the indicated value to output 10V for voltage output, and 20mA for current

output.

《Setting value》

Zero/Full scale value -99999 to 99999

1. Select setting mode 5.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ four times.



rpm Power

Torque

Speed

F 5.2

HOLD

Nm

2. Set "Zero scale value," and "Full scale value."

① Set "Zero scale value."

Press $\frac{1}{\text{RECALL}}$ twice. \Rightarrow "Zero scale value" is displayed.

Press , and the highest digit blinks.

Input the setting value with , and move to the lower digit with (Initial value: 0)

* For inputting a negative sign, press +/-

Press **U** to validate it.

② Set "Full scale value."

Press \nearrow once. \Rightarrow "Full scale value" is displayed.

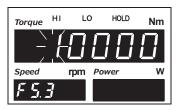
Press , and the highest digit blinks.

Input the setting value with _____, and move to

the lower digit with . (Initial value: 10000)

* For inputting a negative sign, press +/-

Press to validate it.



3. Press ESC twice to go back to the indicated value display.

Chapter 10

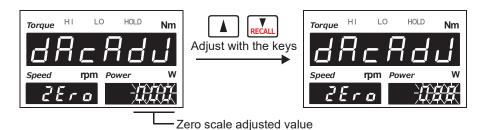
93

Chaptei 10

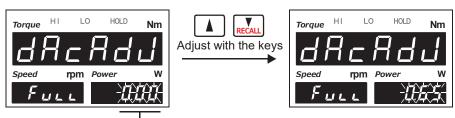
■Adjustment by fixed output

Make output adjustment on the adjustment screen appearing after selecting each fixed output by D/A output data select setting and pressing

While monitoring the output value, make fine adjustment of the output with to validate it, so that the adjusted value (%) is registered.



♦Full fixed output



Full scale adjusted value

- RECALL results in continuous operation. * Keeping on pressing
- * The adjustable range of voltage output is approximately ±2.0V, and that of current output is approximately ± 1.6 mA.
- * Press | **ZERO** | to bring the adjusted value back to the central point (0%).
- * Press | ESC | to stop adjustment and go back to the indicated value display screen.
- * By initializing the system settings, the adjusted value is cleared to go back to 0%.

FERFACE

10

10-5. USB interface

The USB is an interface to read the indicated value of the TM320 and to write parameters into the TM320. This interface is convenient to process controls, totals, records, etc., by connecting the TM320 to PC. Moreover, set values can be read and written by specific PC software, and also input signal can be shown in wave form.

■ Communication specifications

Communication standard: Compliant with USB Ver.2.0, Full speed (12Mbps)

Class: Communication device class

Baud rate: 9600, 19200, 38400, 57600, 115.2k, 230.4k bps selectable

Bit configuration: Start bit: 1bit

Character length: 7 or 8 bit selectable Stop bit: 1 or 2 bit selectable

Parity: Parity none, odd or even selectable

Delimiter: CR, CR+LFSelectable

Code: ASCII

Connector: mini-B TYPE

■PC hardware requirement

OS: Windows7/10 Home Premium/Professional/Ultimate 32/64bit

Japanese edition

Display: 1024×768 pixels or more

USB port: One empty port (USB 2.0 or more)

USB driver: Virtual COM Port(VCP) Drivers by FTDI Ltd.

Memory: 2GB or more

Hard disk: 15GB free space or more

■Installation of a USB driver

Please install a USB driver for connecting with USB of the TM320.

Please see the homepage of FTDI for details and perform download and installation of the driver according to a procedure.

* If the PC is already connected to the network, the driver may be automatically installed via the network when the TM320 is connected to the PC.

Guide: http://www.ftdichip.com/Support/Documents/InstallGuides.htm

Driver: http://www.ftdichip.com/Drivers/VCP.htm

■Connection of USB

Connects a USB cable.

The USB connector of the TM320 is mini-B TYPE.

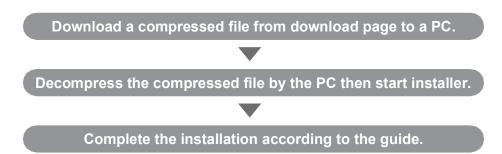
■The check of a virtual COM port

Please check the virtual COM port number which the TM320 is connected from the device manager of PC.

■Installation of the TM320 PC application software

When you use the TM320 PC application software, please download and install it from the Unipulse homepage.

* https://www.unipulse.tokyo/en/product/tm320/



■ The injection of a power supply

On the power supply of TM320. Please check that a display comes.

■ Starting of the TM320 PC application software

The TM320 PC application software will start by executing an EXE file. If there is no shortcut on the desktop, please run the EXE file from the destination folder.

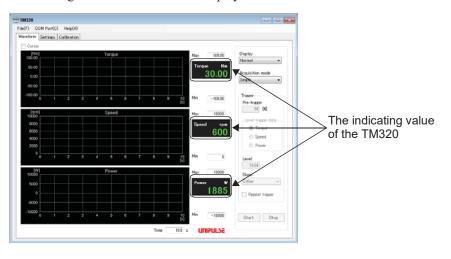
■ Specification of a COM port

Please specify virtual COM port that is confirmed on "COM port" in the window menu.



■The check of a indicating value

Check if indicating value on the TM320 is displayed.



Chapter 10

NTERFACE

■Communication mode

《Setting value》

0: Send/receive

This mode performs communication by a command from the host computer. In this mode, you can read out the indicated value, status, set values and write in set values.

- * Please be sure to use this setting in the case of use of the TM320 PC application software.
- 1: Continuous transmission (hold synchronized) mode

This mode continuously transmits the indicated values and the status. Indicated value and status are synchronized with hold.

2: Printed transmission mode

When the indicated value is printed (a print command is output to the SI/F), the indicated value and status are sent from the TM320 to host.

3: Continuous transmission (hold not synchronized) mode

This mode continuously transmits the indicated values and the status.

Only indicated value is not synchronized with hold.

♦ Communication mode setting method

1. Select setting mode 5.

2. Set "Communication mode."

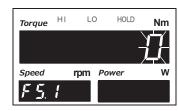
Press , and present set value blinks.

Input the setting value with RECALL

(Initial value: 0)

Press to validate it.





3. Press ESC twice to go back to the indicated value display.

Point

Please be sure to use the following setting in the case of use of the TM320 PC application software.

Communication mode: Send/receive Baud rate: 230.4k bps

Delimiter: CR

Character length, parity bit, and stop bit do not have specification.

The communication conditions can be united with PC application software.

■ Communication conditions

Set the communication conditions according to the host.

♦ Communication conditions setting method

1. Select setting mode 5.

 $Press \boxed{\textbf{FNC}} \rightarrow \boxed{\hspace{1cm}} \qquad \qquad \boxed{\hspace{1cm}} \qquad \qquad \boxed{\hspace{1cm}} \qquad \qquad four times.$

2. Set "Communication conditions."

Press \fbox{RECALL} twice. \Rightarrow "Communication conditions" is displayed.

Press , and present set value blinks.

Input the setting value with

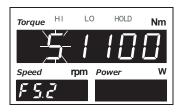
(Initial value: 51100)

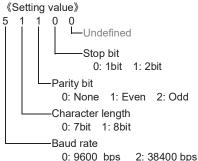
Move to the lower digits with

Press to validate it.

3. Press ESC twice to go back to the indicated value display.







1: 19200 bps 3: 57600 bps 4: 115.2k bps 5: 230.4k bps

■ Delimiter

Set the delimiter for sending messages from the TM320.

《Setting value》 0: CR 1: CR+LF

♦Delimiter setting method

1. Select setting mode 5.

 $Press | FNC | \rightarrow | Four times.$

2. Set "Delimiter."

Press three times. ⇒ "Delimiter" is displayed.

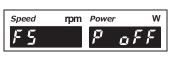
Press , and present set value blinks.

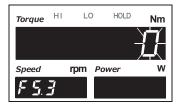
Input the setting value with

(Initial value: 0)

Press **t** o validate it.

3. Press ESC twice to go back to the indicated value display.





Chapter 10

■Communication format

The communication format is the same as an RS-232C interface (option).

For details, see " Communication format" on page 79.



About the timing for continuous transmission

Communication baud rate	Continuous transmission interval
230.4k bps	300 times/sec.
115.2k bps	150 times/sec.
57600 bps	100 times/sec.
38400 bps	50 times/sec.
19200 bps	25 times/sec.
9600 bps	12 times/sec.



11 SPECIFICATIONS

11-1. Specifications

■Analog section

Sensor input for torque (voltage input)

Input resistance $1 M\Omega$

Signal input range -10 to +10V (UTMIII/UTF(option))

-5 to +5V (UTM II/UTMV)

Non-linearity Within 0.02%/F.S.±1digit

Zero drift Within 0.2mV/°C RTI

Gain drift Within 0.01%/°C

Digital low-pass filter Selectable from 3 to 1k Hz and PASS.

Sampling speed 16000 times/sec.

A/D resolution 24bit (binary)

Approx. 1/30000 with respect to 10V

Voltage output Input voltage cuff (For test point)

Use terminal:

C-55-111A (manufactured by Miraial or an equivalent)

 ϕ 2, Depth: 6mm Compatible terminal:

C-55-155B (manufactured by Miraial or an equivalent)

Pulse input for rotation speed (open collector input) (UTM II /UTM V)

Maximum input rotation speed In accordance with the output frequency of

the UTM III/UTM II/UTMV

Minimum input rotation speed 15, 10, 5, 3, 2 rpm selectable * Pulse rate: 4 pulses

60, 40, 20, 12, 8 rpm selectable * Pulse rate: 1 pulse

Minimum detection pulse width 50μs

Circuit configuration No-voltage contact input (minus common)

Open collector connectable (Ic = Approx.10mA)

Pulse input for rotation speed (RS-422 compliant line driver input)

(UTF (option))

Maximum input rotation speed In accordance with the output frequency of the UTF

Circuit configuration RS-422 compliant line driver

Drive power supply for UTMIII/UTM II/UTMV

Power supply voltag DC24V * One UTMIII/UTMI /UTMV at the maximum

^{*} Please prepare power supply for UTF.

■ Display section

Display 7-segment LED, LED lamps

Main display: Character height 15mm, 6-digit,

indicated value: -99999 to 99999

Sub display: Character height 8mm, 5-digit,

indicated value: -19999 to 99999

(The highest digit of a negative value is -1)

Status display: HI, LO, HOLD: Red LED

Decimal place: 0, 0.0, 0.00, 0.000

(Only a torque and a power. Rotation speed is nothing)

Display item Display frequency: Selectable from 3, 6, 13, and 25 times/sec.

■ Setting section

Setting method Setting by inputting with membrane keys

Setting value NOVRAM (non-volatile RAM) or F-RAM (non-volatile RAM)

Record data F-RAM (non-volatile RAM)

■External input/output section

External input Dry contact input circuit (minus common type) for hold control, etc.

(Internal circuit power supply voltage: 12V)

External output Open collector output circuit (sink type) for comparison output, etc.

Rated voltage: 30V, driving current: 30mA or less

■Interface

SIF

2-wire serial interface for connecting a UNIPULSE-manufactured printer, external display, etc.

Transmitting method Asynchronous

Baud rate 600bps

Output data Torque (GROSS area), Rotation speed (NET area),

Power (TARE area)

RS-485 (Only for UTMⅢ/UTF)

Signal level Based on RS-485

Transmitting distance Approx. 1 km

Transmitting method Asynchronous, Full duplex

Transmitting speed 230.4kbps
Bit configuration Start bit: 1bit

Character length: 8bit

Stop bit: 1bit Parity: none Terminator: CR

Code ASCII



■ Options

* Only one of the following options can be selected.

BCD parallel data output (BCO)

Open collector output circuit (sink type)

Data format BCD or binary selectable

Output rate 10, 25, 50, 100, 250, 500, 1000 times/sec.

Rated voltage 30V

Driving current 30mA or less

Output data Selected by the setting of "Torque," "Rotation speed," or

Common for all channels

"Power," or externally.

D/A converter voltage output (3ch) (D3V)

Output range $\pm 10 V$

Load resistance $2k\Omega$ or more

D/A conversion speed 8000 times per second

Resolution 1/10000

Zero/span adjustment range $\pm 10\%$ F.S.

Non-linearity $\pm 0.05\%$ F.S.

Output data Outputs torque, rotation speed and power at the same time.

D/A converter voltage output (DAV)

Output range $\pm 10 \text{V}$

Load resistance $2k\Omega$ or more

D/A conversion speed 8000 times per second

Resolution 1/10000

Zero/span adjustment range $\pm 10\%$ F.S.

Non-linearity $\pm 0.05\%$ F.S.

Output data Selected by the setting of "Torque," "Rotation speed," or

"Power."

D/A converter current output (DAI)

Output range 4 to 20mA

Load resistance 350Ω or less

D/A conversion speed 8000 times per second

Resolution 1/10000

Zero/span adjustment range $\pm 10\%$ F.S.

Non-linearity $\pm 0.05\%$ F.S.

Output data Selected by the setting of "Torque," "Rotation speed," or

"Power."

RS-232C interface (232)

Transmitting method Asynchronous

Baud rate 9600bps to 57600bps

USB interface (USB)

Communication standard Compliant with USB Ver.2.0, Full speed

Communication device class

Baud rate 9600 to 230.4k bps

Virtual COM port Graph display, write & read of setting parameters is

possible through dedicated software.

Connector mini-B TYPE

■General performance

Power supply voltage $DC24V \pm 15\%$

Power consumption 8W typ.

Operating conditions Temperature: Operation -10 to +50°C

Storage $-40 \text{ to } +80^{\circ}\text{C}$

Humidity: 85%RH or less (non-condensing)

Dimension 96 (W)×96 (H)×138 (D)mm (Projections excluded)

Panel cutout size $92 \times 92 \stackrel{+1}{_{-0}}$ mm

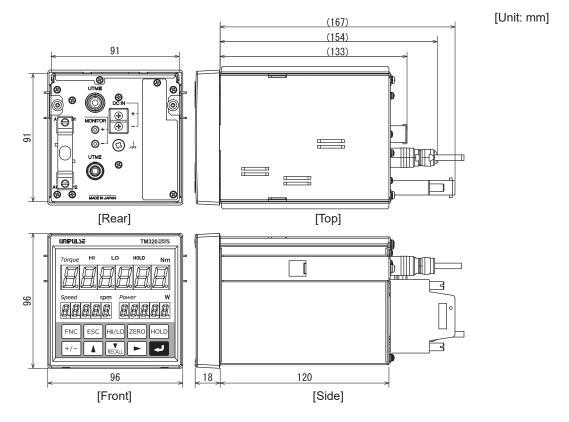
Weight Approximately 1.2 kg

■ Attachment

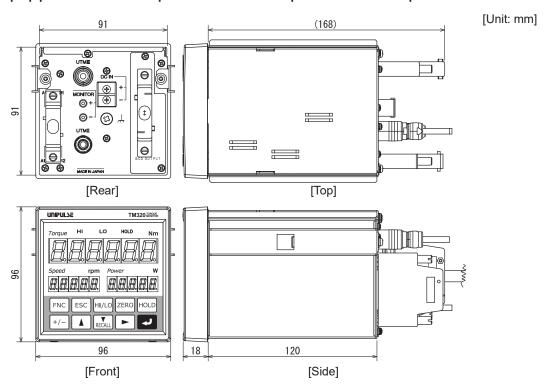
- External input/output connector	. I
- Unit seal	
- Ferrite core	. 1
- Connector for BCD output (with BCD output option)	. 1
- Operating tool (with D/A converter (3ch) option)	
- Mini screwdriver for terminal block connection (with D/A converter option)	
- Operation manual	

11-2. Dimensions

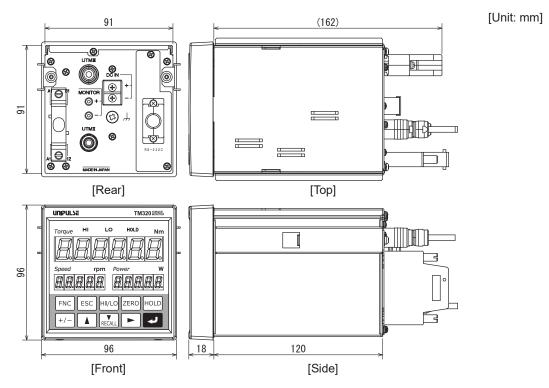
■Standard equipment



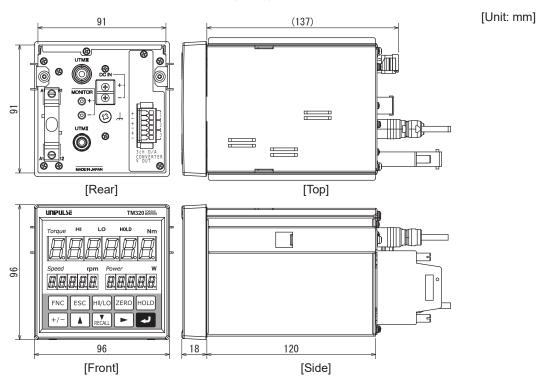
■Equipped with BCD parallel data output interface option



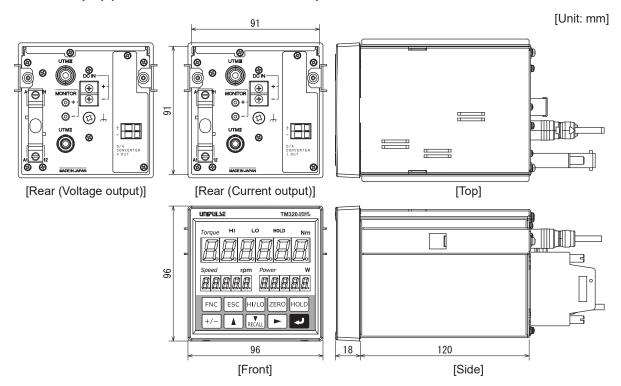
■ Equipped with RS-232C interface option



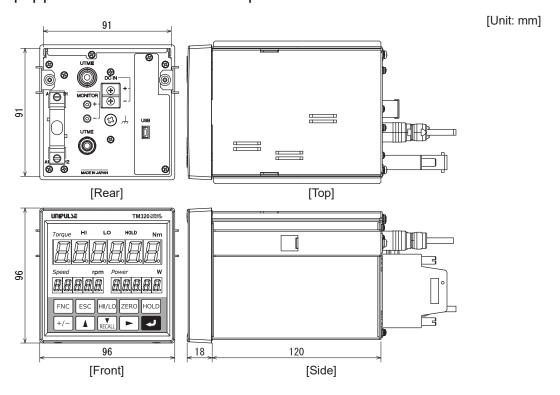
■Equipped with D/A converter (3ch) option



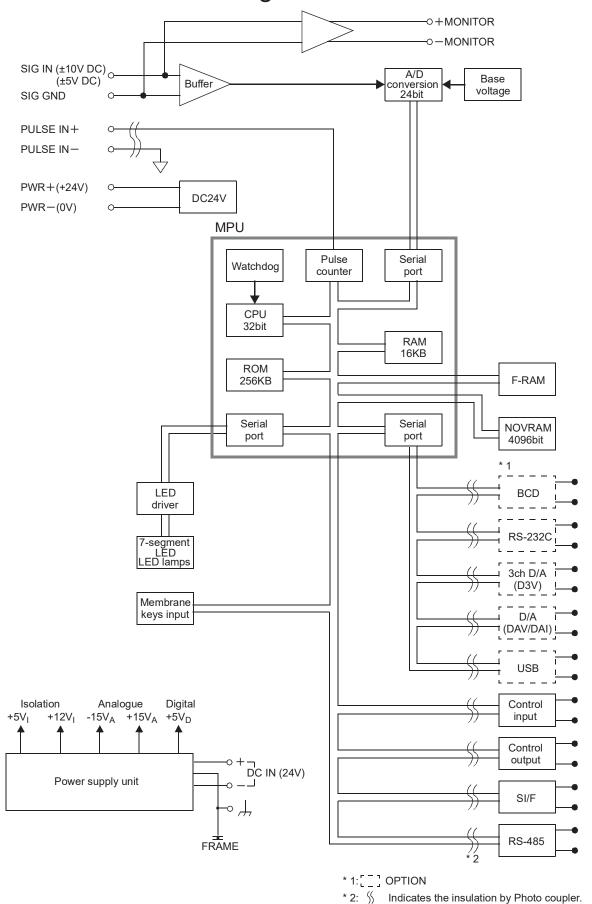
■ Equipped with D/A converter option



■Equipped with USB interface option



11-3. TM320 block diagram



¹⁰⁷

12 SUPPLEMENTS

12

12-1. The list of initial setting value

* Initial value Factory default value

* Protec \bigcirc : Work protect

In accordance with "1. Setting protect" ⊚: System protect in mode 9. Calibration protect

⊚:

* NOVRAM Saved in NOVRAM Saved in F-RAM No mark:

* Reference Reference page on which the details of each item are described

■Mode 0: Work setting (HI/LO limit setting mode)

Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Torque HI limit (HI)	-99999 to 99999	750	0		
2	Torque LO limit (LO)	-99999 to 99999	250	0		
3	Torque Alarm HI limit (ALM HI)	-99999 to 99999	99999	0		
4	Torque Alarm LO limit (ALM LO)	-99999 to 99999	-99999	0		P20
5	Rotation speed HI limit (HI)	0 to 99999	3000	0		P44
6	Rotation speed LO limit (LO)	0 to 99999	100	0		
7	Rotation speed Alarm HI limit (ALM HI)	0 to 99999	99999	0		
8	Rotation speed Alarm LO limit (ALM LO)	0 to 99999	0	0		
9					·	

■ Mode 1: Work setting (comparison/hold)



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Comparison function select	0 0 0 0 B2 output selection 0: Timing output 1: Absolute value output 1: Absolute value output Comparison timing (Rotation speed) 0: All time 1: Torque synchronized Undefined (0 fixed) Comparison timing (Torque) 0: All time 1: Stable 2: Near Zero OFF 3: Stable and Near Zero OFF 4: Hold	0010	0	©	P47
2	Near zero	0 to 99999	100	0	0	P46
3	Hysteresis (Torque)	0 to 9999	0	0	0	P45
4	Hysteresis (Rotation speed)	0 to 9999	0	0	0	P45
5	Torque timing output HI limit	-99999 to 99999	99999	0	0	P48
6	Torque timing output LO limit	-99999 to 99999	-99999	0	0	P48
7	Hold function select	O 0 0 1 Auto reset O: OFF 1: ON This setting is required when the hold section is "external signal" or "external signal + time" or "level + time." Hold section O: All section 1: External signal 2: External signal + time 3: Level + time This setting is required only when the hold mode is other than "0: OFF." Hold mode O: OFF 1: Sample 2: Peak 3: Bottom 4: P-P 5: Average Undefined (0 fixed)	0001	0	©	P49
8	Detection time*1	0.01 to 9.99 [sec.]	1.00	0	0	P55
9	Hold start level*2	-99999 to 99999	100	0	0	P56

^{*1:} This setting is required only when the hold section is "External signal + Time" and "Level + Time."

^{*2:} This setting is required only when the hold section is "Level + Time."

■ Mode 2: System setting (operation 1)

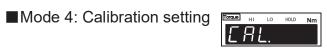


Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Motion detect (time)	0.0 to 9.9	0.0	0	0	P39
2	Motion detect (range)	000 to 999	000	0	0	P39
3	Zero tracking (time)	0.0 to 9.9	0.0	0	0	P40
4	Zero tracking (range)	000 to 999	000	0	0	P40
5	SI/F function select	0 0 0 Undefined (0 fixed) Undefined (0 fixed) SI/F print (record) 0: None 1: Stable value 2: Hold value	000	0	©	P61
6	Display frequency	0: 3	3: 25	0	0	P42
7	Display ON/OFF	0 1 1 1 —Power display 0: OFF 1: ON —Rotation speed display 0: OFF 1: ON —Torque display 1: ON fixed —Undefined (0 fixed)	0111	©	©	P42
8	Absolute value display select	0: Not valid 1: Valid (marked) 2: Valid (Without mark)	0	0	0	P43
9						

■ Mode 3: System setting (operation 2) 595.2



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Digital filter (torque)	0 (OFF), 2 to 999 [times]	030	0	0	P37
2	Digital low-pass filter (torque)	3 to 1000, PASS [Hz]	300	0	0	P36
3	Dead band	0000 to 9999	0000	0	0	P37
4	Digital filter (rotation speed)	0 (OFF), 2 to 999 [times]	030	0	0	P37
5	B8 OFF detect wait	0.00 to 9.99 [sec.]	0.01	0	0	P58
6	B9 OFF detect wait	0.00 to 9.99 [sec.]	0.01	0	0	P59
7						
8						
9						



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Calibration function select 1 (torque)	0 2 2 0 Min. scale division (torque) 0: 1	0220	•	©	P25
2	Zero calibration	-10.000 to 10.000 [V] (UTM III/UTF (option)) -5.000 to 5.000 [V] (UTM II)	0.000	•	0	P26
3	Equivalent input calibration	-10.000 to 10.000 [V] (UTM III / UTF (option)) -5.000 to 5.000 [V] (UTM II) (except 0)	10.000	•	0	P27
4	Actual load calibration	-99999 to 99999 (except 0)	10000	•	0	P29
5	Digital offset	-99999 to 99999	0	•	0	P30
6	Digital Zero limit	0 to 99999	99999	•	0	P30
7	Calibration function select 2 (rotation speed/ power)	1 0 1 0 0 Min. scale division (power) 0: 1 1: 2 2: 5 3: 10 Decimal place (power) 0: None 1: 0.0 2: 0.00 3: 0.000 Unit (power) 0: mW 1: W 2: kW 3: PS 4: HP Min. scale division (rotation speed) 0: 1 1: 2 2: 5 3: 10 Pulse rate (Rotation speed) 0: 1 pulse 1: 4 pulses 2: 60 pulses 3: 90 pulses	10100	•	©	P31
8	Rotation stop settings	0 0 0 0 Minimum input rotation speed 0: 15 1: 10 2: 5 3: 3 4: 2 [rpm] * 4 times the above, when the pulse rate is "1 pulse" * For UTF/60 pulses, 0 is fixed (1rpm) Undefined (0 fixed) Rotation stop mode 0: OFF 1: 2 times 2: 4 times 3: 8 times Undefined (0 fixed)	0000	•	©	P33
9	Voltage input select	0: 10V (UTMIII/UTF) 1: 5V (UTM II)	0	•	0	P24

■ Mode 5: Option setting (BCO option)



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Output data select	0: Torque (hold synchronized) 1: Rotation speed 2: Power 3: Torque (hold not synchronized) 4: External selection	0: Torque (hold synchronized)	0	0	P73
2	Output rate	0: 10	3: 100	0	0	P74
3	BCD/binary select	0: BCD 1: Binary	0: BCD	0	0	P75
4						
5						
6						
7						
8						
9						

■ Mode 5: Option setting (232/USB option)



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Communication mode	0: Send/receive 1: Continuous transmission (hold synchronized) 2: Printed transmission 3: Continuous transmission (hold not synchronized)	0: Send/receive	0	0	P77
2	Communication condition	1 1 1 0 0 (232) 5 1 1 0 0 (USB) Undefined (0 fixed) Stop bit 0: 1bit 1: 2bit Parity bit 0: None 1: Even 2: Odd Character length 0: 7bit 1: 8bit Baud rate 0: 9600 1: 19200 2: 38400 3: 57600 4: 115.2k* 5: 230.4k* [bps] * Only USB option	232: 11100 USB: 51100	©	o	P78
3	Delimiter	0: CR 1: CR+LF	0: CR	0	0	P79
4						
5						
6						
7						
8						
9						

■ Mode 5: Option setting (D3V option)



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Output data select	0 0 0 0 Data select 1 (torque) 0: Hold synchronized 1: Hold not synchronized 0: Hold synchronized 1: Hold not synchronized 0: Output mode 0: Output data select 1: Zero scale fix 2: Full scale fix	0000	©	©	P86
2	Zero scale value 1 (torque)	-99999 to 99999	0	0	0	P88
3	Full scale value 1 (torque)	-99999 to 99999	10000	0	0	P88
4	Zero scale value 2 (rotation speed)	-99999 to 99999	0	0	0	P88
5	Full scale value 2 (rotation speed)	-99999 to 99999	10000	0	0	P88
6	Zero scale value 3 (power)	-99999 to 99999	0	0	0	P88
7	Full scale value 3 (power)	-99999 to 99999	10000	0	0	P88
8						
9						

■ Mode 5: Option setting (DAC (DAV/DAI) option)



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Output data select	0 0 0 0 Output data select 0: Torque (hold synchronized) 1: Rotation speed 2: Power 3: Torque (hold not synchronized) 4: Zero fix 5: Full scale fix Undefined (0 fixed) Undefined (0 fixed) Undefined (0 fixed)	0000	©	©	P92
2	Zero scale value	-99999 to 99999	0	0	0	P93
3	Full scale value	-99999 to 99999	10000	0	0	P93
4						
5						
6						
7						
8						
9						

■Mode 6: RS-485 setting (UTMⅢ/UTF)



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	RS-485 communication mode	0: RS-485 command mode 1: RS-485 display mode 2: Iinvalid	0	0	0	P63
2	UTM/UTF setting value read	0: Cancel 1: Filter setting 2: Rotation speed filter 3: Minimum rotation speed display	0	0	*	P64
3	UTM/UTF filter setting	0: 1 1: 3 2: 10 3: 30 4: 100 5: 300 6: 1k 7: PASS [Hz]	0	0	*	P64
4	UTM/UTF rotation speed filter	0: OFF 1: 2 2: 4 3: 8 4: 16 5: 32 [times]	0	0	*	P65
5	UTM/UTF minimum rotation speed display	0 to 99	00	0	*	P65
6	UTM/UTF assigned action	0: Cancel 1: Digital zero 2: Digital zero reset	0	0	*	P66
7	RS-485 dedicated rated capacity value	0 to 99999	10000	0	0	P66
8	RS-485 terminator	0: OFF 1: ON	1	0	0	P67
9	RS-422 terminator	0: OFF 1: ON	1	0	0	P67

^{*} Setting values are not kept.

■ Mode 9: Protect/Initializ



Item No.	Setting value name	Setting value range	Initial value	Protect	NOV RAM	Reference
1	Setting protect	0 0 0 Calibration protect 0: OFF 1: ON System protect 0: OFF 1: ON Work protect 0: OFF 1: ON	000		0	P116
2	Key protect	0 0 0 Undefined (0 fixed) HOLD key protect 0: OFF 1: ON ZERO key protect 0: OFF 1: ON	000	©	0	P117
3	Initialize	1: Work setting 2: System setting 3: Calibration setting	0	00•		P118
4	Password		0000	_	_	P118
5						
6						
7						
8						
9	Record data clear	0: Cancel 1: Execution	0	0		P70

12-2. Self-check function

The self-check function is to automatically check the memory and detect problems.

This function is to checksum the software, check the NOVRAM operation, check the F-RAM operation, and check the lighting of indicators. This function is not to diagnose the analog circuit.

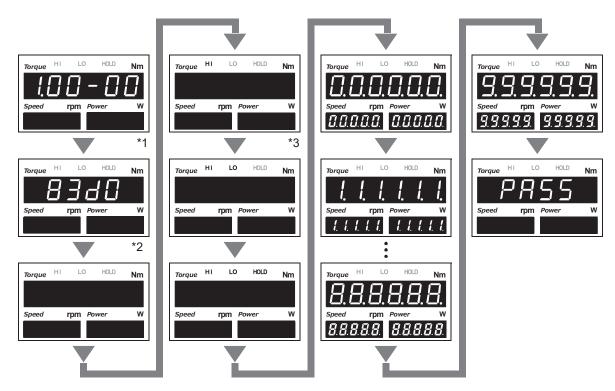
■ Self-check method

- **1.** Turn off the power of the TM320.
- 2. Turn on the power while pressing ESC
- **3.** If "PASS" is displayed at the end, it is normal.

↑ CAUTION

If " *PR55* " is not displayed at the end, there is a possibility of failure. (Contact our sales staff.)

Self-check display items



- *1: ROM version
- *3: Status indications light in sequence.

12

12-3. Setting protect

Each category of setting values can be locked to prevent rewriting. For each category, see the setting value list.

《Setting value》

0: OFF Enables rewriting of setting values.

1: ON Disables rewriting of setting values.

■ Setting protect setting method

1. Select setting mode 9.

 $Press \ \boxed{\textbf{FNC}} \rightarrow \boxed{\ \ } six \ times.$

2. Set "setting protect."

Press RECALL once. ⇒ "Setting protect" is displayed.

Press , and the highest digit blinks.

Input the setting value of "Work protect" with



Move to the lower digit with ► . (Initial value: 0)

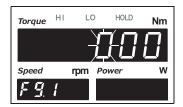
Input the setting values of "System protect" and

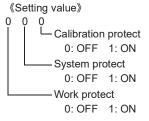
"Calibration protect" in a like manner.

Press to validate it.

3. Press ESC twice to go back to the indicated value display.









For the setting items protected by the setting protect, see "12-1.The list of initial setting value" on page 108.

12-4. Key protect

ZERO key and **HOLD** key operations are disabled to prevent misoperation.

≪Setting value≫

0: OFF Enables key operations.

1: ON Disables key operations.

■Key protect setting method

1. Select setting mode 9.

Press $\boxed{\mathsf{FNC}} \to \boxed{\blacktriangleright}$ six times.

2. Set "Key protect."

Press RECALL twice. ⇒ "Key protect" is displayed.

Press , and the highest digit blinks.

Input the setting value of "ZERO key protect" with



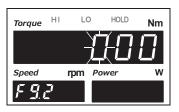
Move to the lower digit with . (Initial value: 0)

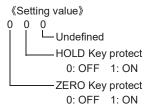
Input the setting values of "HOLD key protect" in a like manner.

Press to validate it.

3. Press ESC twice to go back to the indicated value display.







12

12-5. Initialize

Each category of setting values can be initialized.

For each category, see the setting value list.

≪Setting value≫

- (0: Undefined)
- 1: Work setting (Including record data)
- 2: System setting (Including setting protect and key protect)
- 3: Calibration setting

After inputting the number of the setting value category you want to initialize, press validate it, and initialization is executed.



However, if the category is protected, initialization cannot be performed.

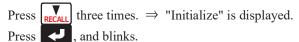
Normally, the setting value of "initialize" is "0 (undefined)."

■Initialize setting method

1. Select setting mode 9.



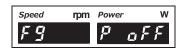
2. Excecute initialization.

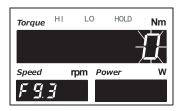


Input the setting value for initialization with



Press to validate it.





- * Upon validation, initialization is executed and the setting value goes back to "0."
- **3.** Press | ESC | twice to go back to the indicated value display.

12-6. Password

This setting is for maintenance and inspection. Do not operate it.

12-7. Error/message list

■Main numerical display section

-LoAd - L o A d	Below the signal input range -10V over (UTMIII/UTF) -5V over (UTM II)	The input electric signal greatly exceeds the signal input range. This also occurs when an excessive load is applied to		
LoAd LoAd	Beyond the signal input range +10V over (UTMIII/UTF) +5V over (UTM II)	the sensor or the input terminal is opened due to a break in the cabling, etc.		
ALA RLR	Beyond the alarm HI limit	This occurs when a larger load than expected is applied to the sensor or calibration is performed below the		
-ALA - ALA	Below the alarm LO limit	measurement range. Check the calibration and measuring object.		
oFL	Below -99999	This occurs when a larger load than expected is applied to the sensor or calibration is performed below the		
oFL2	Beyond 99999	measurement range. Check the calibration and measuring object.		
cErr2	Beyond the zero calibration range in the positive direction	The signal input range is greatly exceeded when zer		
cErr3	Below the zero calibration range in the negative direction	calibration is performed. Check for an excessive load applied to the sensor and for breaks.		
cErr4 c E r r Y	Beyond the rated output value in the positive direction/negative direction. Beyond the rated capacity value.	The signal input range is greatly exceeded when calibration is performed. In the case of equivalent input calibration, check the rated output value, and in the case of actual load calibration, check for an excessive load applied to the sensor and for breaks. Also, Check the setting of rated capacity value (display value) sets it exceeding "±99999".		
cErr5	Rated capacity value = 0	Check the setting of rated capacity value (display value) for being "0" when calibration is performed.		
cErr6	Rated output value 0.000V at the time of equivalent input calibration Rated output value in the range of -0.010 to +0.010V at the time of actual load calibration	Check the rated output value for being 0.000V when equivalent input calibration is performed, and the load for being too light in weight when actual load calibration is performed.		
dZ Err d Z E r r Digital Zero limit error		When the range of zero point correction (deviation from the zero calibration registered point) by Digital Zero or Zero Tracking exceeds the setting value of Digital Zero limit Digital Zero limit error occurs. Perform Digital Zero, etc., in a proper range.		
CALZE	Zero calibration in progress			
CALSP	Actual load calibration in progress	These are not errors. They indicate that each calibration is in execution.		
CALEq	Equivalent input calibration in progress			

■Sub numerical display section

oFL1	Below -19999	The power exceeds the display range. Check the power unit and decimal place settings.	
oFL2	Beyond +99999	The rotation speed or power exceeds the display range. On the rotation speed side, check the connection with the UTMII, and on the power side, check the power unit and decimal place settings.	
ALA ALA	Beyond the alarm HI limit	Rotation speed is at a faster or slower speed than expected Confirm that rated rotation speed and rotation are not lock and so forth.	
-ALA - ALA	Below the alarm LO limit		

12-8. Troubleshooting

Item	Question	Answer/remedy		
Item		,		
Sensor	Is a correct indicated value displayed by simply connecting sensor(s)?	Match the sensor output and indicator by equivalent input calibration or actual load calibration. Then, the indicated value is displayed in proportion to the sensor output.		
	The power cannot be turned on.	Check to see if the power cord is properly connected. If not, connect the power cord properly.		
	The power cannot be turned on.	Check to see if the power source is within the specified range. If not, use a power source within the specified range.		
Wiring and connection	The indicated value is abnormal.	Check to see if the sensor is properly connected. If not, connect the sensor properly.		
Connection		Check the sensor for damage. Connect a normal sensor.		
		Check the sensor for a mechanical load. Prevent such a load.		
		Use MONITOR terminal to check if the voltage is within the specified output range of torque meter. (UTM III /UTF: within ±10V, UTM II : within ±5V)		
	It is desired to decrease the number of digits of the numerical value.	Since there is a need to decrease the number of digits of the value input during equivalent input calibration or actual load calibration, perform calibration again. Also, set the load-related setting values, such as HI and LO limit values, again according to that number of digits.		
	How to get hold is unclear.	The control method may differ according to the hold mode used. See "7-1.Hold functions of torque" on page 49.		
	Judgment results are not output.	Check to see if the output cable is properly connected. If not, connect the output cable properly.		
Setting and operation		In the case of comparison output, the output conditions differ according to the setting of comparison timing. See "6-4.Comparison timing" on page 47.		
	Lower digit(s) of the indicated value fluctuates.	Check for calibration exceeding 10000 at approximately 3.3 Since the resolution is approximately 10000 with respect approximately 3.3V, calibration exceeding it will cause coarsenes and the indicated value will fluctuate and not become stable. Fusing as it is, ignore the lower digit(s), or set the min. sca division again.		
	Is the voltage output and D/A option different?	The monitor output is made by turning back the sensor input. It is different from the D/A converter that converts from digital to analog through digital processing. Consider that the D/A converter is synchronized with the indicated value.		

Item	Question	Answer/remedy	
	The output is abnormal.	Check for parallel wiring with AC lines. Carry out wiring again so as not to become parallel with AC lines.	
SI/F	The print on the printer is abnormal.	Check to see if the print data setting of the printer side is correct. GROSS area, NET area, and TARE area exist. Check that the areas and setting correspond.	
	Automatic printing cannot be	Check to see if the SI/F print setting of the TM320 is correct. Check the setting.	
	performed.	Check to see if the printer side print setting is automatic printing. Check the setting.	
Option	Can two or more options be mounted?	Cannot be mounted. Only one optional function can be mounted.	
		Check to see if wiring is correct. Check the wiring, and connect the communication cable properly.	
	The output is abnormal.	Check to see if the logic is recognized properly. Negative logic/positive logic selection is available.	
BCD output option		Check to see if synchronization is maintained with the strobe signal. Check the setting.	
орион		Check to see if it is in synchronization with the strobe signal. Make the output rate slower or use the BCD data hold if the processing performance of the device that should receive BCD is low.	
	Hold values do not result.	The output data differ according to the setting or external selection. Check to see if it is a torque (hold synchronized).	
		Check to see if the communication cable is properly connected. After turning off the power, connect the communication cable properly.	
	Communications fail.	Check to see if a proper communication cable is used. Check to see if wiring is correct. Check the wiring, and connect the communication cable properly.	
RS-232C option		Check to see if the communication conditions of the master and TM320 correspond. Check the communication conditions, and match the settings.	
	Reading cannot be performed.	Check to see if the transmission command from the master correct. Check for any unwanted code included at the head of t transmission command. Check the transmission command.	
	Is any program necessary for communicating with PC?	Some program or tool for serial communication is necessary. Create software to exchange commands at required timing.	
D3//D4//D41		Check for greatly exceeding the scale.	
D3V/DAV/DAI option	The output is abnormal.	Check for fixed output setting. Set the output setting properly again.	

12

12-9. Conformity with EC directives

The TM320 Torque Monitor is a CE-marked EC-Directive-conforming product (by the Council of the European Union).

EN61326-1 - EMC Directives;

EN55011

EN61000-4-2

EN61000-4-3

EN61000-4-4

EN61000-4-5

EN61000-4-6

EN61000-4-8



EMC Directive EN61000-4-5 (Lightning Surge Immunity) is met by the TM320 body in combination with a lightning surge protector.

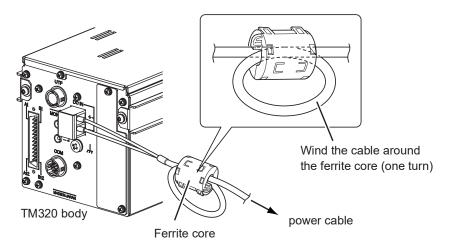
CAUTION

- Since the TM320 is defined as open type (built-in equipment), be sure to use it as installed and fixed to a panel, etc.
- Use shielded cables (for encoder, USB, external input/output, UTM, and option(s)).

■ Attachment of the ferrite core

Wind the power cable around the included ferrite core (SEIWA ELECTRIC MFG.: E04SR211132). Attach the ferrite core as close to the TM320 body as possible.

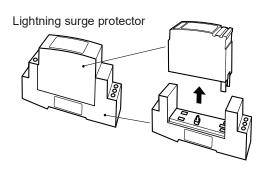
Fix it with cable tie(s) as necessary.



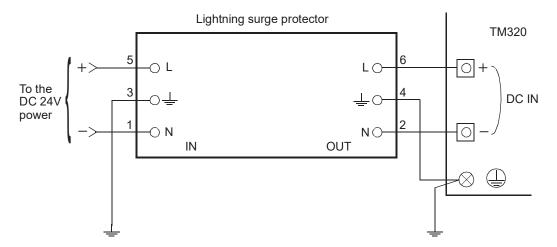
■Connection of a lightning surge protector

Attach a lightning surge protector against lightning surge.

EMC Directive EN61000-4-5 (Lightning Surge Immunity) is met by the TM320 body in combination with a lightning surge protector.



<Connect>



Attention

Be sure to ground $\stackrel{\perp}{=}$ of the lightning surge protector.

Without grounding, it will not function as a lightning surge protector.

Point

No lightning surge protector is included as standard (optionally available).

Our company carries an optional lightning surge protector (TSU03).

Contact our sales department for details.

Unipulse Corporation

International Sales Department
9-11 Nihonbashi Hisamatsu-cho, Chuo-ku, Tokyo 103-0005
Tel: +81-3-3639-6120 Fax: +81-3-3639-6130

www.unipulse.tokyo/en/

Head Office:	9-11 Nihonbashi Hisamatsu-cho, Chuo-ku, Tokyo 103-0005
Technical Center:	1-3 Sengendainishi, Koshigaya, Saitama 343-0041
Nagoya Sales Office:	TOMITA Bldg. 2-5 Ushijima-cho, Nishi-ku, Nagoya 451-0046
Osaka Sales Office:	Sumitomo Seimei Shin Osaka Kita Bldg. 4-1-14 Miyahara, Yodogawa-ku, Osaka 532-0003
Hiroshima Sales Office:	Hiroshima Dai-ichi Seimei OS Bldg. 1-2-21 Matoba-cho, Minami-ku, Hiroshima 732-0824