IP65\_IP68

## **Product Advantages**

**MINI45** 

**One of the Smallest 6-Axis Sensors in the World:** The Mini45 has a compact, low-profile design with a through-hole to allow passage of linkages or cables.

## **Extremely High Strength:**

- EDM wire-cut from high-yield strength stainless steel.
- Maximum allowable single-axis overload values are 5.7 to 25 times rated capacities.

**High Signal-to-Noise Ratio:** Silicon strain gages provide a signal 75 times stronger than conventional foil gages. This signal is amplified, resulting in near-zero noise distortion.

**IP65 and IP68 (4m) Versions Available:** The IP65 version of the transducer is available for use in wet environments. The IP68 version is for underwater environments to a maximum depth of 4 meters in fresh water. Contact ATI Industrial Automation for drawings and more information.

## **Typical Applications**

• Telerobotics • Robotic surgery

y • Robotic hand research

• Finger-force research

	SENSING RANGES Axes	Calibrations US-30-40		US-60-80		US-120-160	
ENGLISH CALIBRATIONS	Fx, Fy (±lbf)	30		60		120	
	Fz (±lbf)	60		120		240	
	Tx, Ty (±lbf-in)	40		80		160	
	Tz (±lbf-in)	40		80		160	
	RESOLUTION	System Type*					
	Axes	CTL	Net/DAQ	CTL	Net/DAQ	CTL	Net/DAQ
	Fx, Fy (lbf)	1/40	1/80	1/20	1/40	1/10	1/20
	Fz (lbf)	1/40	1/80	1/20	1/40	1/10	1/20
	Tx, Ty (lbf-in)	1/44	1/88	1/22	1/44	1/11	1/22
	Tz (lbf-in)	1/88	1/176	1/44	1/88	1/22	1/44
		Calibrations					
	SENSING RANGES						
	SENSING RANGES Axes		rations 145-5	SI-29	90-10	SI-58	30-20
		SI-1			90-10		30-20 580
NS	Axes	SI-1	145-5	2		5	
ATIONS	Axes Fx, Fy (±N)	SI-1	145-5 145	2	290	5	80
LIBRATIONS	Axes Fx, Fy (±N) Fz (±N)	SI-1	145-5 145 290	2	290	5 1' 2	i80 160
CALIBRATIONS	Axes       Fx, Fy (±N)       Fz (±N)       Tx, Ty (±Nm)	SI-1	145-5 145 290 5	2	290 580 10	5 1' 2	580 160 20
tric Calibrations	Axes       Fx, Fy (±N)       Fz (±N)       Tx, Ty (±Nm)       Tz (±Nm)	SI-1	145-5   145   290   5   5	2	290 580 10	5 1' 2	580 160 20
METRIC CALIBRATIONS	Axes       Fx, Fy (±N)       Fz (±N)       Tx, Ty (±Nm)       Tz (±Nm)       RESOLUTION	SI-1	145-5 145 290 5 5 m Type*	2 E	290 580 10 10	5 11 2 2	580 160 20 20
METRIC CALIBRATIONS	Axes     Fx, Fy (±N)     Fz (±N)     Tx, Ty (±Nm)     Tz (±Nm)     RESOLUTION     Axes	SI-1 Syster CTL	145-5 145 290 5 5 m Type* Net/DAQ	CTL	290 580 10 10 Net/DAQ	5 1' : : : : : : :	80 160 20 20 Net/DAQ
METRIC CALIBRATIONS	Axes       Fx, Fy (±N)       Fz (±N)       Tx, Ty (±Nm)       Tz (±Nm)       RESOLUTION       Axes       Fx, Fy (N)	SI-1 Syster CTL 1/8	145-5 145 290 5 5 m Type* Net/DAQ 1/16	2 5 CTL 1/4	290 580 10 10 Net/DAQ 1/8	5 11 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	80 160 20 20 Net/DAQ 1/4

\*CTL: Controller F/T System; Net: Net F/T System; DAQ: 16-bit DAQ F/T System. The resolution is typical for most applications and can be improved with filtering. Resolutions quoted are the effective resolution after dropping four counts of noise (Net/DAQ) or eight counts of noise (CTL). All sensors calibrated by ATI. **Applied loads must be within range in each of the six axes for the F/T sensor to measure correctly** (refer to the transducer manual for complex loading information).

22 VISIT WWW.ATI-IA.COM FOR CURRENT PRODUCT SPECIFICATIONS, 2-D DRAWINGS, AND 3-D CAD MODELS



The Mini45 F/T transducer EDM wire-cut from high yield-strength stainless steel

ATI	INDUSTRIAL AUTOMATION

Single-Axis Overload	English	Metric			
Fxy	±1100 lbf	±5100 N			
Fz	±2300 lbf	±10000 N			
Тху	±1000 lbf-in	±110 Nm			
Tz	±1200 lbf-in	±140 Nm			
Stiffness (Calculated)	English	Metric			
X-axis & Y-axis force (Kx, Ky)	4.2x10⁵ lb/in	7.4x10 <sup>7</sup> N/m			
Z-axis force (Kz)	5.6x10⁵ lb/in	9.8x10 <sup>7</sup> N/m			
X-axis & Y-axis torque (Ktx, Kty)	1.5x10⁵ lbf-in/rad	1.7x10⁴ Nm/rad			
Z-axis torque (Ktz)	3.1x10⁵ lbf-in/rad	3.5x10 <sup>4</sup> Nm/rad			
Resonant Frequency (Measured)					
Fx, Fy, Tz	5200 Hz				
Fz, Tx, Ty	4200 Hz				
Physical Specifications	English	Metric			
Weight*	0.862 lb	0.0391 kg			
Diameter (OD,ID)*	2.28 in, 0.373 in	57.9 mm, 9.5 mm			
Height*	0.988 in	25.1 mm			

"ATI's sales support has been invaluable in helping us select the appropriate sensor and explaining detailed technical issues. I am extremely pleased with the ATI sensor we have chosen. It has enabled us to measure forces exerted by a physician, during a medical procedure, which have never been measured before."

Nathan Delson, PhD Director, Mechanical Engineering Design Center University of California, San Diego Department of Mechanical and Aerospace Engineering

