

GYMRA-PF Probe

Analogue

GPM
**Noise
Cancel**

**Flat head type, analogue output
(detachable probe element)**



This is the linear profile version of GYMRA. The output is voltage or current. The inside probe element can be detached from the outer housing, and with the captive software (GPM), zero and gain adjustment is possible at user side.

Specifications

Accuracy	Non-linearity	$\leq \pm 0.025\%FS$ TYP
	Resolution	$\leq 0.1mm$
	Repeatability	$\leq \pm 0.1mm$
	Temp. drift	$\leq \pm 20ppmFS/^{\circ}C$
Output	Voltage output	0~10V or 10~0V (output current: Max.5mA, load: Min.2k Ω)
	Current output	4~20mA or 20~4mA (load: Max.500 Ω)
	Alarm	Open drain 50V 0.1A (for magnet missing)
	Power supply	+24(± 2)VDC (60mA)
Environment	Sampling freq.	Std 1kHz (up to stroke 1000mm)
	Operating temp.	-20 $^{\circ}C$ ~+75 $^{\circ}C$
	Storage temp.	-40 $^{\circ}C$ ~+75 $^{\circ}C$
	Vibration	15G (20~100Hz)
	Shock	100G (2msec)
	IP grade	IP65

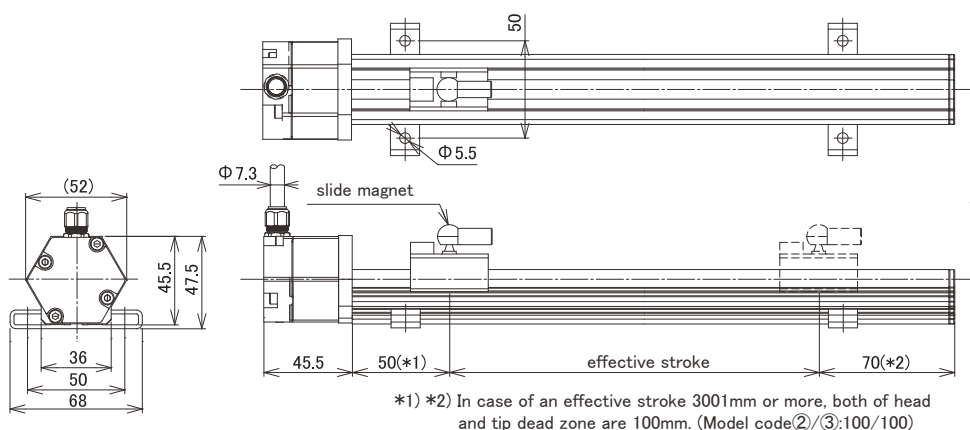
- *The above mentioned accuracy applies to sensors with an effective stroke of 300mm or more.
- *The specification of stroke less than 300mm is equal that of stroke 300mm.

*Fixing clamps are supplied.

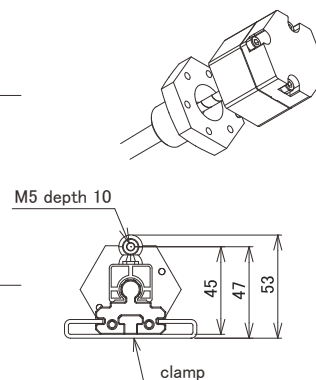
stroke	< 600mm: 2 pcs	
	600~1000mm: 3 pcs	
	1001~1500mm: 4 pcs	One clamp is added
	1501~2000mm: 5 pcs	every 500mm

Dimensions

Probe

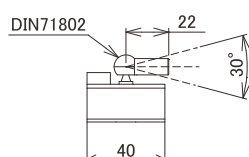


detachable probe element

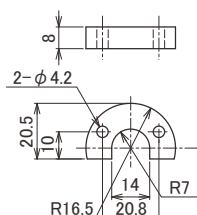


magnet

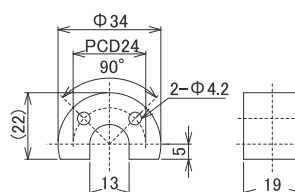
slide magnet
model: PFU
materials: polyacetal



floating magnet
model: No.5N-UK
materials: MC nylon



floating magnet
model: No.5PFT-LG
materials: SS304



Cable

Wire color	Function
red	+24VDC
white	0V
blue	(Voltage)
green	COM1
brown	(Current)
black	COM2
yellow	Alarm

- *Shield should be connected with 0V at user side.
- *In case you select the voltage output, you can't use the brown and black wires.
- *In case you select the current output, you can't use the blue and green wires.

- *materials ; Probe head : Al alloy, body : Al alloy
- *cable length ; Max.10m (0~10V output), Max.100m (4~20mA output)

■ Probe

GYMRA- **-** **/** **-PF-** **-** **-** **-**

①
②
③
④
⑤
⑥
⑦

① Effective stroke

15~7500mm

② Head dead zone

S: 50mm (STD)

: mm (option) (specified by customers)

• Possible Min. length depends on the selected magnet.

③ Tip dead zone

S: 70mm (STD)

: mm (option) (specified by customers)

• Possible Min. length depends on the selected magnet.

④ Associated magnet

PFU : PFU slide magnet
FE : No.5N-UK
BP : No.5PFT-LG

- Please consult if you select a magnet of other than above.
- This Model code means only specifying associated magnet.
- When you need a magnet, please order separately.

⑤ Cable connection

△G□F: pigtail / cable end : free

△G□A: pigtail / cable end : with connector for relay

(□: cable length (m), Max.10m) (*)

(△: cable type

S: standard, H: high temp. cable, R: robot cable, UL: cUL cable)

(*) In case of using extension cable

Voltage output : sensor cable (m) + extension cable (m) ≤ 10m

Current output : sensor cable (m) + extension cable (m) ≤ 100m

• Please consider extension cable on page 113.

⑥ Position output (OUT1)

AD: 0~10V (When magnet moves toward tip, output increase)

AR: 10~0V (When magnet moves toward tip, output decrease)

BD: 4~20mA (When magnet moves toward tip, output increase)

BR: 20~4mA (When magnet moves toward tip, output decrease)

V Z/F: option (specified voltage)

(for example V1/5: 1~5V, V9.5/0.5: 9.5~0.5V)

I Z/F: option (specified current)

(for example I5.2/20: 5.2~20mA, I18/5: 18~5mA)

【Z=output at zero position, F=output at full position】

⑦ Clamp

F50 : with fixing clamps

N : without fixing clamps